

OPERATING MANUAL VERSION 3 MODEL 1600 PRESSURE SENSITIVE LABELER

END USER: SORTIMAT TECHNOLOGY

SERIAL NUMBER: 14-0554

MANUFACTURED: JANUARY 2008

REVISED: JUNE 2008

VERSION 4: October 2016

PLEASE HAVE MODEL NUMBER AND SERIAL NUMBER AVAILABLE
WHEN CALLING FOR PARTS OR SERVICE

LABELING SYSTEMS INC
32 SPRUCE STREET
Oakland, NJ
201-405-0767

Thank you for purchasing an LSI Labeling System. Under proper operating conditions, this labeling system will provide many years of trouble free performance. This manual has been prepared to assist with the set-up and maintenance of the labeling system. It is written for production line and maintenance personnel. LSI equipment is manufactured to the strictest standards and is thoroughly tested before being released into the field. Occasionally, a problem may arise in the field which is not covered in this manual. Remember, we are only a phone call away.

Please have model number and serial number available when calling for parts or service.



WARNING!

Machinery in this manual may be pictured without guards or covers.

This is done only for purposes of illustration clarity.

Never operate any machine without all guards and covers in place.



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SECTION A: SYSTEM DATA SHEET

LABELER SPECIFICATIONS

System Model No.: 1600

Serial Number: 14-0554

Head Serial No's: 40-0334R and 40-0335L Application Rate: 60 products per minute Label Size: 1.218"(F) x 4.25" (W)

Main Input Air: 60 psi

Labeling Heads

Head Model No.:

Applicator Type:

O10 Wipe on

Product Sensor:

Banner SM312CV

Motor:

Stepper

Electrical:

115 VAC / 60 Hz

Fuse Designations:

Power: 10 Amp
Motor 2 Amp
Power Supply 2 Amp

Pneumatic Requirements:

Recommended Settings 60 psi

Factory Default Settings:

Head Serial No.	40-0334	40-0335
Printer Time	200	N/A
Shutdown Time	10	15
Feed Delay Time	0	0
Product Delay	253	238
Label Stop	590	590
Aux Pulses/Inch	10842	10842



SECTION A: SYSTEM DATA SHEET

LABELER SPECIFICATIONS

Fuse Designations:

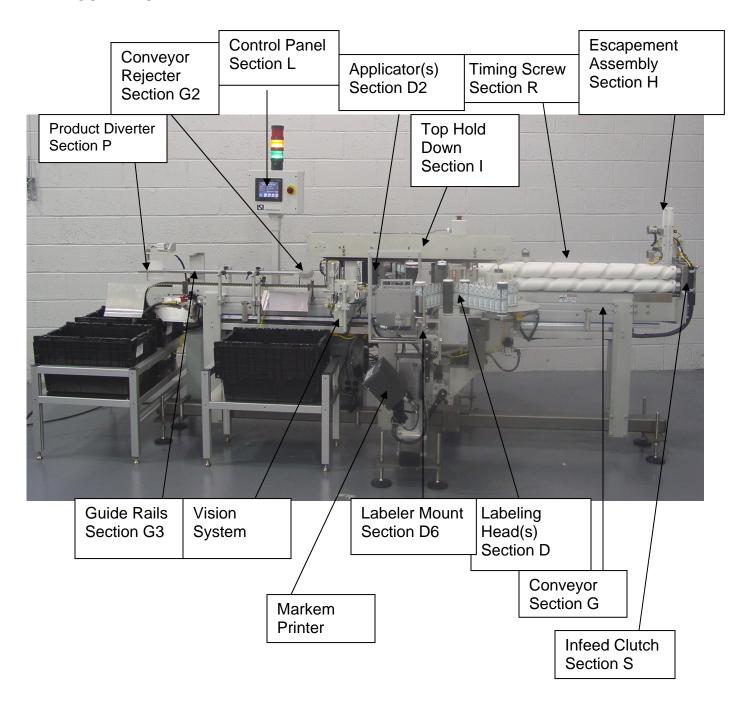
Main Power	15 amp
Power Supply	5 amp
Timing Screw	5 amp
Conveyor Drive	5 amp
Top Hold Down	5 amp



SECTION C: ASSEMBLY INDEX

MAJOR ASSEMBLIES

PLEASE NOTE: THE CONVEYOR BELT HAS CHANGED DUE TO MODIFICATIONS REQUIRED ON THE SYSTEM SEE SECTION G1 CONVEYOR FOR ACTUAL PICTURE OF CURRENT CONVEYOR BELT.





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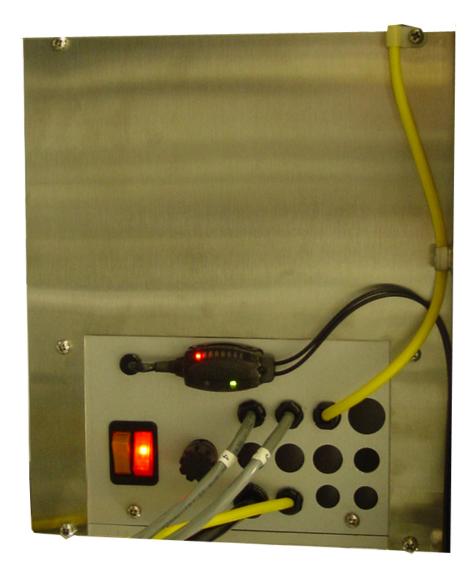
SECTION D:

Introduction / Features

Labeling Head Controls

The front panel of the Series 40 provides access to all user adjustable labeling head functions. Front panel controls include:

- Power Switches
- Label Sensor Interface
- Labeler Fuse



Front Panel of the Series 40 Labeler



Panel Controls

Power Switches

The front panel incorporates two power switches with indicator lights.

Main Power Switch

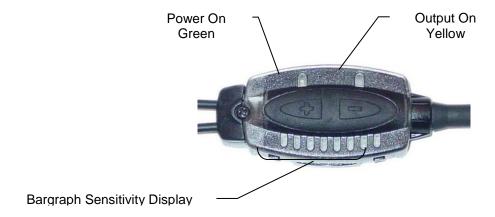
Controls main power to the head, including the DC power supply, control package, and stepper motor drive controller. A red led illuminates to indicate that the main power is on.

Auxiliary Power Switch

Controls power to optional auxiliary devices including the applicator vacuum fan, power rewind motor and printer. An amber LED illuminates to indicate that the auxiliary power is on.

Label Sensor Interface

The body of the high performance fiber optic label sensor is mounted on the front panel of the labeler. The Sensor Interface includes 10 LEDs and 2 pushbuttons allowing the user to monitor and manually control all label sensor functions. There are two sensors used for the interface. The sensors are located on the web path and the tip of the peeler bar.



Fiber Optic Label Sensor Interface



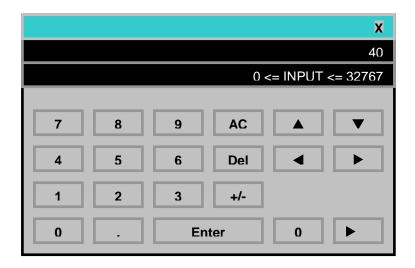
Operator Interface

Operator Interface

The Series 40 includes an Operator Interface with a bright LCD touch screen display. The Operator Interface on this machine is located on the Main Control Box. All performance statistics and user adjustments are accessed through the Operator Interface. The Operator Interface menu is divided into 8 screens.

Changing Parameters

To change Parameters select white box of the parameter Enter Parameter change using keep pad below and Press ENTER. Press "X" to close screen and return to previous screen. Touch **Select Parameters** screen to update Head Parameters.



Operator Interface

Navigation Guide

There are 6 security levels defined in this system (including the default) and are task-specific.

User Name	Description
Default	The operator has access to run the machine. They can load recipes, modify the running recipe data, clear alarms, and generally run the machine.
4	The technician has access to everything the operator does plus the ability to rename and save recipes, modify settings, and handle machine setup and maintenance.

Screen security is handled on the object level, so each object on the screen can have its own set of permissions. The three sets of access for any given object (button, etc.) are:

Access	Description
X	Not visible. This is used for objects that are not available to the current
	user.
R	Read-only. This is used for most display objects and for values that
	cannot be modified by the current user.
R/W	Read-write. This allows the current user full access to the object
	meaning they can operate the pushbutton or modify the value.





Select Product Screen

THIS IS INITIAL SCREEN WHICH WILL APPEAR WHEN SYSTEM IS TURNED ON.



Touch Button Functions

This is the screen that appears when the labeler finishes its boot process.

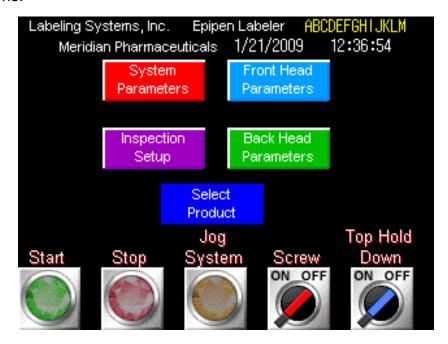
Object	Description	Default	4	Min Entry	Max Entry
US	Select and load the US recipe	R/W	R/W	N/A	N/A
Canada	Select and load the Canada recipe	R/W	R/W	N/A	N/A
Other	Select and load the Other recipe	R/W	R/W	N/A	N/A
Other 2	Select and load the Other 2 recipe	R/W	R/W	N/A	N/A
No Label	Select and load the no label recipe	X	R/W	N/A	N/A
Enter Password	Enter the password to select No Label recipe	R/W	R/W	N/A	N/A



Operator Interface

Main Screen

This is the main operation screen for the labeler. Unless noted below alarm messages are not touch buttons.



Object	Description	Default	4	Min Entry	Max Entry
System Parameters	Opens the System Parameters screen	R/W	R/W	N/A	N/A
Front Head Parameters	Opens the Front Head Parameters screen	R/W	R/W	N/A	N/A
Inspection Setup	Opens the Inspection Setup screen	R/W	R/W	N/A	N/A
Back Head Parameters	Opens the Back Head Parameters screen	R/W	R/W	N/A	N/A
Select Product	Opens the Product Selection screen	R/W	R/W	N/A	N/A
Start	Start the machine	R/W	R/W	N/A	N/A
Stop	Stop the machine	R/W	R/W	N/A	N/A
Jog System	Jog the machine	R/W	R/W	N/A	N/A
Screw	Turn the infeed screw on/off.	R/W	R/W	N/A	N/A
Top Hold Down	Turn the top hold down on/off	R/W	R/W	N/A	N/A
Low Label Front Head	Appears when front head has a low label condition. Touch to reset.	R/W	R/W	N/A	N/A
Low Label Back Head	Appears when back head has a low label condition. Touch to reset	R/W	R/W	N/A	N/A

SECTION D: OPERATOR INTERFACE



Operator Interface

System Parameters Screen

System Speed- This is the speed of the conveyor. This setting should not be changed!

Reject Time – time reject cylinder stays extended

Rejected Products – number of products discarded due to failing inspection

Consecutive Rejects Before Shutdown – number of products rejected by inspection station without interruption before stopping conveyor

Products in Each Bin – Maximum number of products in each bin. Bin is FULL when the maximum number is reached.

Products in Bin 1 – number of products in Bin 1 location

Products in Bin 2 – number of products in Bin 2 location

Total Labeled Products-number of products labeled

Products per Minute- the current label dispense rate based on the number of labels detected by the Label Sensor



Reset Counters Used to go to Reset Counters Screen

Main Used to go to Main Screen

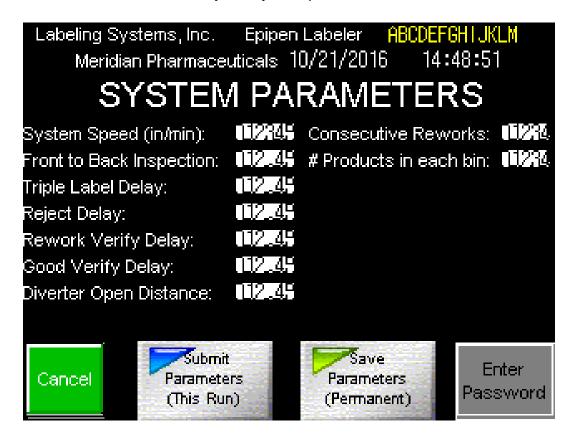
Edit Used to go to System Parameters Edit Screen



Operator Interface

System Parameters Edit Screen

This screen allows the user to modify the system parameters.



Touch Button Functions

Object	Description	Default	4	Min Entry	Max Entry
System Speed (in/min)	Enter the system speed in in/min.	R/W	R/W	10	535
Front to Back Inspection	Distance in inches from Back Inspection Sensor to Front Inspection Sensor	R/W	R/W	0.01	36.00
Triple Label Delay	Distance in inches from Back Inspection Sensor to Triple Label Camera trigger location	R/W	R/W	0.01	36.00
Reject Delay	Distance in inches from Back Inspection Sensor to reject trigger location	R/W	R/W	0.01	36.00
Rework Verify Delay	Distance in inches from Back Inspection Sensor to rework location (the point where the product falls into the rework bin)	R/W	R/W	0.01	36.00
Good Verify Delay	Distance in inches from Back Inspection Sensor to Conveyor Verify Sensor	R/W	R/W	0.01	36.00
Diverter Open Distance	Distance in inches the diverter must stay open to allow a good product to pass.	R/W	R/W	0.01	36.00



System Parameters Edit Screen

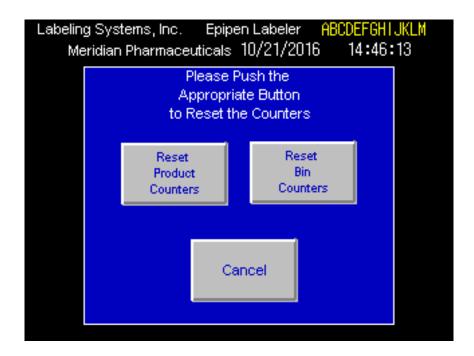
Object	Description	Default	4	Min Entry	Max Entry
Consecutive Reworks	Number of consecutive rework products before the machine faults	R/W	R/W	0	32767
# Products in each bin	Number of products in each bin	R/W	R/W	0	32767
Cancel	Return to the previous screen and discard all changes	R/W	R/W	N/A	N/A
Submit Parameters (This Run)	Submit parameters for this run only (don't save to recipe).	R	R/W	N/A	N/A
Submit Parameters (Permanent)	Submit parameters permanently (save to the recipe)	R	R/W	N/A	N/A
Enter Password	Enter password to allow operation of submit parameters buttons	R/W	R/W	N/A	N/A



Operator Interface

Reset Counters Screen

This screen allows the counters to be reset.



Touch Button Functions

Object	Description	Default	4	Min Entry	Max Entry
Reset Product Counters	Reset the product counters	R/W	R/W	N/A	N/A
Reset Bin Counters	Reset the product count for each bin	R/W	R/W	N/A	N/A
Cancel	Return to previous screen	R/W	R/W	N/A	N/A



Operator Interface

Front Head Parameter Screen #1 (Display):

This screen displays the system parameters. All parameter values are read-only for all users.

Product Delay – the time delay between when the product input trigger turns on to when the labeling cycle begins

Feed Delay – the time delay between the end of the applicator dwell and when the label should be dispensed.

Label Stop – the distance in pulses from the label sensor to the tip of the peeler bar.

Shutdown Time – The time (in 1/100ths of a second) before shutdown is activated. The timer will start when the label begins dispensing. To clear the error, hit the RST button, and then push the BACK button.

Encoder Pulses/Inch—controls speed ratio between labeling head and conveyor



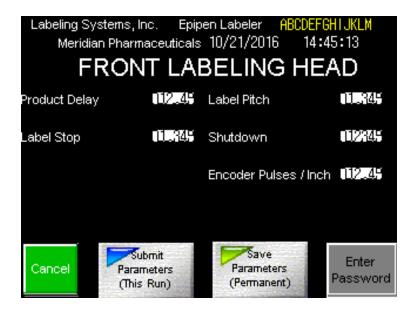
Object	Description	Default	4	Min Entry	Max Entry
Main	Return to System Screen	R/W	R/W	N/A	N/A
Reset	Reset front head alarms	R/W	R/W	N/A	N/A
Jog	Jog a single label on front head	R/W	R/W	N/A	N/A
Teach	Teach label sensor on front head	R/W	R/W	N/A	N/A
Edit	Open the Front Head Parameter Edit Screen	R/W	R/W	N/A	N/A



Operator Interface

Front Head Parameter Screen #2 (Edit):

This screen allows the user to modify the front head parameters.



Touch Button Functions

Object	Description	Default	4	Min Entry	Max Entry
Product Delay	Delay Distance in inches from Front head sensor to start of label dispense		R/W	0.01	36.00
Label Pitch	Distance in inches from front of one label on the web to the front of the next label on the web	R/W	R/W	0.001	12.000
Label Stop	Distance in inches from label sensor trigger position to label stop position.	R/W	R/W	0.001	12.000
Shutdown	Time in seconds allowed for label to dispense before causing a fault.	R/W	R/W	0.1	3276.7
Encoder Pulses/Inch	Encoder input scale in pulses/in	R/W	R/W	0.01	327.67
Cancel	Return to the previous screen and discard all changes	R/W	R/W	N/A	N/A
Submit Parameters (This Run)	Submit parameters for this run only (don't save to recipe).	R	R/W	N/A	N/A
Submit Parameters (Permanent)	Submit parameters permanently (save to the recipe)	R	R/W	N/A	N/A
Enter Password	Enter password to allow operation of submit parameters buttons	R/W	R/W	N/A	N/A



Operator Interface

Back Head Parameter Screen #1 (Display):

This screen displays the Front Labeling Head Parameters, Product Delay, Feed Delay, Label Stop, Shutdown Time, Printer Time and Encoder Pulses/Inch.

Product Delay – the time delay between when the product input trigger turns on to when the labeling cycle begins

Feed Delay – the time delay between the end of the applicator dwell and when the label should be dispensed.

