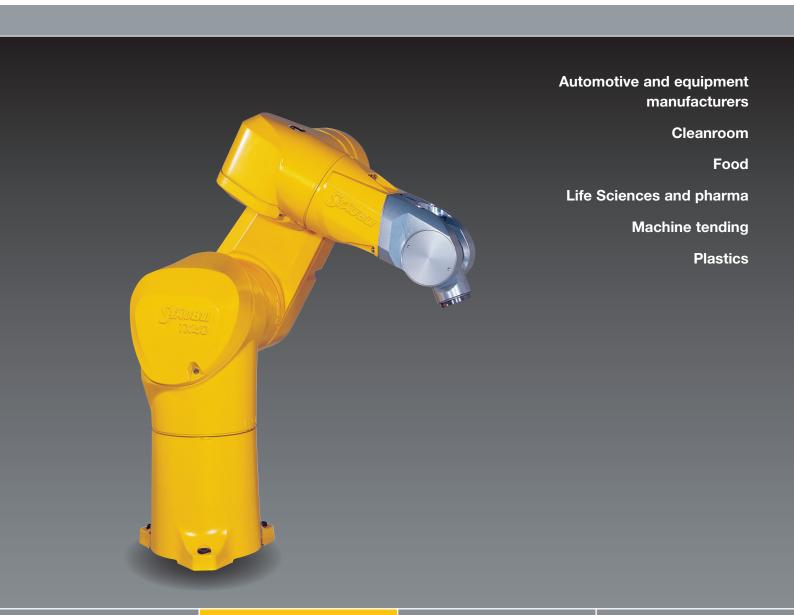
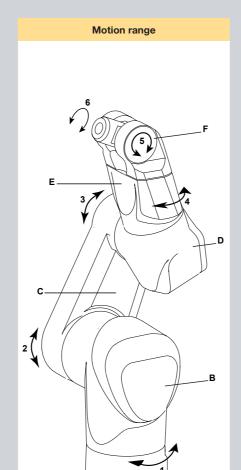