Label Stop – the distance in pulses from the label sensor to the tip of the peeler bar.

Shutdown Time – The time (in 1/100ths of a second) before shutdown is activated. The timer will start when the label begins dispensing. To clear the error, hit the RST button, and then push the BACK button.

Printer Time – The dwell time for the printer such as hot stamp. This time will be activated once the label motion is stopped.

Encoder Pulses/Inch—controls speed ratio between labeling head and conveyor

Meridian Pharm	aceuticals	en Labeler ABCDEFGH 10/21/2016 14:42 ELING HEAD	2:50
Product Delay	012.45	Label Pitch	01.345
Label Stop	01.345	Shutdown	012345
Printer Time	Param	Encoder Pulses / Inch eters are for display only! :, push "Edit">	012.45 Edit
Main		Reset Jog	Teach



Operator Interface

Back Head Parameter Screen #1 (Display):

This screen displays the back head parameters. All parameter values are read-only for all users.

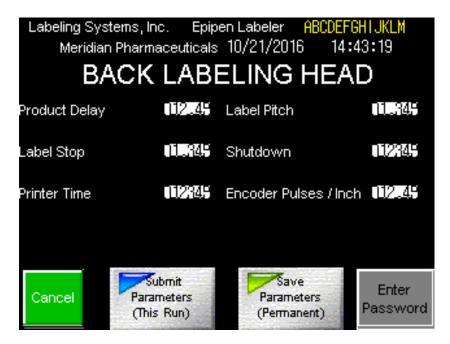


Object	Description	Default	4	Min Entry	Max Entry
Main	Return to System Screen	R/W	R/W	N/A	N/A
Reset	Reset front back alarms	R/W	R/W	N/A	N/A
Jog	Jog a single label on back head	R/W	R/W	N/A	N/A
Teach	Teach label sensor on back head	R/W	R/W	N/A	N/A
Edit	Open the Back Head Parameter Edit Screen	R/W	R/W	N/A	N/A



Operator Interface

Back Head Parameter Screen #2 (Edit):



Touch Button Functions

Object	Description	Default	4	Min Entry	Max Entry
Product Delay	Distance in inches from Back head sensor to start of label dispense	R/W	R/W	0.01	36.00
Label Pitch	Distance in inches from front of one label on the web to the front of the next label on the web	R/W	R/W	0.001	12.000
Label Stop	Distance in inches from label sensor trigger position to label stop position.	R/W	R/W	0.001	12.000
Shutdown	Time in seconds allowed for label to dispense before causing a fault.	R/W	R/W	0.1	3276.7
Printer Time	Time in ms allowed for print cycle	R/W	R/W	0	32767
Encoder Pulses/Inch	Encoder input scale in pulses/in	R/W	R/W	0.01	327.67
Cancel	Return to the previous screen and discard all changes	R/W	R/W	N/A	N/A
Submit Parameters (This Run)	Submit parameters for this run only (don't save to recipe).	R	R/W	N/A	N/A
Submit Parameters (Permanent)	Submit parameters permanently (save to the recipe)	R	R/W	N/A	N/A
Enter Password	Enter password to allow operation of submit parameters buttons	R/W	R/W	N/A	N/A



Operator Interface

Inspection (Vision) Setup Screen:

This screen displays Vision Inspection Statistics (Good Products + Bad Products). Bad products will be removed from the conveyor by the Conveyor Rejecter.

To stop the inspection of products, turn off the Vision Bypass by hitting button on this screen.



Touch Button Functions

Object	Description	Default	4	Min Entry	Max Entry
Send Data to Devices	Send barcodes & lot code to cameras and printer	R/W	R/W	N/A	N/A
Edit	Open the Vision Parameter Edit Screen	R/W	R/W	N/A	N/A
Main	Return to System Screen	R/W	R/W	N/A	N/A
Reset Counters	Reset Vision Inspection Statistics	R/W	R/W	N/A	N/A



Operator Interface

Inspection (Vision) Screen #2 (Edit):



Object	Description	Default	4	Min Entry	Max Entry
Front Label Barcode	Enter Front Label Barcode	R/W	R/W	1000	32767
Back Label Barcode	Enter Back Label Barcode	R/W	R/W	1000	32767
Lot Code	Enter Lot Code	R/W	R/W	N/A	N/A
Cancel	Return to the previous screen and discard all changes	R/W	R/W	N/A	N/A
Submit Parameters (This Run)	Submit parameters for this run only (don't save to recipe).	R	R/W	N/A	N/A
Submit Parameters (Permanent)	Submit parameters permanently (save to the recipe)	R	R/W	N/A	N/A
Enter Password	Enter password to allow operation of submit parameters buttons	R/W	R/W	N/A	N/A



Operator Interface

Numeric Entry Screen

This is the numeric entry keypad. All items are operable by all users.



ASCII Entry Screen

This is the ASCII entry keypad. All items are operable by all users.

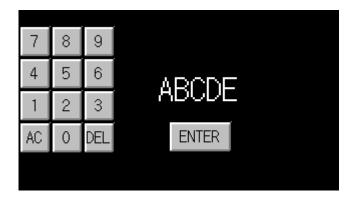




Operator Interface

Lot Code Input Screen:

Screen where lot code is entered



Engineering Lot Code Screen:

This appears in engineering mode only with Security level 3 or Higher. This will appear on Vision Edit Inspection Screen



Entering code will bring you to Lot Code Input Engineering Screen.

Lot Code Input Engineering Screen:

Screen where Engineering lot code is entered.





Operator Interface

Alarm Screen:

This window will appear when an alarm is active. Touch the alarm to reset it – all alarms are operable by all users.

ALARM -	Push Text	to Reset
Product Jam	Consecutive	Web Break
Timing Screw	Rework Products	Front Head
Msion System	Front Camera	Web Break
Not Online	Sensor Failure	Back Head
Outfeed Bins	Back Camera	Unexpected Product
Full-Empty Both	Sensor Failure	Rework Bin
Rework Bin	Good Product	Unexpected Product
Not In Place	Rejected	Good Verify
Outfeed Bin	Rework Product	Product Not
Not In Place	Not Rejected	Verified
	E-STOP	Reset Pushed
	ACTIVATED	Please Wait
	PUSH TO RESET	rease water



Operator Interface

Waiting Screen:

This screen appears once a recipe is selected. There are no user operable items on this screen.





SECTION D: LABEL SENSOR

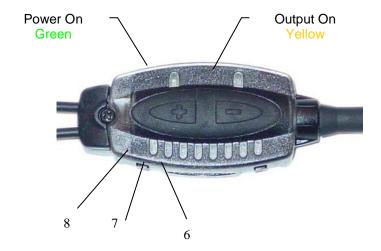
Leading / Trailing edge Trigger

Label Sensor

Leading/Trailing Edge Trigger

Set-up mode is used to change label sensor output response for:

- Light or Dark Operate
- 30 Millisecond Off Delay



The status LEDs (6, 7 and 8), active only during Set-up mode, indicate the output response configuration. Four combinations are possible:

Trigger Sensor Mode Delay		Status LED			
Trigger	Sensor wode	Delay	6	7	8
Trailing Edge	Light Operate	No Delay	Off	Off	On
Leading Edge	Dark Operate	No Delay	Off	On	Off
Not Used	Dark Operate	30ms Delay	On	On	Off
Not Used	Light Operate	30ms Delay	On	Off	On

To access set-up mode, press and hold both + and – buttons until the green power indicator turns off. Press either + or – to toggle through the four possible settings. Press and hold both + and – until the green power LED turns back on.

If Set-up mode is interrupted and remains inactive for 60 seconds, the sensor returns to run mode with the most recent settings (i.e. exits and saves current selection).



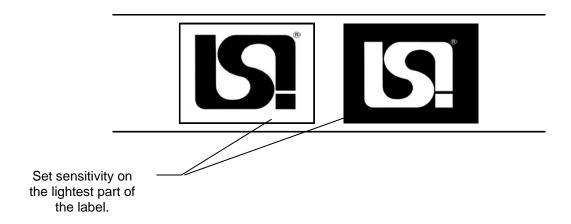
SECTION D: LABEL SENSOR

Manual Adjust Label Sensor Sensitivity

Manually Adjusting Label Sensor Sensitivity

Press + or – on the label sensor to increase or decrease label sensor sensitivity. The lighted bargraph LEDs will move to reflect the increase or decrease.

Adjust sensitivity so the sensor "sees through" the web but not through the label. Sensitivity should be set on the lightest (least opaque) portion of the label.



After manual adjustment, press **JOG** to ensure that label sensitivity has been set properly.

Auto-Teach Label Sensor Sensitivity

The standard label sensor package includes an Auto-Teach feature, which automatically adjusts sensor sensitivity.

To Auto-Teach the label sensor, thread the labeler and press RST, then press (TEACH). The Teach light on the Operator Interface will illuminate indicating that the labeler is in teach mode and the labeler will continuously dispense labels at 200 inches per minute for five seconds During this time, the power LED on the label sensor will turn off and LEDs 6 and 7 will alternately flash, indicating that the teach sequence is active. At the end of 5 seconds, the web stops, and the Teach LED on the operator display extinguishes. LED 3 on the label sensor will turn on briefly to indicate that the Teach has been accepted. The green power LED on the label sensor will illuminate to indicate that Auto-Teach is complete.

Press **JOG** to ensure that label sensitivity has been set properly.

In the event of an Auto-Teach failure, LEDs 1, 3, 5 and 7 will flash alternately and the label sensor will return to run mode without changing settings. In this case, the label sensor sensitivity must be manually set as described above.

SECTION D: ALARMS

Low Label / Web Break

Low Label/Web Break Alarms (optional)

The **Series 40** Alarm Package option detects and annunciates the status of the label unwind reel and the label web. Sensors on the labeling head detect and alarm the following states:

- Low Label
- Label Out/Web Break

A photo-eye located on the unwind assembly monitors the unwind reel and detects a Low Label condition.



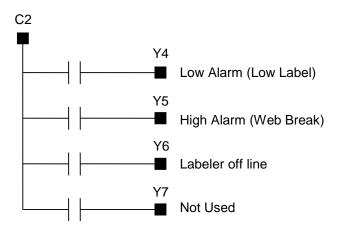
A convergent beam photoeye detects the presence of the web on the web drive roller. Absence of web on the drive roller indicates a Label Out/Web Break condition.

SECTION D: ALARMS

Low Label / Web Break



Two dry contact, digital outputs are available to communicate alarm conditions to outside devices. These outputs are located on the PLC I/O expansion module. Output Y4 turns on to indicate Low Alarm. Output Y5 turns on to indicate High Alarm. The program to control these outputs is included in the base *Series 40* control program. No custom programming is required. Dry contacts are rated for 2 Amps at 250 Volts AC or 30 Volts DC.



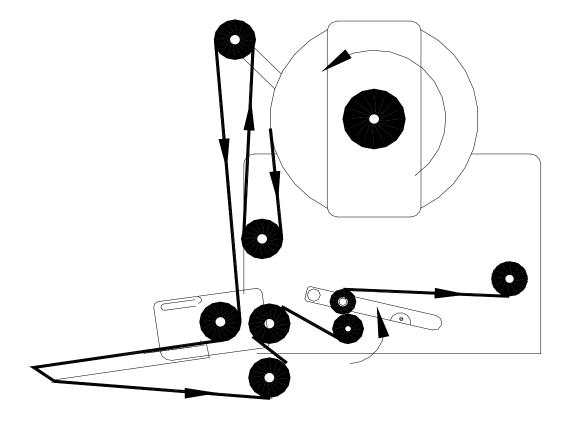


THREADING DIAGRAMS

Standard Threading Diagram

Threading the Machine

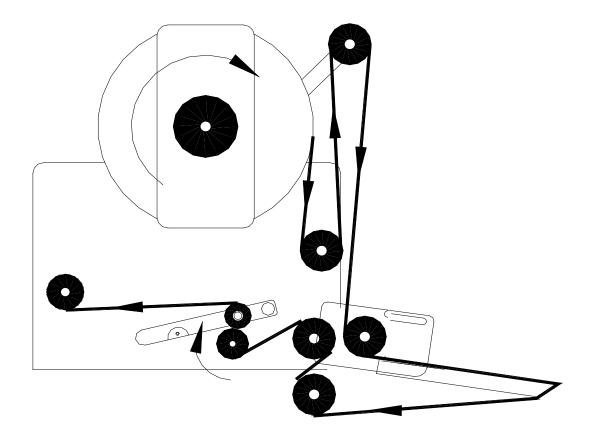
Model 40 Left Hand (12" Unwind / Single Roller Dancer / Slaved Rewind) shown.



THREADING DIAGRAMS

Standard Threading Diagram

Model 40 Right Hand (12" Unwind / Single Roller Dancer / Slaved Rewind) shown





SECTION D: MAINTENANCE GUIDE

Stepper Drive

This Series 40 utilizes a P70360 Pacific Scientific High Performance MicroStepping Drive to control the stepper motor.

Please refer to P70360 Pacific Scientific High Performance MicroStepping Drive Reference Guide for additional information.



P70360 Pacific Scientific High Performance MicroStepping Drive

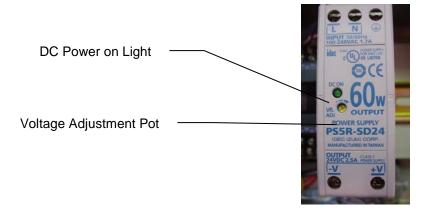


SECTION D: MAINTENANCE GUIDE

Power Supply / PLC

DC Power Supply

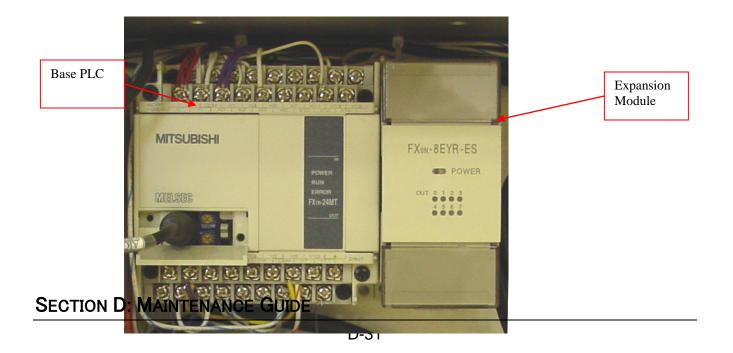
The Series 40 utilizes a 24 volt DC power supply to power the PLC and various I/O devices. The power supply incorporates a green pilot light on the front face. The pilot light illuminates to indicate that DC power is available.



The front panel of the power supply includes a potentiometer to allow adjustment of the power supply's output voltage. Output voltage is set to 24 volts at the factory. No user adjustment should be required.

PLC

The Series 40 utilizes a PLC for logical control of the labeling sequence and to manage the operator interface. If the Low Label/Web Break Alarm Package is selected or the Applicator 2 Output is required, an I/O expansion module with 8 additional Outputs can be added. The Base PLC includes an Input Voltage Selector Switch, located on the left side of the case. This switch must be set to 24V Input.





PLC / Inputs - Outputs

Input Specifications

Maximum Input Rating 26.4 VDC
Input Voltage 24VDC, 5.3mA
Minimum On Voltage 19V
Minimum Off Current 2mA

Base Module Output Specifications

Rated Load 30 VDC, 0.3A

Peak Load Current 1.0A

Maximum Off Voltage 30VDC

Leakage Current in Off State 100µA or Less

Residual Voltage in On State 0.8V or Less

Expansion Module Output Specifications

 $\begin{array}{lll} \text{Output Type} & \text{Relay} \\ \text{Rated Load} & 250\text{VAC/30VDC} \\ \text{Rated Output Current} & 2\text{A/Point, 4A Common} \\ \text{On Resistance} & 150\text{m}\Omega \text{ or Less} \\ \text{Residual Voltage in On State} & 0.8\text{V or Less} \\ \end{array}$



SECTION D: ELECTRICAL

PLC Designations

Note: Electrical Section may vary for LSI Systems. Consult Electrical section in systems manual for correct schematics and diagrams.

PLC I/O

Input designation	Model 40	Output designation	Model 40
X0	Pulse Loop-Back	Y0	Pulse Output
X1	Encoder 1	Y1	Printer Output
X2	Label Sensor	Y3	Applicator 1
X3	Product Sensor	Y4	Printer
X4	Encoder 2	Y5	Air Assist
X12	Low Label	Y6	Pulse Stop
X13	Web Break	Y7	Vacuum
		Y11	Auto Teach
		Y24	Low Label Alarm Contact
		Y25	Web Break
		-Y26	System Ready
		-	

^{*}Note - Expansion Module is only used when Alarm Package is purchased



SECTION D: MACHINE ADJUSTMENTS

Unwind / Dancer

Mechanical Adjustments

All Series 40 labelers come complete from the factory and are adjusted to meet the operational specifications of the original application. The components described below may need occasional adjustment to ensure optimal performance.

BEFORE PERFORMING ANY ADJUSTMENTS, ENSURE THAT THE MACHINE IS DISCONNECTED FROM BOTH ELECTRICAL POWER AND COMPRESSED

Adjusting the Unwind Brake Belt

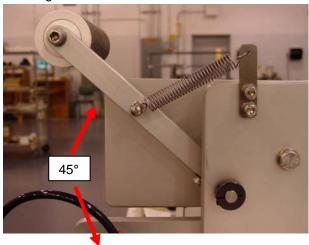
The unwind brake stops the unwind roll from free wheeling. Unwind brake tension is controlled by the position of the dancer arm. When properly adjusted, the dancer are should rest with the brake fully engaged, at approximately 45° from horizontal. Pulling down on the dancer arm will release the brake.

To adjust the unwind brake:

- Loosen socket head cap screw "1" using an Allen wrench until the brake belt mount turns freely.
- Using a second Allen wrench inserted into screw "2", turn the brake belt mount until the dancer arm rests at approximately 45°.