# **TX40** series industrial robots

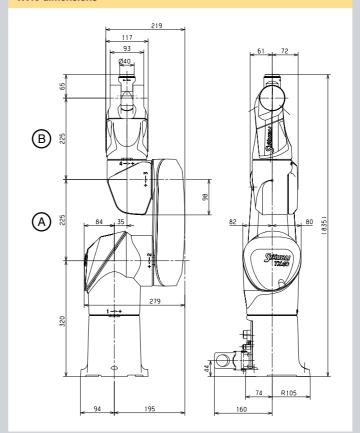


Nominal load (1)   2,3 kg	
Maximum load (1)         2,3 kg           Nominal load         1,7 kg           Reach (between axis 1 and 6)         515 mm           Number of degrees of freedom         6           Repeatability - ISO 9283         ± 0,02 mm           Axis 1 (A)         ± 180°           Axis 2 (B)         ± 125°           Axis 3 (C)         ± 138°           Axis 4 (D)         ± 270°           Axis 5 (E)         +133,5°/-120°           Axis 6 (F)         ± 270° (2)           Maximum reach between axis 1 and 5 (R. M)         450 mm           Minimum reach between axis 2 and 5 (R. m1)         151 mm           Minimum reach between axis 3 and 5 (R. b)         225 mm           Axis 1         555°/s           Axis 2         475°/s           Axis 3         585°/s           Axis 4         1035°/s           Axis 5         1135°/s           Axis 6         1575°/s           Maximum speed at load gravity center         8,2 m/s	
Nominal load	
Reach (between axis 1 and 6)   515 mm	
Number of degrees of freedom   6	
Axis 1 (A)	
Axis 1 (A)	
Axis 2 (B)	
Axis 3 (C)	
Axis 6 (F)  Axis 6 (F)  Expansion (2)  Axis 6 (F)  Expansion (2)  Maximum reach between axis 1 and 5 (R. M)  Minimum reach between axis 1 and 5 (R. m1)  Minimum reach between axis 2 and 5 (R. m2)  Minimum reach between axis 3 and 5 (R. b)  Axis 1  Axis 1  Axis 2  Axis 2  Axis 3  Axis 4  Axis 5  Axis 6  Maximum speed at load gravity center  Axis 6  Axis 6  Axis 7  Axis 8  Axis 8  Axis 8  Axis 8  Axis 9  Axis 9	
Axis 6 (F)  Axis 6 (F)  Expansion (2)  Axis 6 (F)  Expansion (2)  Maximum reach between axis 1 and 5 (R. M)  Minimum reach between axis 1 and 5 (R. m1)  Minimum reach between axis 2 and 5 (R. m2)  Minimum reach between axis 3 and 5 (R. b)  Axis 1  Axis 1  Axis 2  Axis 2  Axis 3  Axis 4  Axis 5  Axis 6  Maximum speed at load gravity center  Axis 6  Axis 6  Axis 7  Axis 8  Axis 8  Axis 8  Axis 8  Axis 9  Axis 9	
Axis 6 (F)  Axis 6 (F)  Maximum reach between axis 1 and 5 (R. M)  Minimum reach between axis 2 and 5 (R. m1)  Minimum reach between axis 2 and 5 (R. m2)  Minimum reach between axis 3 and 5 (R. b)  Axis 1  Axis 2  Axis 2  Axis 3  Axis 4  Axis 5  Axis 6  Maximum speed at load gravity center  Axis 6 (F)  ± 270° (2)  450 mm  151 mm  162 mm  555°/s  475°/s  475°/s  1035°/s  1135°/s  8,2 m/s	
Maximum reach between axis 1 and 5 (R. M)  Minimum reach between axis 1 and 5 (R. m1)  Minimum reach between axis 2 and 5 (R. m2)  Minimum reach between axis 3 and 5 (R. b)  Axis 1  Axis 1  Axis 2  Axis 3  Axis 3  Axis 4  Axis 5  Axis 5  Axis 6  Maximum speed at load gravity center  Maximum reach between axis 1 and 5 (R. m2)  162 mm  225 mm  475°/s  475°/s  1035°/s  1135°/s  8,2 m/s	
Minimum reach between axis 1 and 5 (R. m1)  Minimum reach between axis 2 and 5 (R. m2)  Minimum reach between axis 3 and 5 (R. b)  Axis 1  Axis 2  Axis 2  Axis 3  Axis 4  1035°/s  Axis 5  Axis 6  Maximum speed at load gravity center  151 mm  162 mm  162 mm  555°/s  475°/s  475°/s  1035°/s  1135°/s  8,2 m/s	
Minimum reach between axis 3 and 5 (R. b)  225 mm  Axis 1  555°/s  475°/s  Axis 2  475°/s  Axis 3  585°/s  Axis 4  1035°/s  Axis 5  1135°/s  Axis 6  Maximum speed at load gravity center  8,2 m/s	
Minimum reach between axis 3 and 5 (R. b)  225 mm  Axis 1  555°/s  475°/s  Axis 2  475°/s  Axis 3  585°/s  Axis 4  1035°/s  Axis 5  1135°/s  Axis 6  Maximum speed at load gravity center  8,2 m/s	
Minimum reach between axis 3 and 5 (R. b)  225 mm  Axis 1  555°/s  Axis 2  475°/s  Axis 3  585°/s  Axis 4  1035°/s  Axis 5  Axis 5  Axis 6  1575°/s  Maximum speed at load gravity center  8,2 m/s	
Axis 1 555°/s  Axis 2 475°/s  Axis 3 585°/s  Axis 4 1035°/s  Axis 5 1135°/s  Axis 6 1575°/s  Maximum speed at load gravity center 8,2 m/s	
Axis 6 1575°/s  Maximum speed at load gravity center 8,2 m/s	
Axis 6 1575°/s  Maximum speed at load gravity center 8,2 m/s	
Axis 6 1575°/s  Maximum speed at load gravity center 8,2 m/s	
Axis 6 1575°/s  Maximum speed at load gravity center 8,2 m/s	
Axis 6 1575°/s  Maximum speed at load gravity center 8,2 m/s	
Maximum speed at load gravity center 8,2 m/s	
Axis 5 0,1 kg.m²  Axis 6 0,03 kg.m²	
Axis 6 0,03 kg.m <sup>2</sup>	
Weight 27 kg	
Brakes All axis	
Pneumatic  2 direct lines between the base and the form optional solenoid valve 5/2-way (compress or 3/2-way (vacuum) monostable of 1 female 8-contact socket (2 shielded twisted pairs, 3 power contacts)	
Electrical  1 female 8-contact socket (2 shielded twisted pairs, 3 power contacts)	
Cleanroom standard - ISO 14644-1 5	
Protection class (*wrist) according to standard NF EN 60529	
Stäubli CS8 series controller CS8C	
Installation environment	
Working temperature according to standard directive NF EN 60 204-1 + 5°C to + 40°C	
Humidity according to standard directive NF EN 60 204-1 30% à 95% max. non-condensin	ng
Attachment methods Floor/Wall/Ceiling	
Vertical cable outlet version (8)	
Pressurized version <sup>(4)</sup>	
HE (Humid Environment) version (5)	
Market specific versions	
CR Cleanroom - class 4 cleanliness - ISO 14644-1	
SCR Cleanroom - class 2 cleanliness - ISO 14644-1	
Plastics - Euromap 12/67 interface	