3. Tighten screw "1".

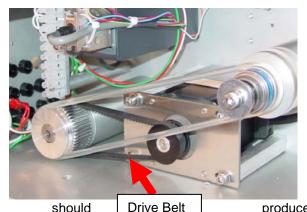


When properly set, the tension arm should be at approximately a 45° angle from the edge of the main plate when in a resting position.



SECTION D: MACHINE ADJUSTMENTS

Drive Belt / Rewind Tension



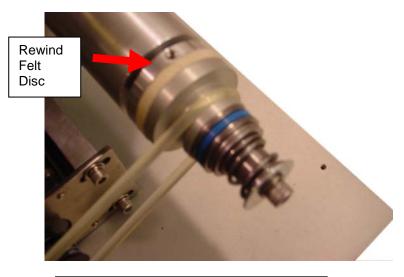
Adjusting the Drive Belt

To adjust web drive belt tension:

- 1. Loosen the 4 mounting screws, that attached the motor mounting plate to the stand offs.
- After confirming that belt teeth are properly engaged in the pulley grooves, adjust motor position to set belt tension and retighten mounting screws.
- 3. When the belt is properly tensioned, light pressure in the center of the span between the 2 pulleys

produce approximately 1/8" of belt movement.

Setting Rewind Tension



Note: Add **1 drop** of oil to the felt disc to help prevent squeaking. This will also help the disc from drying out. Add oil to disc once every 6 months.

Rewind tension on the standard Series 40 slaved rewind assembly is set at the factory using shims. Field adjustment should never be required.

Over time, rewind tension may decrease due to wear or contamination of the felt rewind clutch disk or wear or contamination of the rewind drive belt.

To replace the felt rewind clutch disc.

- 1. Remove the socket head cap screw at the end of the shaft.
- 2. Remove the washer, shims, spring, thrust bearing and clutch plate/drive sheave from the rewind shaft.
- 3. Remove old felt disc and replace with a new felt disc. New disc must by clean and dry and free of oil.
- 4. Replace the clutch plate / drive sheave, thrust bearing, spring and shims in the reverse order from the way they were removed.
- 5. Install screw and washer and tighten.

To replace the rewind drive belt:

- 1. Remove the old rewind drive belt. The drive belt is very elastic and can be removed by hand without tools.
- 2. Clean the sheaves to remove any oil or contamination.
- 3. Install a new rewind drive belt.

SECTION D: MACHINE ADJUSTMENTS



Power Rewind Tension

Adjusting Rewind Tension (Powered Rewind)

Rewind tension on the optional powered rewind assembly may require periodic adjustment as the clutch wears.

Rewind tension is adjusted by tightening (more rewind tension) or loosening (less rewind tension) the split collar, located at the end of the rewind drive shaft.

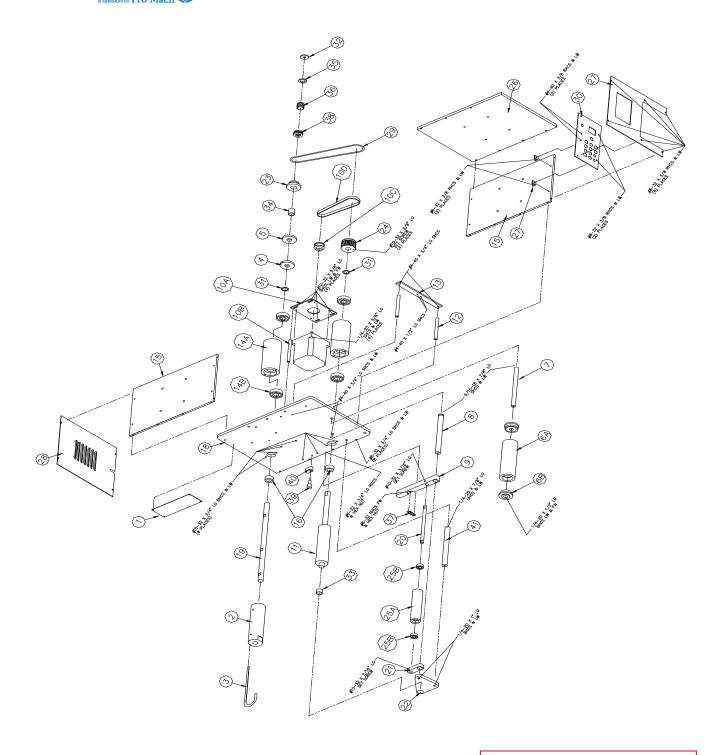
The collar is adjusted at the factory to be approximately 1/32" from the end of the shaft.

To adjust rewind tension:

- 1. Rotate the rewind roller until the locking screw for the split color is visible through the slot in the rewind roller.
- 2. Loosen the screw until the collar can be rotated.
- 3. Screwing the collar in (clockwise) increases tension. Screwing the collar out (counterclockwise) decreases tension.







41-0021LS LABELER, BASE,41, LEFT HAND, WITH SENSOR

SECTION D: MACHINE PARTS IDENTIFICATION

Parts list Base Labeler

a division of Pro Mach 🧇			
ID#	Qty	Description	
1	1	L.S.I. NAME PLATE PRE-STAMPED	
2	1	REWIND HUB MODIFIED	
3	1	CANDY CANE,1000	
4	1	REWIND BACK UP HUB	
5	1	FELT DISC	
6A	1	ROLLER, LONG	
6B	2	BALL BEARING, ROLLER END	
7	1	ROLLER SHAFT - LONG	
8	1	ROLLER ARM PIVOT SHAFT	
9	1	ROLLER ARM	
10A	1	MOTOR MOUNT	
10B	1	MOTOR MOUNT ROD	
10C	1	PULLEY 3mm, MODIFICATION	
10D	1	BELT 9mm WIDE	
11	1	DRIVE ROLLER ASS'Y	
12	2	SPACER, T.B.	
13	1	MOUNT, T.B.	
14A	1	SUPPORT, SHAFT	
14B	2	BALL BEARING 5/8 ID 1 3/8 OD	
15	2	PLATE, BOTTOM AND TOP	
16	1	SPACER	
18	1	PLATE, MAIN	
19	1	REWIND ASSY. 7"	
20	1	SHAFT, NIP ROLLER	
21	1	ROLLER SUPPORT	
		-	

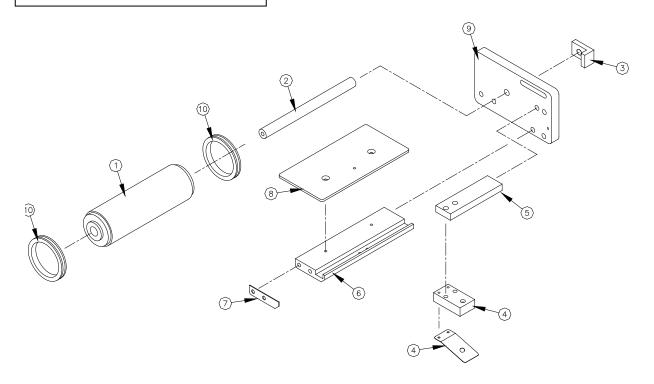
Parts list Base Labeler

ID#	Qty	Description
22	1	DRIVE ROLLER SUPPORT
23	1	PULLEY, REWIND, 1.172 P.D.
24	1	PULLEY, 28 TEETH
25A	1	ROLLER, NIP
25B	2	BALL BEARING 3/8 ID 7/8 OD
26	1	PLATE, SIDE
27	2	MOUNT, COVER
28	1	COVER, REAR
29	1	BELT, ROUND 3/16 DIA, ENDLESS
30	1	STRAIN RELIEF MOUNTING PLATE
31	2	WASHER
32	1	FLAT WASHER
33	1	PLAIN BUSHING
34	1	PLAIN BUSHING
35	4	BEARING
36	2	SHIM BUSHING
37	1	COMPRESSION SPRING
38	1	EXTENSION SPRING
39	2	BALL BEARING
40	1	THRUST BEARING
41	1	ROLLER ARM PIVOT SHAFT
42	1	CAM WITH SHOULDER BOLT
	1	KEY
	1	SUBASSY. ELECTRIC
	1	SHAFT SUPPORT
	1	SPRING HOLDER
	1	SENSOR, AMPLIFIER
	1	DISCONNECT CABLE FOR SENSOR



Parts list Peeler Bar

PEELER BAR ASSY. LH, 30/40 WITH SENSOR 41-0350LS

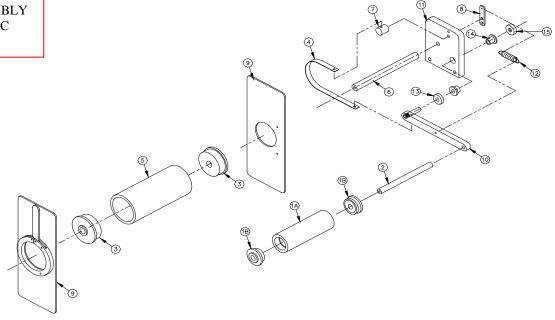


ITEM	QTY	DESCRIPTION
1	1	ROLLER ASSEMBLY
2	1	ROLLER SHAFT
3	1	CLAMP
4	1	FIBER SENSOR MOUNT
5	1	SUPPORT, PHOTOCELL
6	1	PEELER BAR
7	1	COVER
8	1	PEELER BAR PLATE
9	1	PEELER BAR SUPPORT
10	2	SPRING COLLAR
	1	AUTO TEACH AMPLIFIER
	1	PLASTIC FIBER
	1	PLASTIC FIBER



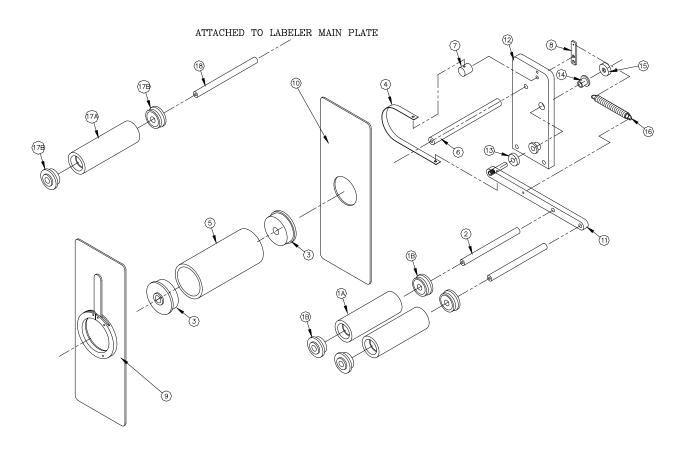
Unwind Assembly 12"





ITEM	QTY	DESCRIPTION
1A	1	ROLLER SHORT
1B	2	BALL BEARING, ROLLER END
2	1	ROLLER SHAFT – SHORT
3	2	ROLLER END
4	1	BRAKE END
5	2	UNWIND CORE
6	1	UNWIND ROLLER
7	1	MOUNT BRAKE BAND
8	1	MOUNT EXTENSION SPRING
9	1	UNWIND DISC ASSEMBLY WITH LOCK
10	1	TENSION ARM ASSEMBLY
11	1	PLATE UNWIND MOUNTING
12	1	EXTENSION SPRING
13	1	FLAT WASHER
14	2	FLANGE BUSHING
15	1	COLLAR CLAMP

Unwind Assembly 16"



UNWIND ASSEMBLY,L.H. 40, 16" DUAL DISK 41-0022L

Unwind Assembly 16"

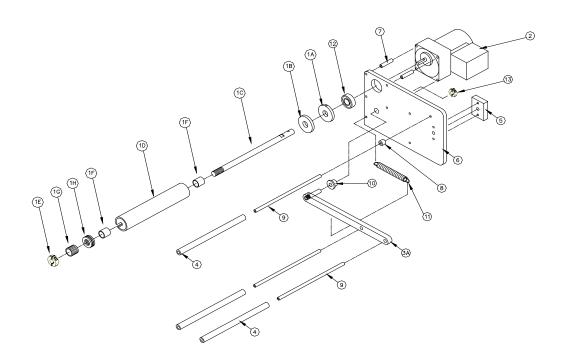
1ITEM	QTY	DESCRIPTION
1A	2	ROLLER – SHORT
1B	4	BALL BEARING, ROLLER END
2	2	ROLLER SHAFT
3	2	ROLLER END
4	1	BRAKE BAND
5	1	UNWIND CORE
6	1	UNWIND ROLLER
7	1	MOUNT BRAKE BAND
8	1	MOUNT EXTENSION SPRING
9	1	LET OFF DISK ASSY., 16"
10	1	LET OFF DISK ASSY., 16",CLAMP TYPE
11	1	TENSION ARM ASSEMBLY,DUAL
12	1	PLATE UNWIND MOUNTING
13	1	FLAT WASHER
14	2	FLANGE BUSHING
15	1	COLLAR CLAMP
16	1	EXTENSION SPRING
17A	1	ROLLER – LONG
17B	2	BALL BEARING, ROLLER END
18	1	ROLLER SHAFT-LONG

Power Rewind Assembly

ITEM	QTY	DESCRIPTION
1A	1	REWIND BACK UP HUB
1B	1	FELT DISC
1C	1	SHAFT, POWER REWIND
1D	1	ROLLER, REWIND SUB-ASSY
1E	1	COLLAR, THREADED MODIFIED
1F	1	THRUST BEARING 5/8 ID
1G	1	SPRING COMP .845 x .081 x ¾
1H	1	CANDY CANE
2	1	GEARMOTOR SUB-ASSEMBLY,MODEL 41
3A	1	TENSION ARM ASSEMBLY
4	3	TENSION ROLLER
5	1	NUT PLATE,MODEL 41
6	1	MOUNT PLATE, 41 POWER REWIND,RH
7	4	MOTOR MOUNT ROD
8	1	SPACER
9	3	SPACER SHAFT
	1	BUSHING,FLANGE
	1	SPRING, EXT438 X .037 X 3
	1	BALL BEARING 5/8 ID
	1	COLLAR CLAMP 3/8 ID
	1	MOTOR MOUNT PLATE
	1	STRAIN RELIEF BUSHING
	2FT.	CABLE,18/4, 300V,PVC



Power Rewind Assembly

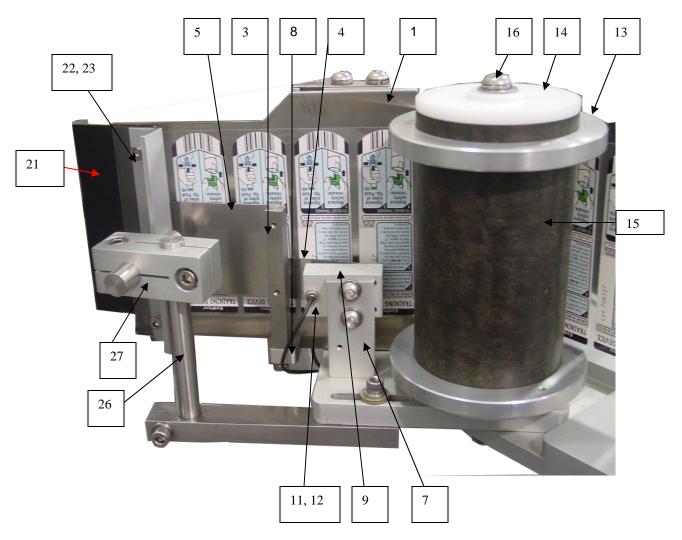




010 WIPE ON

The labeling heads each have a Model 10 Wipe-on applicator with a squeegee.

Applicator on Labeling Head Serial #40-0334 (includes Markem Printer)



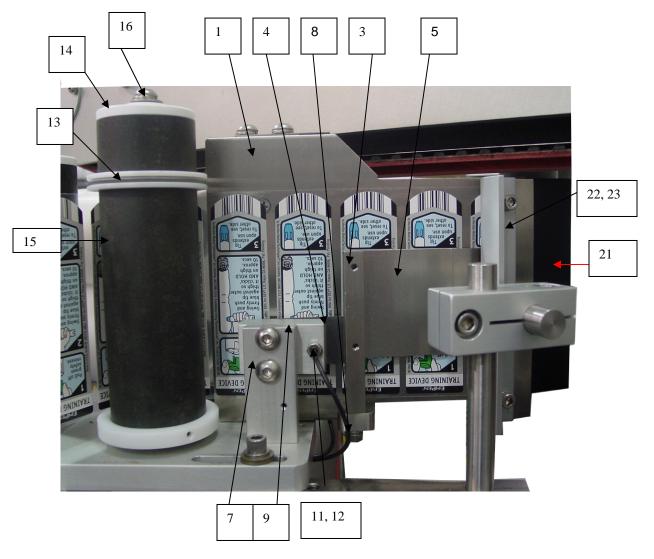
010 WIPE ON

ITEM	QTY	DESCRIPTION
1	1	PEELER BAR
2	1	MOUNT SPRING HOLDER
3	1	SPRING HOLDER
4	1	SPRING, 2.25L , 2.18 W
5	1	SPRING, 3.75L , 2.18 W
6	1	SUPPORT PEELER BAR MODIFIED
7	1	SUPPORT PHOTCELL MODIFIED
8	1	ROT. ARM CLAMP
9	1	FIBER SENSOR MOUNT
10	1	COVER
11	1	FIBER
12	1	FIBER
13	2	LET OFF CLAMP
14	2	ROLLER END 3"
15	1	DANCER ROLLER 3"
16	1	SHAFT DANCER ROLLER
17	1	PLATE, PEELER BAR MODIFIED
19	1	BRUSH HOLDER BRACKET
20	1	ROD, BRUSH HOLDER (2 HOLES)
21	1	SQUEEGEE 4 ½"W
22	1	SQUEEGEE CLAMP
23	1	SQUEEGEE MOUNT
24	1	NUT PLATE, SQUEEGEE MOUNT
25	1	SPRING, SQUEEGEE
26	1	ROD
27	1	UNIVERSAL MOUNT BLOCK LH



010 WIPE ON

Applicator on Labeling Head Serial #40-0335 (NO Printer)



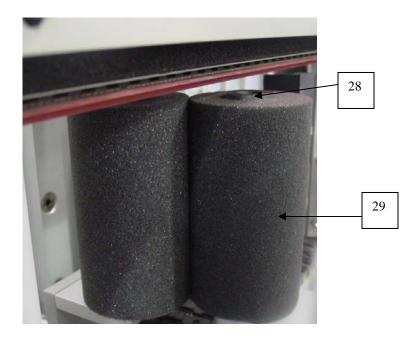


010 WIPE ON

ITEM	QTY	DESCRIPTION
1	1	PEELER BAR
2	1	MOUNT SPRING HOLDER
3	1	SPRING HOLDER
4	1	SPRING, 2.25L , 2.18 W
5	1	SPRING, 3.75L , 2.18 W
6	1	SUPPORT PEELER BAR MODIFIED
7	1	SUPPORT PHOTCELL MODIFIED
8	1	ROT. ARM CLAMP
9	1	FIBER SENSOR MOUNT
10	1	COVER
11	1	FIBER
12	1	FIBER
13	2	LET OFF CLAMP
14	2	ROLLER END "
15	1	DANCER ROLLER"
16	1	SHAFT DANCER ROLLER
17	1	PLATE, PEELER BAR MODIFIED
19	1	BRUSH HOLDER BRACKET
20	1	ROD, BRUSH HOLDER (2 HOLES)
21	1	SQUEEGEE 4 ½"W
22	1	SQUEEGEE CLAMP
23	1	SQUEEGEE MOUNT
24	1	NUT PLATE, SQUEEGEE MOUNT
25	1	SPRING, SQUEEGEE
26	1	ROD
27	1	UNIVERSAL MOUNT BLOCK LH

010 WIPE ON

After the labelers apply both labels to the product, rollers will wipe down, the product to ensure the labels are attached.



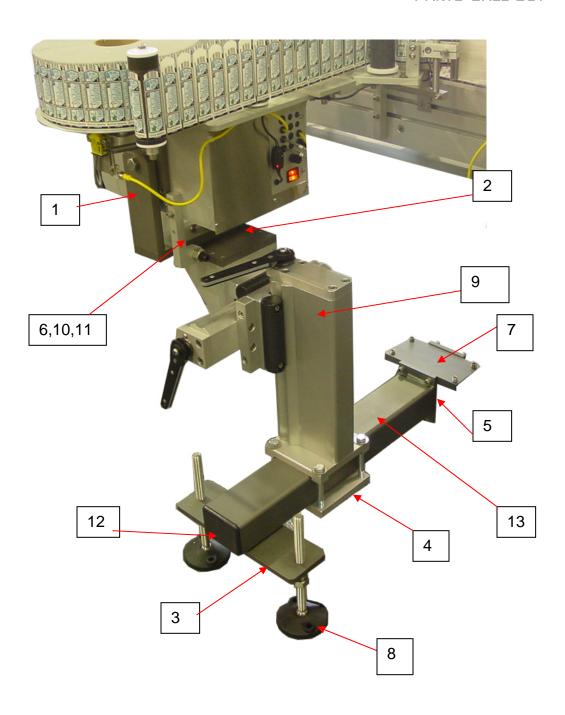
ITEM	QTY	DESCRIPTION
28	2	AXLE ROLLER
29	2	ROLLER

To ensure the labels are on properly and without error, the products will be inspected by the Vision System (see Section E).



SECTION D6: LABELER MOUNT

PARTS CALL OUT





SECTION D6: LABELER MOUNT

DESCRIPTION AND BILL OF MATERIALS

Item	Qty	DESCRIPTION
1	1	Yoke Assy. 41 Head, Short Arm
2	1	Yoke Mount Assy.
3	1	Caster & Leveling Pad Mount
4	1	Plate, Frame Support Spacer
5	2	Base Flange, 4" Wide
6	1	Skew Adjustment Bracket
7	1	Jack Plate
8	2	Leveling Pad
9	2	X-Y Table
10	1	Swivel Pad 5/8-11 X 3" Long
11	2	Block Skew Adjust
12	1	End Cap
13	1	Frame Weldment



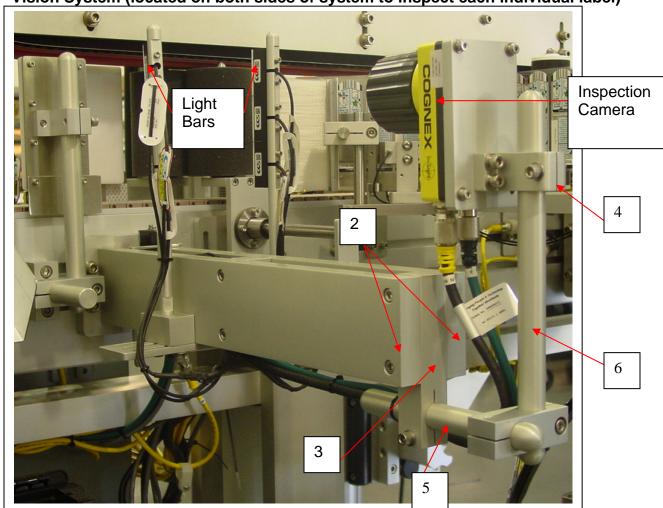
SECTION E: VISION SYSTEM

INSPECTION STATION

The Vision System Inspection Station examines each product to ensure the label is properly attached and the information on the label is clearly identifiable. The product travels down the conveyor to the product bin after passing through the Inspection Station.

In the event, the Vision System Inspection Station examines the product and the label is not properly attached and/or the information on the label is not clearly identifiable, the product will be removed from the conveyor by the Conveyor Rejection Station (Section G2).

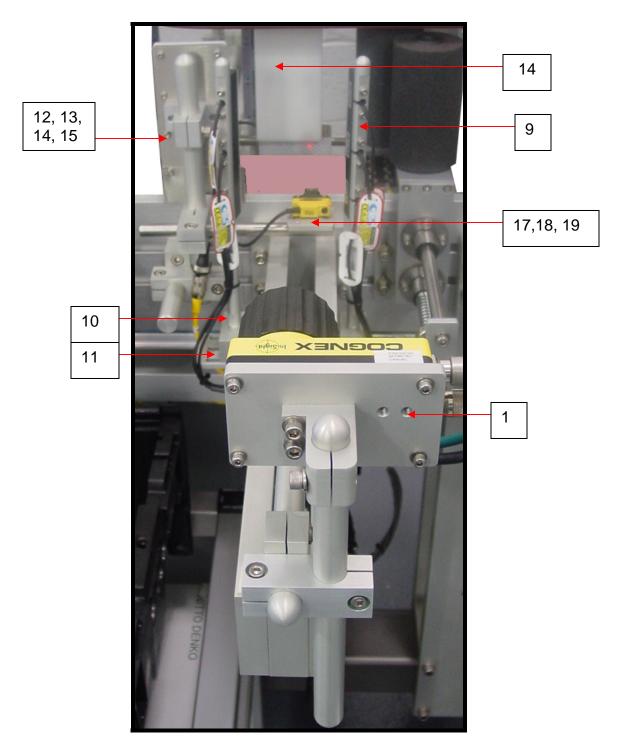
Vision System (located on both sides of system to inspect each individual label)





SECTION E: VISION SYSTEM

PARTS CALL OUT





SECTION E: VISION SYSTEM

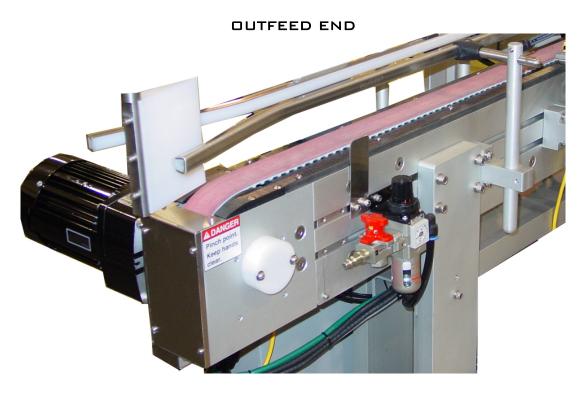
PARTS LIST

Number	Qty	Description
1	1	Mounting Plate, Vision Camera
2	2	Mounting Beam, Vision Camera
3	1	Mounting Plate, Camera Post
4	1	Mounting Bracket, Camera
5	1	Post, Horizontal - Camera
6	2	Post, Vertical - Camera
7	1	Spacer, Beam
8	1	Mounting Plate, Camera
9	2	Mounting Bracket, Light Bar
10	2	Mounting Post, Light Bar
11	1	Base Mount ¾" Shaft
12	1	Post, Horizontal – Reflector
13	1	Mounting Plate – Reflector
14		Reflector
15	2	Universal Mounting Block LH
16	1	Banner Mount
17	1	Sensor Mounting Rod
18	1	Sensor Mounting Bracket
19	1	Universal Mounting Block LH

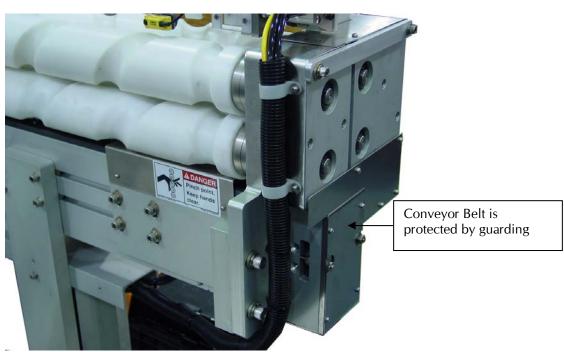


SECTION G1: CONVEYOR

PARTS CALL OUT (CONVEYOR)



INFEED END

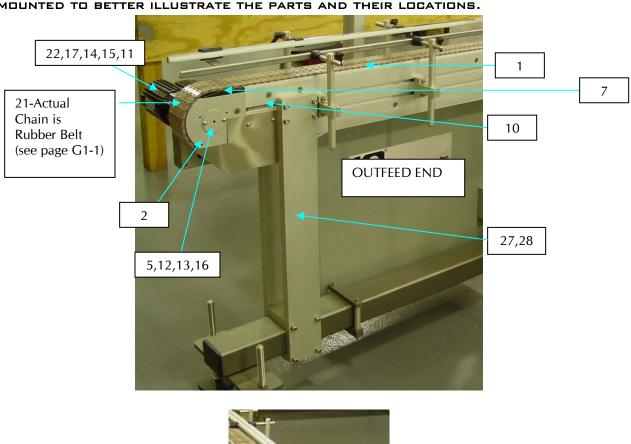


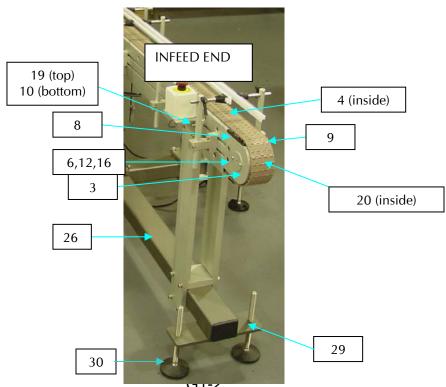


SECTION G1: CONVEYOR

PARTS CALL OUT (CONVEYOR)

THE PICTURES ARE SHOWN WITHOUT ANY SYSTEM ASSEMBLIES ATTACHED OR GUARDS MOUNTED TO BETTER ILLUSTRATE THE PARTS AND THEIR LOCATIONS.





SECTION G1: CONVEYOR

PARTS LIST CV30100

Number	Quantity	Description
1	2	Conveyor Plate
2	2	End Plate (outfeed)
3	2	End Plate (infeed)
4	11	Spacer, Conveyor
5	1	Drive Shaft
6	1	Idler Shaft
7	2	Strip, End
8	2	Strip, End
9	4	Clamp Plate (inside)
10	8	Nut Block
11	1	Key 1/8" THK X ¼" W
12	3	Bearing Cap
13	1	*Ball Bearing, .625 ID 1.575 OD
14	1	Motor, Junction Box
15	1	Collar Shaft
16	1	*Ball Bearing, .625 ID 1.5748OD
17	1	Gear Motor, 1/6 HP Invert. AC
18	18 FT	J-Leg Wear Strip
19	18 FT	Wear Strip
20	1	Sprocket
21	22 FT	Chain Rubber Belt
22	1	Motor, Spacer
23	1	End Cap
25	4	Nut Block
26	1	Tube Base
27	2	Support, 3" Wide Conveyor
28	2	Plate Frame Support Spacer
29	2	Caster and leveling pad mount
30	4	Leveling Pad



SECTION G2: CONVEYOR REJECTION SYSTEM

REJECTION IDENTIFICATION

The Conveyor Rejection System removes product from the conveyor if the product is mislabeled, not label or the label is rejected by the vision system.

Conveyor Rejection Station



Rejection mechanism

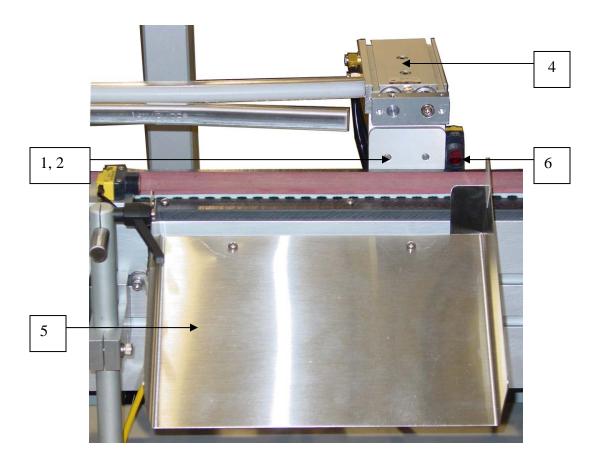
The reject mechanism shall consist of the following items.

- 1. One air slide cylinder to push the cases from the moving friction belt conveyor into a bin for rejected products.
- 2. Banner photoeyes to sense the rejected products.



SECTION G2: CONVEYOR REJECTION SYSTEM

REJECTION IDENTIFICATION

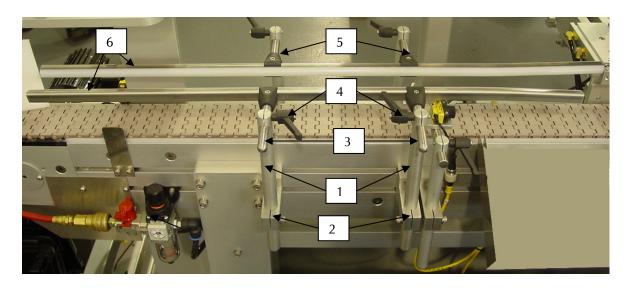


Number	Qty	Description
1	1	Mounting Plate, Reject
2	1	Mounting Bracket, Reject
3	1	Plate, Chute Support
4	1	Air Slide 20MM x 50mm
5	1	Chute
6	1	Retroreflective LSI std/QD PI



SECTION G3: PRODUCT GUIDES

PARTS CALL OUT (RAILS)



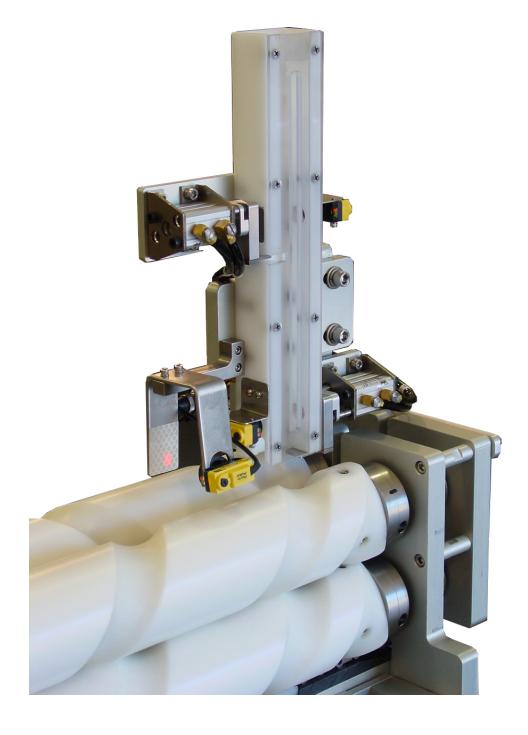
NOTE: CONVEYOR CHAIN MODIFIED (ACTUAL CONVEYOR CHAIN NOT SHOWN IN THIS PICTURE. SEE SECTION G1 FOR EXACT BELT.)

ITEM	QUANTITY	DESCRIPTION
1	5	UNIVERSAL PHOTO CELL MOUNTING
2	4	BANNER MOUNT 2 ½"L
3	4	GUIDE SUPPORT SHORT
4	4	HANDLE ADJ ¼-20 X .79
5	6	ROD END CONV RAIL HOLDER
6		GUIDE RAIL ROUNDTOP



SECTION H: ESCAPEMENT ASSEMBLY

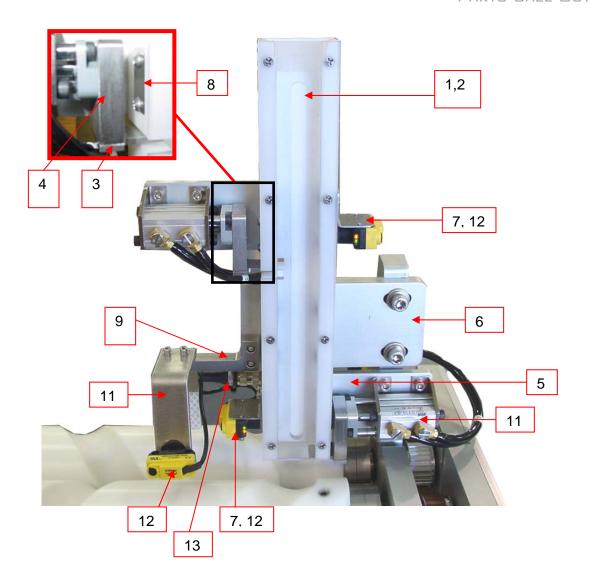
The Escapement Assembly is calculated to release one product at a time into the Timing Screw Assembly. This allows the proper spacing of products on the conveyor.