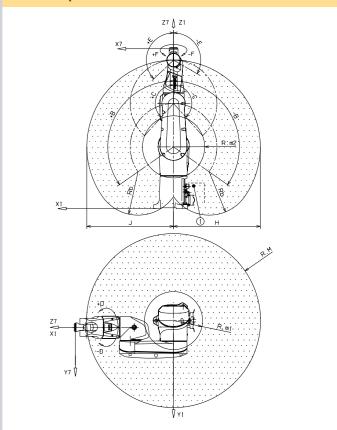


- (1) Under special conditions, consult us.
- (2) Software configurable up to  $\pm 18000^{\circ}.$
- (3) Pressurization kit: necessary for use in an environment with high dust levels or with substantial liquid splashing. This kit generates positive pressure in the arm. Factory installation only and required with Pressurization kit.
- (4) Pressurization kit: necessary for use in an environment with high dust levels or with substantial liquid splashing. This kit generates positive pressure in the arm. Factory installation only and required with Pressurization kit..
- (5) Version HE (Humid Environment): designed for use in humid and oxidizing environments. The arm components are painted individually, providing additional arm protection against oxidation and corrosion. Factory installation only and required with Pressurization kit.

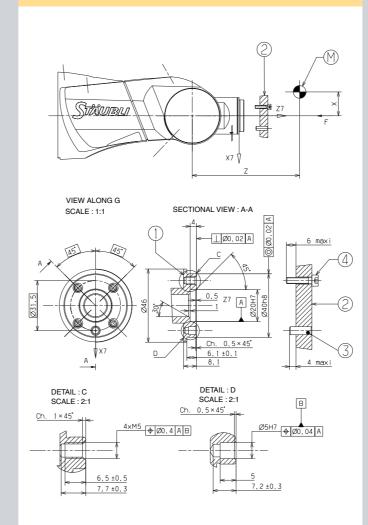
#### TX40 dimensions



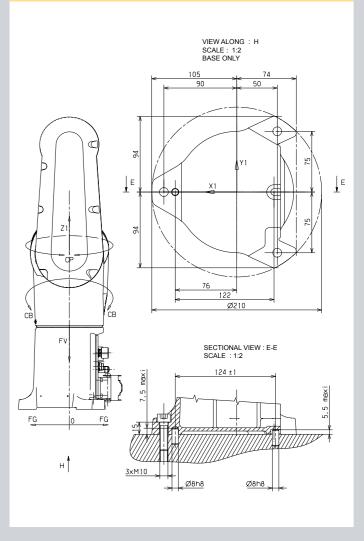
#### Work envelope



### Wrist



## Mounting ( not for vertical cable outlet option)





# **Product benefits**

The TX40 robot series feature unique benefits to fit in all environments providing the best possible process quality and increased productivity.



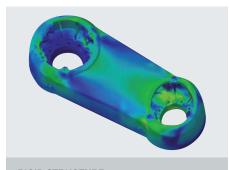
IP67 rating, submersible, high robustness, limited built-up on wrist.



STÄUBLI PATENTED REDUCTION GEAR SYSTEMS Unmatched precision, flexibility and speed, high rigidity, reduced maintenance.



FOREARM CONNECTIONS
Electrical and pneumatic connections close to the tool, user lines already installed.



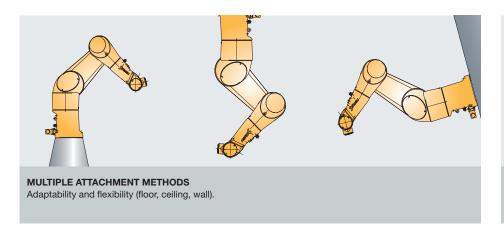
**RIGID STRUCTURE**Better dynamic performance.

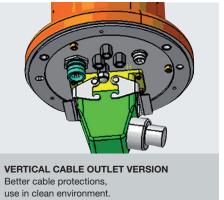


**ENCLOSED STRUCTURE**Easy to clean and use in clean or hostile environments.



**ARM FINISH**Smooth or textured, color customization.





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