SECTION H: ESCAPEMENT ASSEMBLY

PARTS CALL OUT





SECTION H: ESCAPEMENT ASSEMBLY

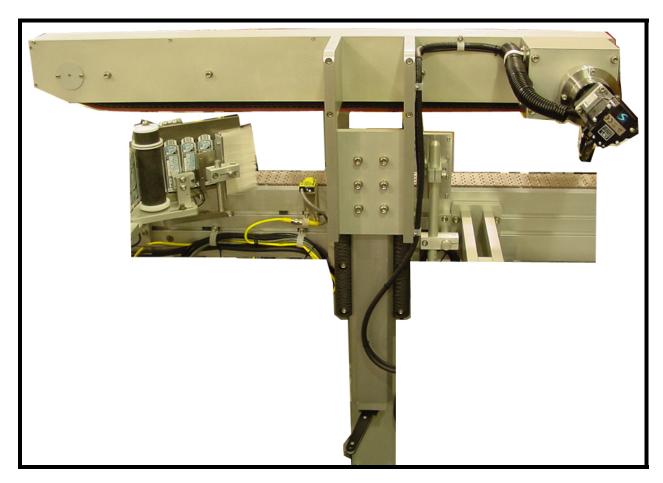
PARTS LIST

REF	QTY	DESCRIPTION
1	1	Chute, Escapement
2	1	Cover, Chute-Escapement
3	2	Finger, Product Stop
4	2	Mounting Bar, Finger
5	2	Mounting Plate, Air Cylinder
6	1	Mounting Plate, Escapement Chute
7	2	Mounting Angle, Sensor
8	2	Mounting Plate, Reflector
9	1	Mounting Bracket, Sensor
10	1	Mounting Bar, Sensor
11	2	Air Cylinder, 12mm Bore x 1/4"
12	3	Sensor, QS18, Retro, NPN
13	3	Disconnect Cable for 312



SECTION I: TOP HOLD DOWN

TOP HOLD DOWN BELT



Top Hold Down

The top hold down belt is used to prevent the product from moving out of position while the label is being applied. The product must be spaced and oriented prior to entering the top hold down belt. The belt provides sufficient downward pressure on the product to hold the product in position on the conveyor. A foam rubber backing material is incorporated into the top hold down belt design to compensate for slight variations in product height.

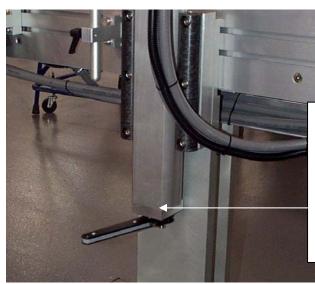
The top hold down belt is powered by an independent AC motor. The drive motor is electronically linked to the conveyor drive motor so that both the conveyor and top hold down belt run at the same rate. The top hold down belt stops and starts with the conveyor and does not have its own start / stop controls.

SECTION I: TOP HOLD DOWN

TOP HOLD DOWN ADJUSTMENT

ADJUSTMENT

The top hold down needs to be adjusted for each different product height. To set the belt height, turn the adjustment handle (located at the base of the top hold down mount). Start by raising the belt up higher than the product. Place the product approximately centered under the belt width and lower the assembly with the adjustment handle. Lower the belt until the <u>minimum</u> pressure required to hold the product is applied. Run the machine and verify that the product does not move from its position while being labeled. Readjust the belt height to change the pressure if necessary.



Adjustment Handle Raises and lowers top hold down belt.

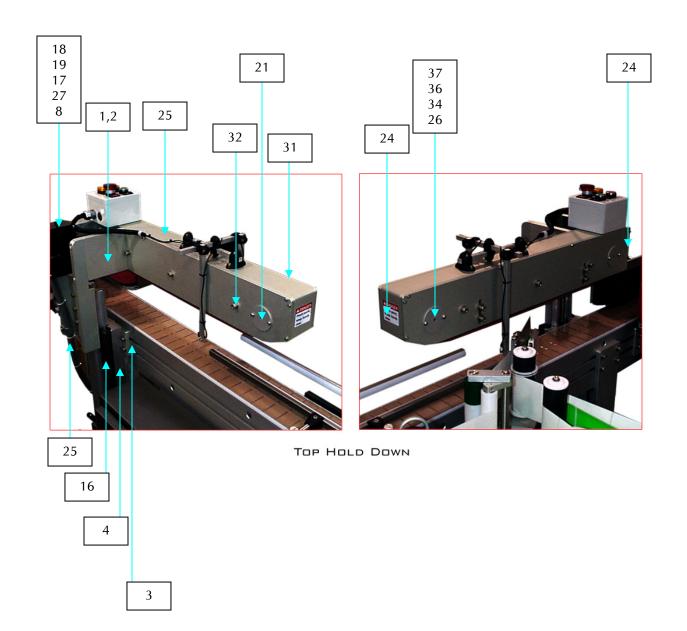
To set height:

- Place product under belt
 Lower Top Hold Down till
- the product fits snuggly,ie operator cannot easily pull product out from the fit.



SECTION I: TOP HOLD DOWN

TOP HOLD DOWN ADJUSTMENT



SECTION I: TOP HOLD DOWN

TOP HOLD DOWN PARTS LIST

REF	QTY	DESCRIPTION
1	2	Support 3"WideTHD
2	1	Mount Plate THD to Conv.
3	2	Nut Block 5/16 6-3/4 C.D.
4	1	Mount Plate THD
5	1	Leg THD Mounting
6	1	THD Support, 3" Wide Conveyor
7	2	Back Support THD
8	1	Spacer Plate Motor
9	1	Frame Support Spacer Plate, Motor
10	2	Plate, Frame Support Spacer
16		Column Horizontal Kit, 22-1/4 (1)
17	1	Motor, Junction Box, AC motor
18	1	Gear Head 30:1 Apex
19	1	Collar Shaft 1 ID
20	3	Spacer
21	1	Idler Shaft
22	2	Bracket Belt Support
23	1	Side Transfer Rear Cover Plate
24	1	Side Transfer Front Cover Plate
25	1	Side Transfer Top Cover Plate
26	1	Taper Lock Bushing Modification
27		Shaft Driver THD

SECTION I: TOP HOLD DOWN

TOP HOLD DOWN PARTS LIST

REF	QTY	DESCRIPTION
28	1	Belt Support
29	1	Foam Rubber Pad
31	1	Far Side THD
32	1	Near Side THD
33	1	Spring , Side Transfer
34	2	Bearing Cap Modified
36	2	Ball Bearing .625 ID 1.5748OD
37	1	Timing Pulley TL24H200



SECTION J: SENSOR

SENSOR SPECIFICATIONS



MOUNTING AND CONNECTING

1. The Banner sensor (QS18VN6FF50Q8), can be mounted on adjustable bracket and positioned to detect the leading or trailing edge of a product.

DIFFUSED BEAM SENSOR SM312D AND QS18VN6FF50

These type of sensors are the most commonly used. The sensor emits a light which reflects off of the product and is then detected by the sensor. The defused beam sensor does not require the use of a reflector. This sensor works well on light colored products where there is an unobstructed area behind the product. This sensor should not be used on dark colors or transparent products. The QS series is a 50 mm fixed field sensor.



SECTION J: SENSORS

SENSOR SPECIFICATIONS

SUPPLY VOLTAGE: 10 to 30V dc at less than 25mA (exclusive of load). 10% maximum ripple.

OUTPUT CONFIGURATION: One current sourcing (PNP) and one current sinking (NPN) open collector transistor.

PROTECTION: protected against false pulse on power-up, inductive load transients, power supply polarity reversal. Outputs are protected against continuous overload or short-circuit of outputs.

RESPONSE TIME: sensors will respond to either a "light" or a "dark" signal of 1 millisecond or longer duration, 500Hz max. (Note: 100 millisecond delay on power-up: outputs are non-conducting during this time.) Response time specification is independent of signal strength.

REPEATABILITY OF RESPONSE: 0.3 milliseconds, independent of signal strength.

LIGHT BEAM: visible red (650nm): for use with plastic fiber optics.

CONSTRUCTION: reinforced VALOX® housing, totally encapsulated, stainless steel screws. Meets NEMA standards 1, 2, 3, 3S, 4, 4X, 12, and 13.

CABLE: PVC-jacketed 4-wire cable (6' length) standard. Sensor model SM312FPQD with QD (Quick-Disconnect) connectors is also available; mating cable must be ordered separately.

ADJUSTMENTS: Light/Dark Operate select switch and 15-turn slotted brass screw Gain (sensitivity) adjustment potentiometer (clutched at both ends of travel). Both controls located on rear panel, and protected by a gasketed, clear acrylic cover.

INDICATOR LED: exclusive, patented Alignment Indicating Device system (AID™, US patent #4356393) lights a rear-panel mounted red LED indicator whenever the sensor sees a "light" condition, with a superimposed pulse rate proportional to the light signal strength (the stronger the signal, the faster the pulse rate).

OPERATING TEMPERATURE RANGE: -20 to +70 degrees C (-4 to +158 degrees F).



PRODUCT SENSOR

PRODUCT SENSING

The labeling head can use a variety of different sensors or methods for giving the machine a start signal. The most common method of giving a start signal is with the use of a photo-electric product sensor. Alternatives to using a photo-electric sensor can be using a PLC, relay, or a mechanical switch. Any of these methods are well suited to trigger the LSI labeler.

PHOTO-ELECTRIC SENSORS

Different types of sensors can be used to detect the product. The product size, shape, and color should all be taken into consideration when selecting a product sensor. Physical limitations for mounting the sensor must also be considered. Some of the sensors more frequently used are listed in the next several pages.

Mounting

The sensor should be positioned so it detects the product as it passes in front of the sensor. For many applications the sensor would be mounted over a conveyor. When the product passes in front of the sensor it is detected and a signal is sent to start the labeling cycle. The sensor is normally mounted on an adjustable bracket which allows the sensor to be moved in the direction of product flow. Moving the sensor in the direction of product flow will change the location of the label on the product.

DIFFUSED BEAM SENSOR SM312D

This type of sensor is the most commonly used. The sensor emits a light which reflects off of the product and is then detected by the sensor. The defused beam sensor does not require the use of a reflector. This sensor works well on light colored products where there is an unobstructed area behind the product. This sensor should not be used on dark colors or transparent products.

Sensor Specifications

SUPPLY VOLTAGE: 10 to 30V dc at less than 25mA (exclusive of load). 10% maximum ripple.



PRODUCT SENSOR

OUTPUT CONFIGURATION: One current sourcing (PNP) and one current sinking (NPN) open collector transistor.

PROTECTION: protected against false pulse on power-up, inductive load transients, power supply polarity reversal. Outputs are protected against continuos overload or short-circuit of outputs.

RESPONSE TIME: sensors will respond to either a "light" or a "dark" signal of 1 millisecond or longer duration, 500Hz max. (Note: 100 millisecond delay on power-up: outputs are non-conducting during this time.) Response time specification is independent of signal strength.

REPEATABILITY OF RESPONSE: 0.3 milliseconds, independent of signal strength.

LIGHT BEAM: visible red (650nm): for use with plastic fiber optics.

CONSTRUCTION: reinforced VALOX® housing, totally encapsulated, stainless steel screws. Meets NEMA standards 1, 2, 3, 3S, 4, 4X, 12, and 13.

CABLE: PVC-jacketed 4-wire cable (6' length) standard. Sensor model SM312FPQD with QD (Quick-Disconnect) connectors is also available; mating cable must be ordered separately.

ADJUSTMENTS: Light/Dark Operate select switch and 15-turn slotted brass screw Gain (sensitivity) adjustment potentiometer (clutched at both ends of travel). Both controls located on rear panel, and protected by a gasketed, clear acrylic cover.

INDICATOR LED: exclusive, patented Alignment Indicating Device system (AID™, US patent #4356393) lights a rear-panel mounted red LED indicator whenever the sensor sees a "light" condition, with a superimposed pulse rate proportional to the light signal strength (the stronger the signal, the faster the pulse rate).

OPERATING TEMPERATURE RANGE: -20 to +70 degrees C (-4 to +158 degrees F).

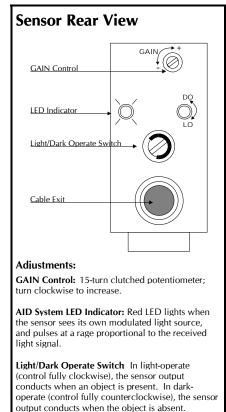


PRODUCT SENSOR

Installation and Alignment

Proper operation of the SM312D sensor requires that it be mounted securely and aligned properly. Excessive movement or vibration can result in intermittent or false operation caused by loss of alignment. For best results, final-mount the SM312D in an 18-mm hole by its threaded barrel or use one of the available mounting brackets.

- 1. Begin with the sensor at the desired distance from the object to be sensed, and at the approximate position where it will be mounted. The background should be as far behind the object as possible (at least three times the distance of the sensor from the object), and as dark a color as possible compared to the object. Ideally, the object should present its largest reflective surface to the sensor.
- 2. Apply power to the sensor, and advance the 15-turn Gain control to maximum (clockwise end of rotation). If the sensor is "seeing" its reflected light, the sensor alignment LED should be "on". Move the sensor up-down-right-left (include angular rotation) to obtain the fastest alignment LED pulse rate. If a pulse is not observable (too fast to count), reduce the Gain control (counterclockwise rotation) to obtain a countable pulse rate.
- 3. Repeat the alignment motions after each Gain reduction. When you have found the sensor orientation that produces the fastest pulse rate, mount the sensor solidly in that position. Increase the receiver Gain to maximum. Test the system by removing the object from the sensing position. The receiver LED indicator should go "off". If the LED indicator does not go "off", the sensor is reacting to light reflected from a background surface. Reduce the Gain setting until the alignment indicator goes "off", plus two additional full turns. Again place the object in the sensing position. If the alignment indicator does not come "on", the sensor is receiving as much or more light energy from the background as from the object. Consider the following alternatives:
 - Move the sensor closer to the object and reduce the sensitivity (Gain);
 - Reduce background reflectivity by painting the background with flat-black paint, or by scuffing the background or cutting a hole through it;
 - Tilt the sensor or the background so that the sensing beam is not perpendicular to the background.





PRODUCT SENSOR

RETRO-REFLECTIVE SENSOR SM312LV

This sensor is frequently used to detect products that are dark in color or in applications where the area behind the product is obstructed. This sensor requires the use of a reflector opposite of the sensor. The sensor emits a light which is reflected off of the reflector and detected by the receiver in the sensor. When the product passes through the beam of light it interrupts the signal being received by the sensor. It then gives a signal to fire the labeler.

Sensor Specifications

SUPPLY VOLTAGE: 10 to 30V dc at less than 25mA (exclusive of load). 10% maximum ripple.

OUTPUT CONFIGURATION: One current sourcing (PNP) and one current sinking (NPN) open collector transistor.

PROTECTION: protected against false pulse on power-up, inductive load transients, power supply polarity reversal. Outputs are protected against continuos overload or short-circuit of outputs.

RESPONSE TIME: sensors will respond to either a "light" or a "dark" signal of 1 millisecond or longer duration, (independent of signal strength), 500Hz max. (Note: 100 millisecond delay on power-up: outputs are non-conducting during this time

REPEATABILITY OF RESPONSE: 0.3 milliseconds, independent of signal strength.

LIGHT BEAM: visible red (650nm): model SM312LVAG has a polarizing lens filter.

CONSTRUCTION: reinforced VALOX® housing, totally encapsulated, o-ring sealing, acrylic lenses, stainless steel screws. Meets NEMA standards 1, 2, 3, 3S, 4, 4X, 12, and 13.

CABLE: PVC-jacketed 4-wire cable (6' length) standard. Sensor model SM312LVQD and SM312LVAGQD with QD (Quick-Disconnect) connector are available; mating cable is ordered separately.

ADJUSTMENTS: Light/Dark Operate select switch and 15-turn slotted brass screw Gain (sensitivity) adjustment potentiometer (clutched at both ends of travel). Both controls located on rear panel, and protected by a gasketed, clear acrylic cover.

INDICATOR LED: exclusive, patented Alignment Indicating Device system (AID™, US patent #4356393) lights a rear-panel mounted red LED indicator whenever the sensor sees a "light" condition, with a superimposed pulse rate proportional to the light signal strength (the stronger the signal, the faster the pulse rate).



PRODUCT SENSOR

OPERATING TEMPERATURE RANGE: -20 to +70 degrees C (-4 to +158 degrees F).



PRODUCT SENSOR

Installation and Alignment

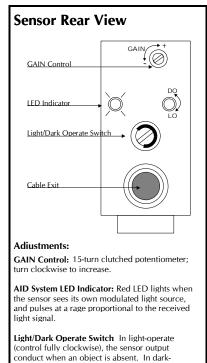
Proper operation of these sensors requires that they be mounted securely and aligned properly. Excessive movement or vibration can result in intermittent or false operation caused by loss of alignment. For best results, final-mount these sensors in an 18-mm hole by their threaded barrel or use one of the available mounting brackets.

- 1. Begin with the sensor at the desired distance from the retro target and at the approximate position where it will be mounted. An object at the sensing position should pass through the "core" of the sensor's light beam.
- 2. Apply power to the sensor, and advance the sensor's 15-turn Gain control to maximum (clockwise end of rotation). If the sensor is "seeing" the reflected light beam, the alignment LED should be "on". Move the sensor up-down-right-left to obtain the fastest receiver LED pulse rate. (Alternatively, the reflector may be moved.) If a pulse is not observable (too fast to count), reduce the Gain control (counterclockwise rotation) to obtain a countable pulse rate. (As an aid to alignment, it may be necessary to further reduce the strength of the light signal by tape-masking a portion of the retro reflective target area.)
- 3. Repeat the alignment motions after each Gain reduction. When you have found the sensor orientation that produces the fastest pulse rate, mount the sensor (or reflector) solidly in that position. Increase the receiver Coin

reflector) solidly in that position. Increase the receiver Gain to maximum. Test the system by placing the object to be detected into the sensing position. The indicator should go "off". If an "LV" model sensors indicator does not go "off" at this point, the sensor is reacting to light reflected from the object ("proxing").

If proxing occurs, reduce the Gain setting until the alignment indicator goes "off", plus two additional full turns. Remove the object from the sensing position and check that the alignment from the sensing position and check that the alignment indicator Led come "on" and pulses at a rate of at least two beats per second. Confirm that the Led goes "off" when the object is replaced.

It will help to mount the sensor so that it's light beam is not perpendicular to any flat reflective surfaces on the object (an angle of 10 to 15 degrees is usually sufficient). Also, at distances of a few feet or more, using more than one



operate (control fully counterclockwise), the sensor output conduct when the object is present.



PRODUCT SENSOR

reflector may increase sensing contrast between object-present and object-absent.



PRODUCT SENSOR

CONVERGENT BEAM SENSOR SM312CL

This sensor is used the least of all the sensors listed. This sensor is color sensitive and must be mounted at close range to the area being sensed, normally within one inch. It is very usefull in detecting large differences in contrast.

Sensor Specifications

SUPPLY VOLTAGE: 10 to 30V dc at less than 25mA (exclusive of load). 10% maximum ripple.

OUTPUT CONFIGURATION: One current sourcing (PNP) and one current sinking (NPN) open collector transistor.

OUTPUT RATING: 150mA maximum each output at 25°C, derated to 100mA at 70°C (derate≈1mA per°C). Output leakage current less than 1 microamp (off-state). Output saturation voltage (PNP output) less than 1 volt at 10mA and less than 2 volts at 150mA. Output saturation voltage (NPN output) less than 200 millivolts at 10mA and less than 1 volt at 150mA.

OUTPUT PROTECTION: protected against false pulse on power-up, inductive load transients, power supply polarity reversal. Outputs are protected against continuos overload or short-circuit of outputs.

RESPONSE TIME: sensors will respond to either a "light" or a "dark" signal of 1 millisecond or longer duration, (independent of signal strength), 500Hz max. (Note: 100 millisecond delay on power-up: outputs are non-conducting during this time. Response Time and Repeatability specifications are independent of signal strength.

REPEATABILITY OF RESPONSE: 0.3 milliseconds.

LIGHT BEAM: visible red (650nm); convergent beam.

SM312CV: spot size 0.05" diameter at 0.65" (16mm) focus point; SM312CV2: spot size 0.12" diameter at 1.7" (43mm) focus point.

CONSTRUCTION: reinforced VALOX® housing, totally encapsulated, o-ring sealing, acrylic lenses, stainless steel screws. Meets NEMA standards 1, 2, 3, 3S, 4, 4X, 12, and 13.

CABLE: PVC-jacketed 4-conductor cable (6' length) standard.

ADJUSTMENTS: Light/Dark Operate select switch and 15-turn slotted brass screw Gain (sensitivity) adjustment potentiometer (clutched at both ends of travel). Both controls located on rear panel, and protected by a gasketed, clear acrylic cover.



PRODUCT SENSOR

INDICATOR LED: exclusive, patented Alignment Indicating Device system (AID™, US patent #4356393) lights a rear-panel mounted red LED indicator whenever the sensor sees a "light" condition, with a superimposed pulse rate proportional to the light signal strength (the stronger the signal, the faster the pulse rate).

OPERATING TEMPERATURE RANGE: -20 to +70 degrees C (-4 to +158 degrees F).

Installation and Alignment

Proper operation of these sensors requires that they be mounted securely and aligned properly. Excessive movement or vibration can result in intermittent or false operation caused by loss of alignment. For best results, final-mount these sensors in an 18-mm hole by their threaded barrel or use one of the available mounting brackets.

Begin with the sensor at the approximate position where it will be mounted. With power applied to the sensor, direct its visible red spot at the object approximately 0.65" (for model SM312CV) or 1.7" (for model SM312CV2) directly in front of the lens. Move the sensor very slightly toward or away from the object while observing the red "AID" indicator on the back of the sensor. Maximum reflected light and optimum sensor alignment to the object are indicated by the fastest Led pulse rate obtainable with Gain control set at the lowest setting required to light obtainable with the Gain control set at the lowest setting required to light the Led. This should occur at the same time that the red sensing spot on the object appears most sharply defined. Mount the sensor at this position and distance.



PRODUCT SENSOR

Reliable convergent sensing requires that the sensor-to-object distance be held relatively constant. This may be a critical factor, especially when highly reflective background objects are present, or when the background is close to the object. Best results will be attained under the following conditions: constant sensing distance from one object to the next, a background of low reflectivity, and the background as far from the object as possible.

FIBER-OPTIC

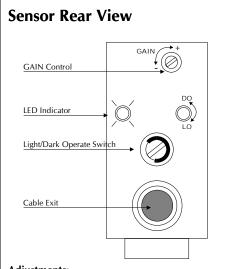
Most of the sensors listed in this section are available in a fiber-optic version. The sensors will operate in the same manner as described earlier in this section. The difference is the emitter and receiver are mounted to the end of a fiber-optic cable(s). This type of scanner is used when the standard unit is too large to mount in a restrictive area.

MECHANICAL SWITCH INTERFACE

In certain applications it may be necessary to use a

in the fixture it will trip the switch and trigger the machine.

darker of the two colors is sensed. mechanical switch to trigger the labeling head. This is very useful in semi-automatic applications. A switch can be mounted in a fixture which holds the product. When the product is placed



Adjustments:

GAIN Control: 15-turn clutched potentiometer; turn clockwise to increase.

LED Indicator: Red LED lights when the sensor sees its own reflected light from an object, and pulses at a rate proportional to the received light signal.

Light/Dark Operate Switch: In light-operate (control fully clockwise), the sensor outputs conduct when an object is present. In dark-operate (control fully counterclockwise), the sensor outputs conduct when the object is absentor when the



ELECTRICAL ENCLOSURE

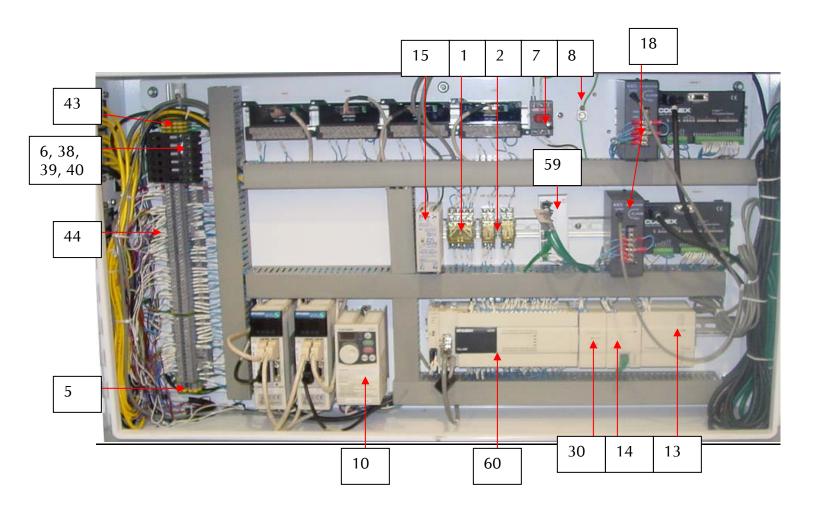
Door Enclosure





SYSTEM SPECIFICATIONS

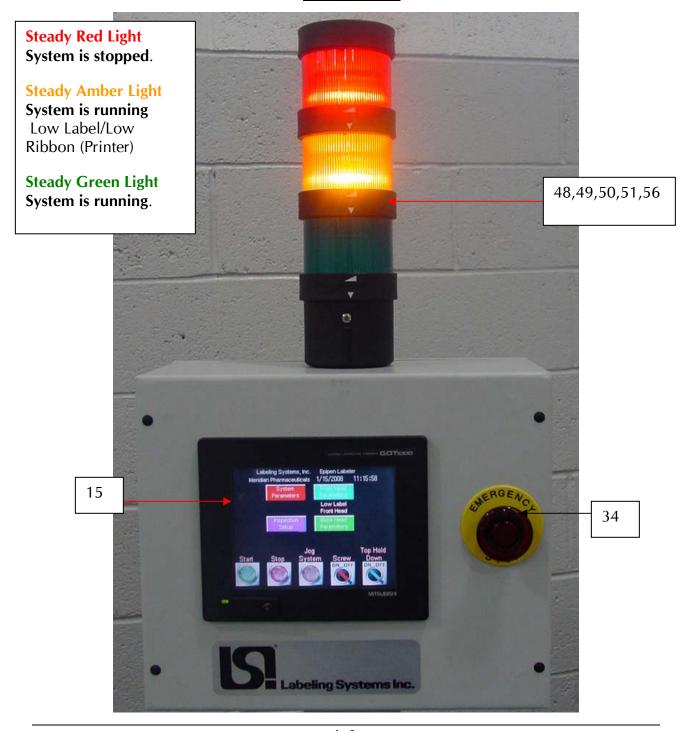
Main Control Panel (Inside)





SYSTEM SPECIFICATIONS

Alarm Tower





SYSTEM SPECIFICATIONS

E-Stop 34

E-Stop located on Control Box and on Top Hold Down Assembly.



Ref	QTY	Description
1	1	RELAY, 4PDT, 24V
2	1	RELAY SOCKET 4PDT
3	1	MAIN DISCONNECT BASE
4	1	MAIN DISCONNECT HANDLE
5	1	END SECTION
6	5	FUSEHOLDER
7	1	SHAFT, MAIN DISCONNECT 10"
8	1	GROUND LUG, PANEL MOUNT
9	5	TERMINAL BLOCKS (GROUND)
10	2	DRIVE, AC INVERTER, S500. 5HP
11	2	END SECTION
12	3	END STOP
13	1	CCLINK MASTER
14	1	CCLINK SLAVE
15	1	OPERATOR INTERFACE, GOT SERIES
16	1	OPERATING CABLE, 10M, GT to FX
17	2	MOTOR CONTROLLER, SERVO, J2
18	2	MOTOR SERVO 200 WATT W/ENCODE
19	2	MOTOR CONTROLLER, POWER CABLE
20	2	MOTOR CONTROLLER, CABLE ACCY
21	4	MOTOR CONTROLLER, TRM BLK



Ref	QTY	Description
22	1	POWER SUPPLY, +24 VDC, 60 WATTS
23	4	MOTOR CONTROLLER, CABLE ACCY
24	1	ENCLOSURE 24" x 42" x 8"
25	1	PANEL FOR ENCLOSURE 24" x 42"
26	1	CONSOLE BOX MODIFICATION
27	1	WALL FLANGE/BASE BRACKET
28	1	FLANGE COUPLING
29	2	PENDANT ARM TUBE 19"
30	1	EXPANSION MODULE 8 OUTS
31	4	ENTRY SYSTEM, CABLE GLAND
32	2	15 AMP, 115 VAC DUPLEX RECEP
33	1	QUAD BOX OUTLET
34	2	E STOP YELLOW NAMEPLATE
35	3	CONNECTOR, FEMAL FREE HANGING
36	3	CONNECTOR, PLUG CIRCULAR
37	6	CABLE CLAMP, STRAIN RELIEF
38	1	FUSE, 2-AMP 3AG FAST ACTING
39	4	FUSE, 5 AMP, LITTLEFUSE
40	1	FUSE 15 AMP, LITTLEFUSE



Ref	QTY	Description
41	1	RELAY, SOLID STATE DC-DC PIN
42	1	TERM BLOCK JUMPER
43	2	END SECTION
44	56	TERMINAL BLOCKS
45	1	COVER, MICROSWITCH
46	1	MICRO-ROLLER, MICROSWITCH
47	1	CONNECTOR, PLUG, 2P, 3W
48	1	BASE UNIT LITE STACK XBV SERIES
49	1	ALARM GREEN STEADY
50	1	ALARM RED STEADY
51	1	ALARM ORANGE STEADY
52	2	CONNECTOR, FEMALE, 9-PIN
53	1	CONNECTOR 9-PIN D-SUB
54	1	RELAY SOCKET DPDT
55	2	RELAY DPDT+24 VDC
56	3	LAMP (24V, 6.5W) ALARM
57	1	SERVO CABLE 5M ENCODER CABLE
58	1	SERVO CABLE CBL 5M, J2S
59	1	5 PORT ENET SWITCH, 24VDC



Ref	QTY	Description
60	1	ETHERNET MODULE FOR FX3U
61	1	PLC, FX3U, 16 DC IN
62	1	RS485 MODULE FOR FX3U



SECTION M: MACHINE SPARE PARTS IDENTIFICATION

SPARE PARTS LIST

	Section D-Labeler(s) Section				
Qty	Part Number	Description			
1	ETAFUSE602002	6.25 AMP Fuse			
1	ELMSCACC0064	Fuse Holder 3 AG			
1	ELPWRL024017	Power Supply, 24VDC			
1	ELPLCHMI0014	Operator Interface GOT Series			
1	ELPLCCMP0038	PLC Fixed I/O Control			
1	ELOPTOB00008	Amplifier Sensor (Auto Teach)			
1	ELSWTRCN0001	Rocker Switch			
1	9609-1061	Pressure Spring Label Sensor			
1	ELOPTAF00004	Fiber plastic 46UHFM			
1	ELOPTAF00002	Fiber Plastic Pit 66U			
	Unwind - Rewind Drive Subassembly				
1	10-1191-1010 A	Rewind Felt Disc			
1	9609-2040	Pulley Rewind 1.17 pd			
1	50-1304	Pulley 3mm			
1	50-2044	Pulley 28 T			
1	PTTB072M150	Timing belt			
1	PTRB3044K141	Round Belt 3/16 diameter			
1	MHES05004502	Unwind Spring			
1	1000-1128 A	Brake Band			
1	ELMOTCST013	Drive Stepper Motor			
1	095-1002	Candy Cane for rewind			
1	MHCS08508500	Spring compression .845 x .081 x ¾			
2	PTBB06213700	Ball Bearing 5/8 ID x 3/8 OD			
2	ELOPTCS11	Convergent beam sensor			



SECTION M: MACHINE SPARE PARTS IDENTIFICATION

SPARE PARTS LIST

Section D2-Applicator				
2	40-0334-2002	Brush Holder Bracket		
2	40-0334-2004	Brush Holder Rod		
2	40-0334-2005	Squeegee 4 ½" W		
2	40-0334-2006	Squeegee Clamp 4 ½" W		
2	40-0334-2008	Squeegee Spring 4 1/2" W		
2	14-0554-5001	Roller Axle		
2	14-0554-5005	Roller		
1	PNASSYMAC09	Manifold		
	Sec	tion L- Systems Controls		
2	ELMOTCAC0014	Drive, Ac Inverter, S500, 0.5 Hp		
5	ELTRMFUS0002	Fuseholder		
1	ETFUSE152002	15 Amp Fuse		
4	EFTUSE502002	5 Amp Fuse		
1	EFTUSE202002	2 Amp Fuse		
2	ELSWTRPL0010	E-Stop Illuminated Switch Push/Pull		
1	ELSWTALM0031	Alarm Green, Steady 24VDC XVB		
1	ELSWTALM0034	Alarm Red, Steady 24VDC XVB		
1	ELSWTALM0035	Alarm Orange, Steady 24VDC XVB		
1	ELRLY4FDC001	Relay, 4PDT, 24V		
1	ELRLTSKT0001	Relay Socket 4PDT		



SECTION M: MACHINE SPARE PARTS IDENTIFICATION

SPARE PARTS LIST

Section G1-Conveyor and Base Frame Assembly				
8	MHLM37314	Leveling Pad		
1	PTBB06215700	Ball Bearing		
22	14-0554-0080	Rubber Conveyor Belt		
1	PTGMINV02226	1/6HP Gearmotor		
	Section G2	-Conveyor Rejection Assembly		
1	PNALCXSM2050	Air Slide 20mm x 50mm		
	Section	n H-Escapement Assembly		
1	PNALR12002500	Air Cylinder 12mm B x 1		
	Se	ection I-Top Hold Down		
1	PTRS101020	Gear Head Apex 30:1		
1	14-0554-3002	Belt (timing - Multi Layer)		
	PTBB06215700	Ball Bearing .625 ID 1.5748 OD		
	Section J- Sensors			
3	ELOPTCS11	Convergent Beam Sensor 312CVQD		
2	ELOPTDS10	Sensor QS18VN6FF50Q8		
3	ELOPTRB12	Sensor QS18 Retro, NPN		
	Section P- Diverter Assembly			
1	PNALR25007500	Air Cylinder 25mm Bore		
	Section R- Timing Screw Assembly			
1	PTCLTGC6	Clutch, Torq/Gard		
1	PTRS10120	Gear Head Apex 30:1		
1	PTTB16T50750	Timing Belt 16mmW, T5mmP		



TROUBLE SHOOTING

TROUBLE SHOOTING

PROBLEM	PROBABLE CAUSE SOLUTION	
No Power		
	 Machine not plugged in No main power Fuse #1 blown Main Power Switch failure Internal wiring faulty or incorrect Faulty input power 	Correct Correct Replace Fuse Replace Switch Repair Correct
Motor Fuse Blown		
	 Defective or incorrect fuse Bind or jam-up in motor, drive chain or web path Electrical short Motor defective 	Replace with proper fuse Correct binding Inspect & correct Replace
No Function Auxiliary		
	 fuse blown Aux component not connected Defective Aux control component Defective switch Defective or broken wires 	Replace Connect Replace Replace Inspect & repair
No Label Feed- see Pr	inter OEM manual	
	 Motor not working Failed product sensor Nip roller disengaged 	Check motor and wiring Replace sensor Release nip lift
Continuous Label Fee	d – see Printer OEM manual	
Continuous Label Fee	d – see Printer OEM manual 1. Defective jog switch	Replace
Erratic Label Feed	 Nip roller not engaged Label unwind brake not installed properly Adhesive built up on peeler bar Variation in motor speed Threaded around air assist tube 	Release nip lift Re-adjust Clean Check motor Correct threading



TROUBLE SHOOTING

PROBLEM	PROBABLE CAUSE	SOLUTION
Web Breaks		
	1. Label die cut through liner partially or completely	Replace
	2. Improper threading	Check threading
	3. Web guide collar too tight or misaligned	Re-adjust
	4. Worn peeler blade	Inspect & replace
	5. Dancer arm tension too high	Reset
Rewind Does Not Wor	k	
	1. Felt disc worn out	Replace
	2. Rewind clutch adjusted too loose	Re-adjust



CLEANING AND MAINTENANCE

CLEANING

To maintain proper operation, your labeler must be kept clean from label and adhesive build-up. During normal operation, the adhesive in the labels may transfer and build-up on the labeler. A mild solvent such as alcohol should be used to remove the adhesive. Labels should be removed, first by tearing off the label material, and then by removing the adhesive with a solvent. When removing adhesive build-up, special attention should be given to the pinch roller, peeler bar, drive roller, photocell spring steel, and any other part that comes in direct contact with the web. If the adhesive build-up is allowed to accumulate, it will affect labeling accuracy and may cause damage to the machine.

NOTE: Never use a razor or any other sharp instrument to remove labels from a roller. Doing this will damage to the roller.

To clean the machine, we recommend a mild solvent such as alcohol. If a solvent other than alcohol is used, it should not have an oil base and should dry quickly without leaving any residue. If the solvent is too strong, it may damage the finish of the machine or deteriorate the rollers.

MAINTENANCE

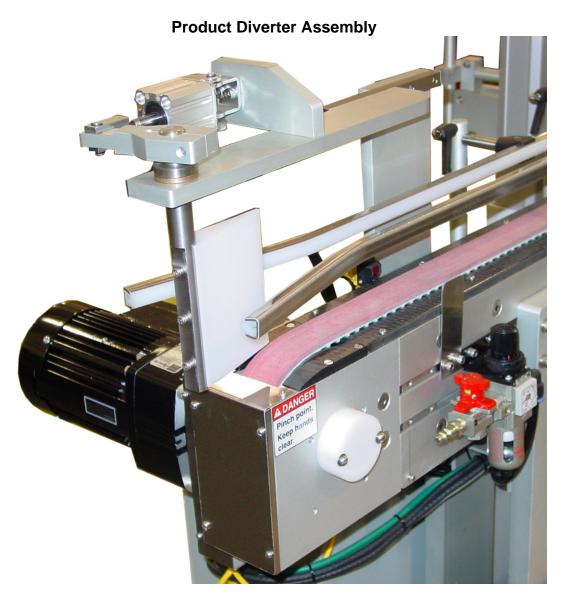
LSI builds machines to require a minimum amount of maintenance. If the regular maintenance is performed, the machine will last for years. However, if maintenance is ignored, it may shorten the life of the machine. The following is a list of the required maintenance required to keep your machine in top operating condition.

- 1. Keep machine clean from foreign matter, label and adhesive build-up.
- 2. Periodically check and retighten any screws that may have vibrated loose.
- 3. Replace any worn or damaged parts with the correct factory replacement. Incorrect or makeshift parts may affect the proper operation of the machine.
- 4. The machine requires no further lubrication. All chains are operated dry to prevent oil from slinging onto electronic components.
- 5. Check for wear, and replace if necessary, the unwind brake belt and the rewind disc.
- 6. Check and adjust if necessary any chains or belts installed on the machine.



SECTION P: PRODUCT DIVERTER

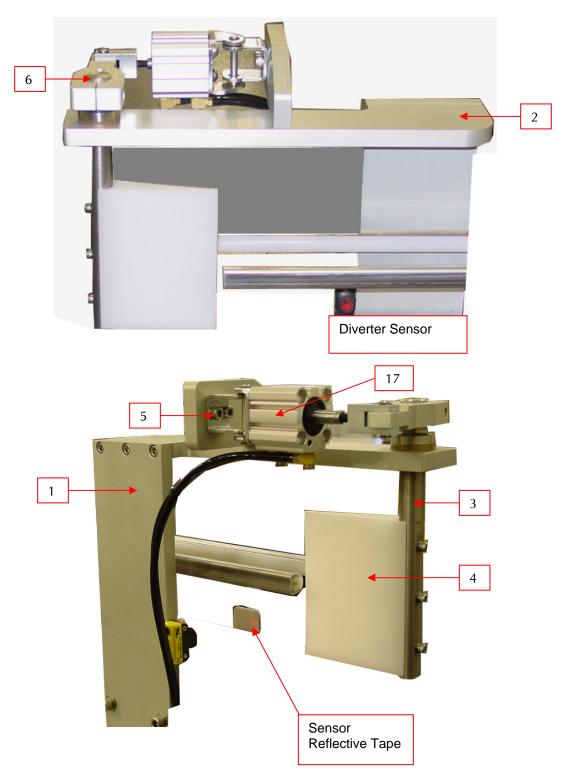
The Product Diverter redirects the product from the conveyor into the outfeed bin. Each bin will have a maximum number of products allowed. A sensor will keep count of the allotment. Once the allotment is reached, the sensor will signal the Product diverter to reposition and continue dispensing the product into the next outfeed bin. This is done without stopping the conveyor. An operator needs to remove the full outfeed bin and replace it with an empty otufeed bin at the end of the conveyor.





SECTION: PRODUCT DIVERTER

PARTS CALL OUT



SECTION: PRODUCT DIVERTER

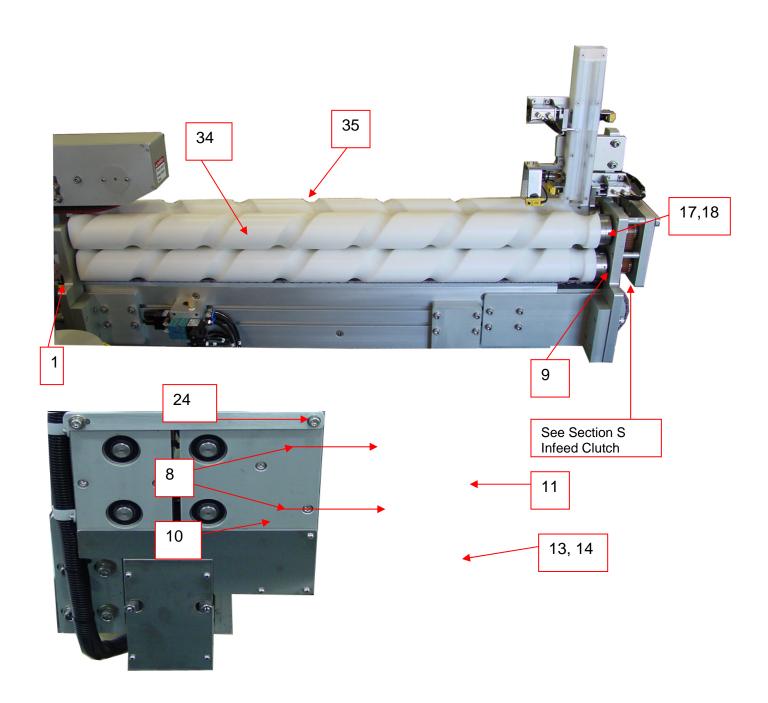
PARTS CALL OUT

REF	QTY	DESCRIPTION
1	1	Mounting Plate, Horizontal
2	1	Mounting Plate, Vertical
3	1	Post, Pivot – Diverter
4	1	Diverter
5	1	Mount, Air Cylinder
6	1	Lever, Diverter
8	1	Mounting Bar, Lower
9	1	Mounting Bar, Upper
10	1	Mounting Bar, Vertical
11	1	Rod, Vertical
12	1	Rod, Horizontal
13	1	Base Mount ¾" Shaft
14	1	Banner Mount 2"L, Vertical
15	1	Universal Mounting Block, LH
16	1	Bushing Flange ¾ x 1 x ¾
17	1	Air Cylinder, 25mm Bore x 3/4"
18	1	Frame by 8020 (Double Box)



SECTION R: TIMING SCREW ASSEMBLY

The Timing Screw Assembly is designed in order for the proper spacing and balance of the product on the conveyor. The product is released into the Timing Screw Assembly (via the Escapement Assembly) where it is carried down the conveyor.





SECTION R: TIMING SCREW ASSEMBLY

REF	QTY	DESCRIPTION
1	1	Mounting Plate, Front Timing Screw
2	2	Adjusting Plate, Front
3	1	Arm, Mounting – Front
4	4	Shaft Drive
5	4	Pulley, Altered -24T
6	1	Arm Mounting, Front
7	1	Mounting Plate
8	4	Shaft, Idler
9	1	Mounting Plate - Rear
10	1	Arm, Mounting - Rear
11	1	Mounting Bracket, Motor
12	1	Pulley, Idler – Altered 24T
13	1	Shaft, Idler
14	1	Shaft, Motor
15	1	Plate, Clutch Adapter
16	1	Pulley, Drive – Altered 24T
17	8	Collar, Timing Screw
18	8	Collar Clamp, Timing Screw
19	1	Arm, Mounting – Rear
20	1	Bearing Support Plate, Front



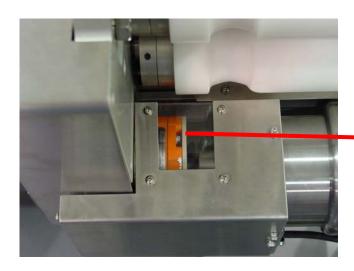
SECTION R: TIMING SCREW ASSEMBLY

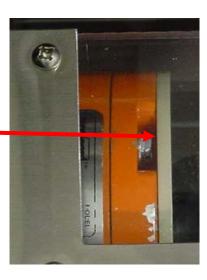
REF	QTY	DESCRIPTION
21	6	Stand-Off, Bearing Plate
22	1	Spacer Ring
23	1	Bearing Support Plate – Rear
24	1	Strap, Plate
25	1	Collar Modified w. Timing Mar
26	1	Shaft, Idler (Timing Shaft)
27	2	Retaining Ring, ½ ID SS
28	8	Retaining Ring, 5/8 ID SS
29	3	Ball Bearing .500 ID 1.125 OD
30	12	Ball Bearing .5/8 ID 1 3/8 OD
31	1	Timing Belt 16mm , T5mmP
32	1	Clutch, Torq/Gard #TGC6
33	1	Motor, Servo 200 Watt W/Encoder
34	2	Timing Screw LH -42"LG, 6"P
35	2	Timing Screw RH -42"LG, 6"P
36	1	Key, Motor Shaft
37	1	Collar Shaft 1-1/2" ID
38	1	Gearhead, 30:1 Apex

SECTION S: INFEED CLUTCH

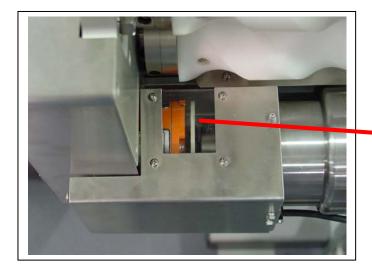
SERVICE OVERLOAD CLUTCH

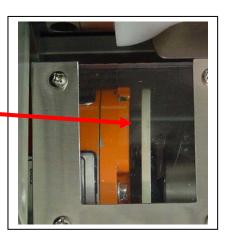
This infeed screw assembly is equipped with a "kick-out" system which has a clutch. The clutch is located by the timing screw drive on the FRONT head side of the conveyor. During normal operation the clutch will be in the "ENGAGED" position as shown below through the vision window provided.





In the event of a product jam, human error, or some other cause that prevents the Timing Screw from rotating, the clutch will automatically disengage. When the clutch disengages three things will happen. They are: the machine will shutdown, a red warning beacon light will illuminate, and "Timing Screw Clutch Disengaged" is shown on the HMI.



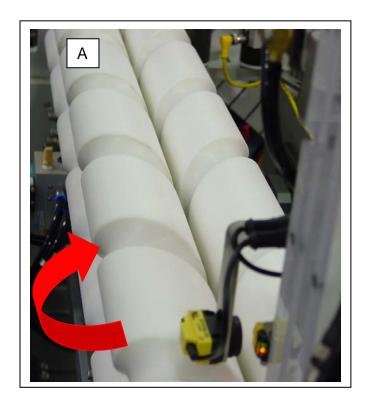




SECTION S: INFEED CLUTCH

RESETTING THE CLUTCH

To reset the clutch:

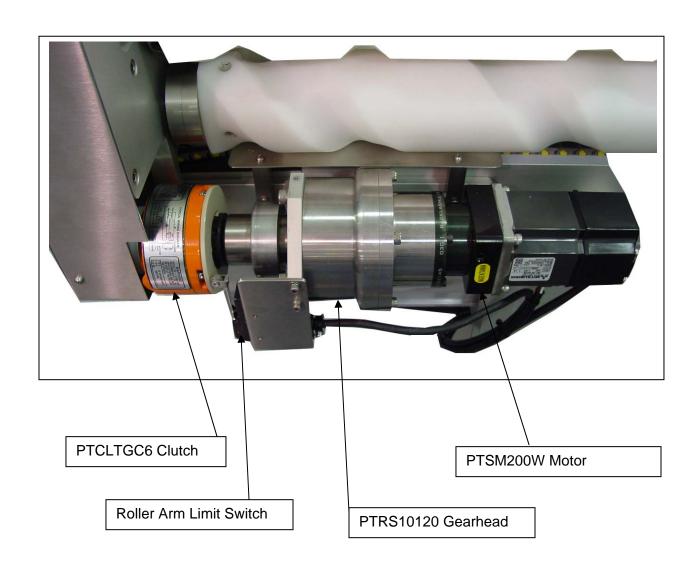


Operator is to stand on the clutch side of the conveyor. Using two hands grab timing screw "A". With a jerking motion turn screw towards self till the clutch reseats. NOTE: This may take up to three times before the clutch firmly seats itself.



SECTION S: INFEED CLUTCH

PARTS ASSEMBLY





Appendix A Ladder Logic

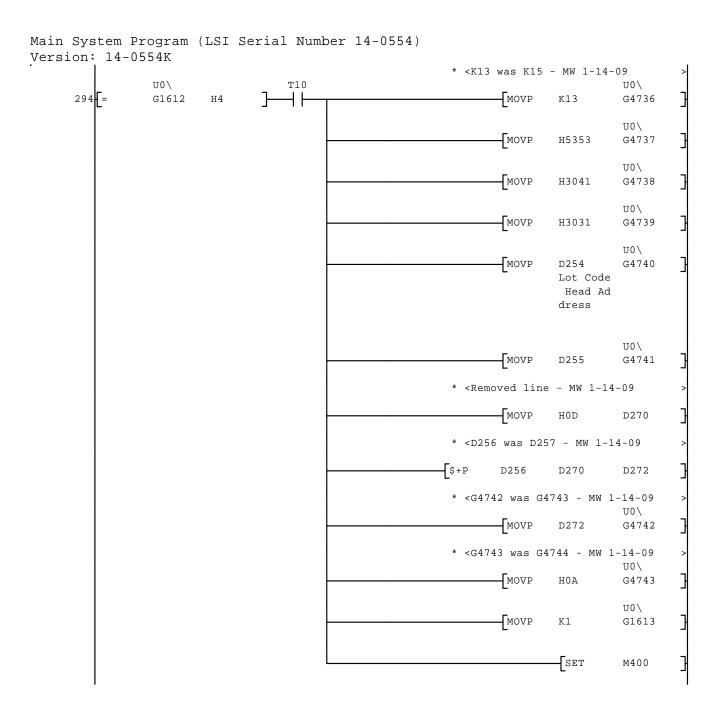
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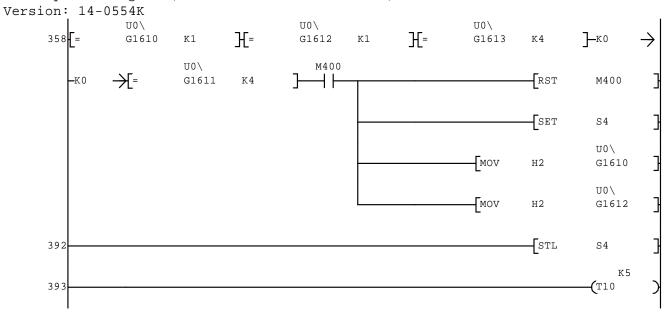
Main System Program (LSI Serial Number 14-0554) Version: 14-0554K EI. * Start of Ethernet Comms to Cognex M8002 SET S0 first sc an STL S0 X023 RST \dashv \vdash M499 c1 not o send dat nline X040 c2 not o nline * open ports to both cameras X040 M499 UO\ MOVP К1 G1602 c1 not o c2 not o send dat nline nline UO\ MOVP К1 G1604 UO\ UO\ UO\ 21 = \mathcal{H} = \mathcal{H} **]**_K0 G1602 G1604 G1612 Н5 Н5 Κ1 UO/ -= SET G1610 **-**K0 К1 S1 UO\ Mov Н2 G1610 UO\ MOV Н2 G1612 -[STL 53 S1 К5 **(**T10 54

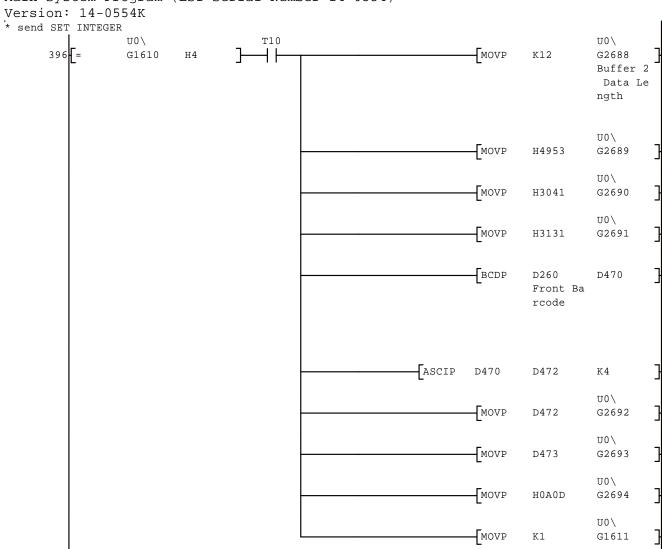
Version: 14-0554K . \star login to cameras with user "a" CR+LF UO\ UO\ T10 UO\ Н= 57**F**= G1612 Н4 G1610 Н4 **}**—| |-MOVP К3 G2688 Buffer 2 Data Le ngth UO\ MOVP H0D61 G2689 UO\ MOVP G2690 H0A UO\ MOVP К1 G1611 UO\ MOVP К3 G4736 UO\ MOVP H0D61 G4737 UO\ MOVP HOA G4738 UO\ MOVP К1 G1613 SET M400 UO\ UO\ U0\ Н= \mathcal{H} = 109 = G1610 G1612 К1 G1613 **]**_K0 \rightarrow К1 K4 UO/ M400 -= RST **-**K0 G1611 К4 **}**—--| |-M400 RST T10 SET S2 UO\ MOV G1610 Н2 UO\ MOV Н2 G1612 STL 145 S2 К5 **(**T10 146

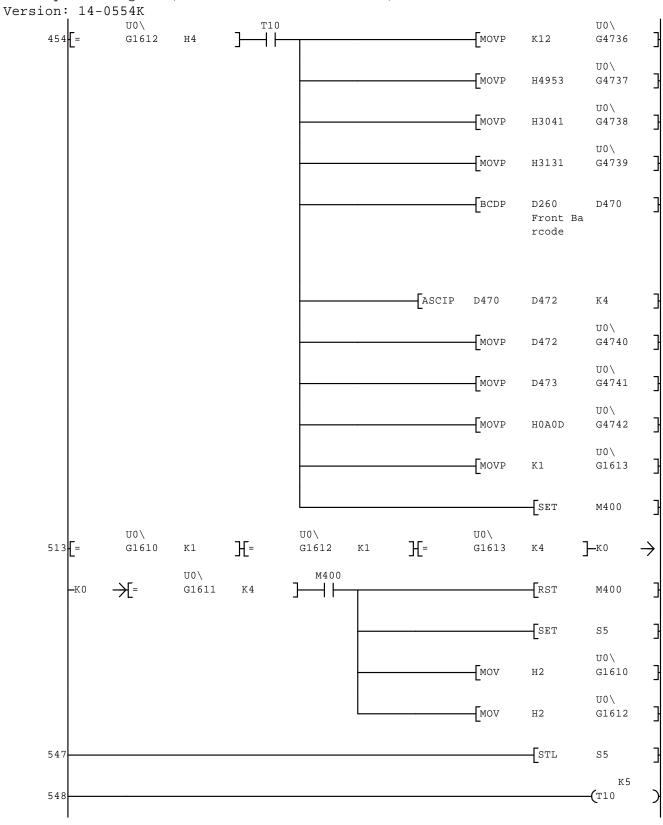
Version: 14-0554K * enter blank password into cameras CR+LF UO/ UO\ T10 UO\ Н= **}**— 149 = G1610 Н4 G1612 Н4 MOVP Κ2 G2688 Buffer 2 Data Le ngth UO\ MOVP H0A0D G2689 UO\ MOVP G1611 К1 UO\ MOVP G4736 Κ2 UO\ MOVP H0A0D G4737 UO\ MOVP К1 G1613 SET M400 UO\ UO/ UO/ Н= Н= 191 = G1612 G1613 **]**—K0 \rightarrow G1610 К1 Κ4 UO\ M400 -[= **-**K0 RST G1611 Κ4 M400 RST T10 SET S3 UO\ MOV Н2 G1610 UO\ MOV Н2 G1612 STL 227 S3 К5 228 **(**T10

Main System Program (LSI Serial Number 14-0554) . Version: 14-0554K * send SET STRING command to both cameras * <K13 was K15 - MW 1-14-09 UO\ T10 UO\ 231 = MOVP G1610 Н4 K13 G2688 Buffer 2 Data Le ngth UO\ MOVP H5353 G2689 U0\ MOVP H3041 G2690 UO\ MOVP H3031 G2691 UO/ MOVP D254 G2692 Lot Code Head Ad dress UO\ MOVP D255 G2693 * <Removed line - MW 1-14-09-MOVP H0D D270 * <D256 was D257 - MW 1-14-09 \$+P D256 D270 D272 * <G2694 was G2695 - MW 1-14-09 UO\ MOVP D272 G2694 * <G2695 was G2696 - MW 1-14-09 UO\ MOVP H0A G2695 UO\ MOVP G1611 К1

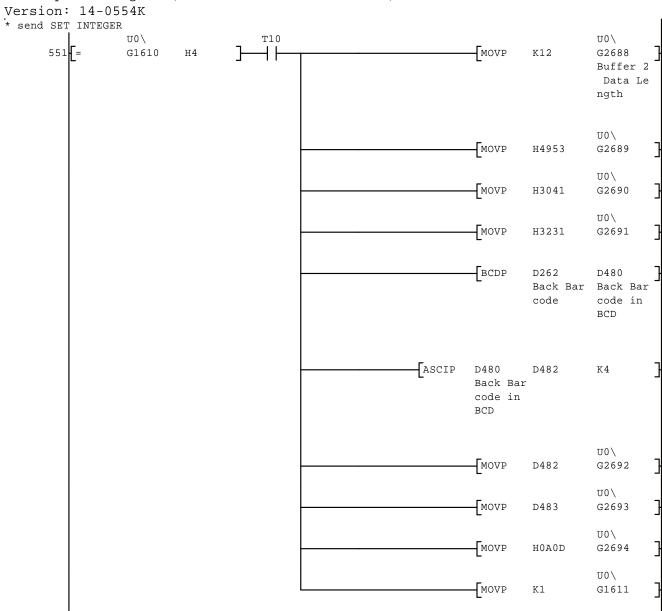


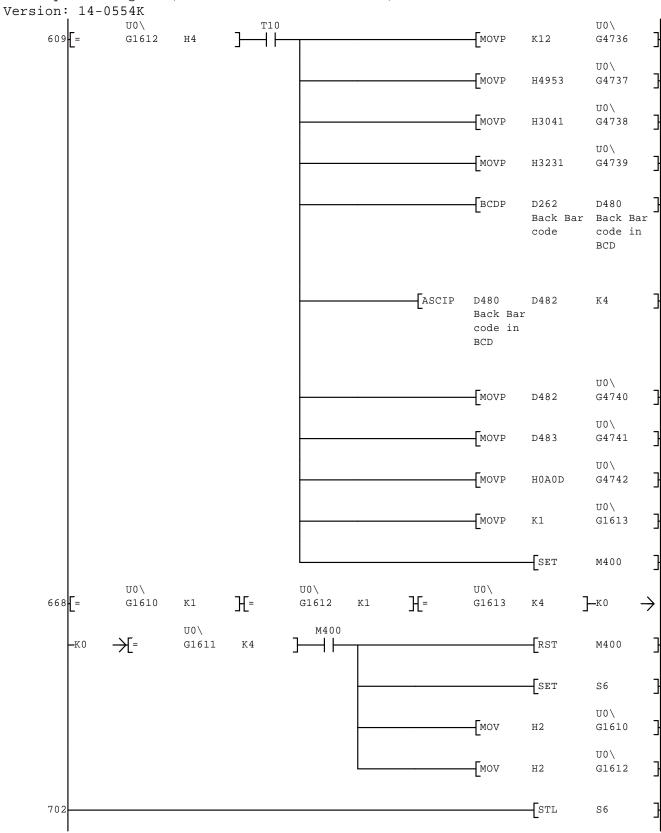






Main System Program (LSI Serial Number 14-0554)





Main System Program (LSI Serial Number 14-0554) Version: 14-0554K * close ports UO\ UO\ UO\ \mathbb{H} = 703**F**= MOVP G1612 Н4 G1610 Н4 H8000 G1604 U0\ MOVP Н8000 G1602 UO/ **]**_K0 G1602 ΚO UO\ -= SET **–**K0 G1604 ΚO S0 RST M499 send dat 736 RET * end ethernet comms * start CCLINK comms to head PLCS M8000 FROM К1 H0A K4M20 К1 always o module e rror M20 M35 module e link ok PLS М0 rror M0SET M1

Main System Program (LSI Serial Number 14-0554) Version: 14-0554K Mov К2 D0 # statio ns -[MOV К7 D1 # retrie -[MOV К2 D2 auto ret urn stat ions TO К1 Н1 D0 К3 # statio ns -[MOV ΚO D3 plc erro r stop ТО К1 Нб D3 К1 plc erro r stop MOV H1401 D4 station 1 MOV H1405 D5 station 2

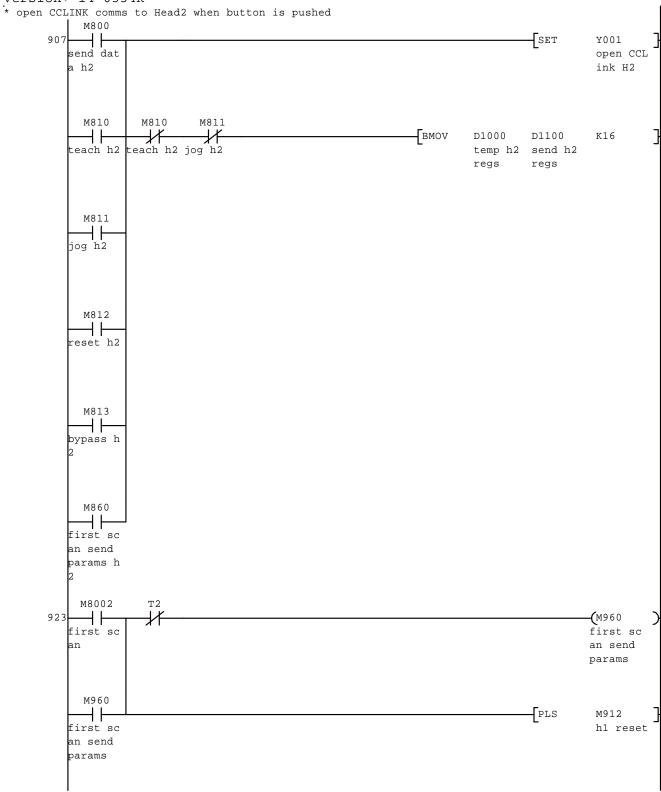
Main System Program (LSI Serial Number 14-0554) Version: 14-0554K ТО К1 H20 D4 К2 station 1 RST M1 M8002 SET 812 \dashv \vdash M40 first sc an M20 M35 module e link ok PLS 814 M2 rror М2 SET 818 М3 SET M46 M26 RST 822 M46 RST мз M27 825 FROM D100 К1 H668 К1 RST M46 RST МЗ M8000 always o TO К1 HOA K4M40 К1

Version: 14-0554K M35 M20 M21 module e link ok 4 + FROM Н1 H680 K1M401 К1 rror M401 # CALL Р1 send par ams h1 M401 **(**M901 M405 1/ CALL Ρ2 send par ams h2 M405 **(**M801 M902 BMOV D600 D800 K16 send h1 temp h1 cancel s end para regs regs ms hl

Version: 14-0554K

 $\dot{}^{\star}$ open CCLINK comms to Headl when button is pushed M900 -[SET 883 Y000 send dat head 1 o a h1 pen CCLi nk M910 M910 M911 h1 teach h1 teach h1 jog BMOV D800 D600 K16 temp h1 send h1 regs regs M911 h1 jog M912 +h1 reset M913 +h1 bypas M960 first sc an send params M802 BMOV 899 D1100 D1000 K16 cancel s send h2 temp h2 end para regs regs ms h2

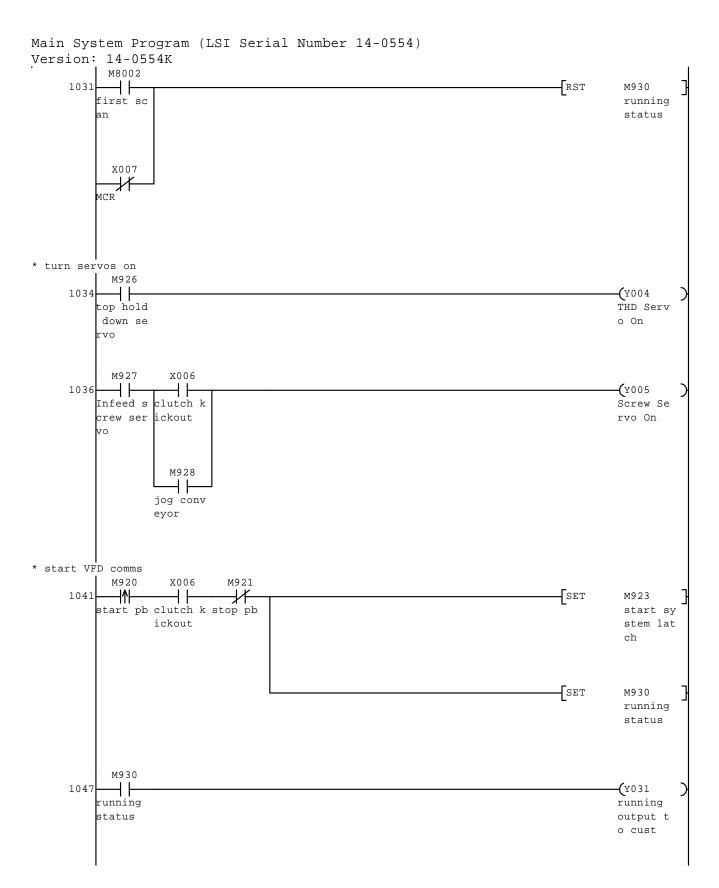
Version: 14-0554K

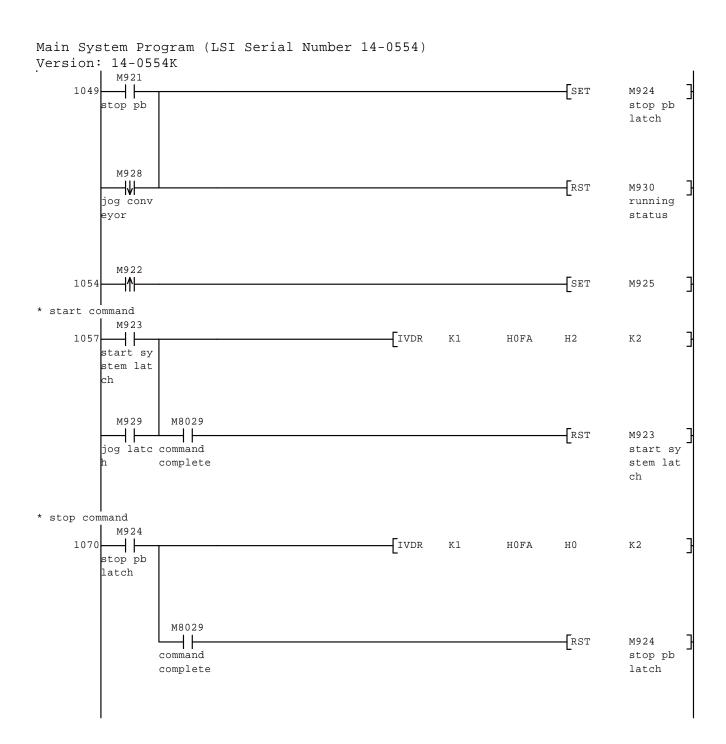


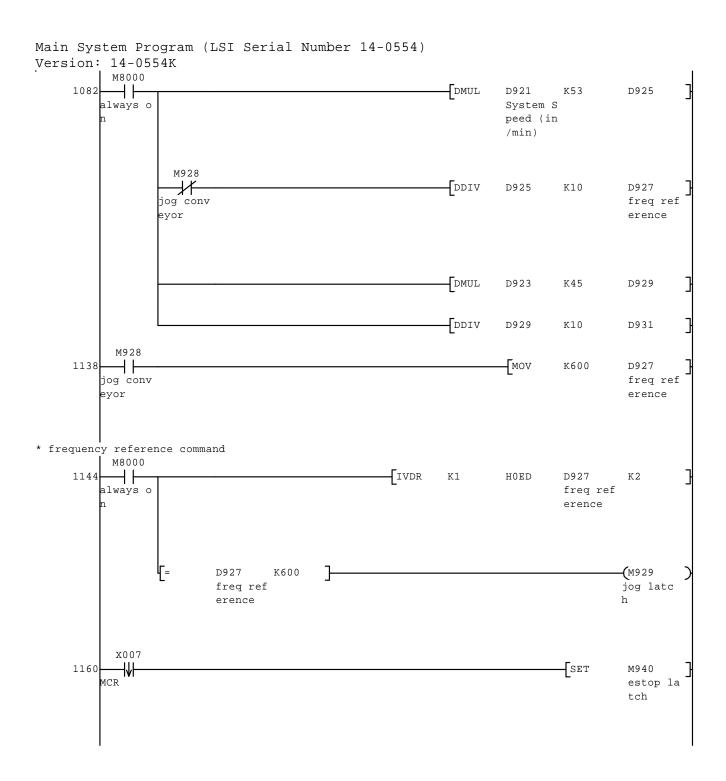
```
Version: 14-0554K
                                                                                                (M860
                                                                                                first sc
                                                                                                an send
                                                                                                params h
                                                                                                2
             M860
                                                                                      PLS
                                                                                                 M812
           first sc
                                                                                                 reset h2
          an send
          params h
            M960
                                                                                                   K20
             \dashv \vdash
                                                                                                -(T2
       939
          first sc
           an send
           params
            M860
                                                                                                    К5
          first sc
                                                                                                (T3
           an send
          params h
            M913
             -11
                                                                                      -[ALT
                                                                                                 M914
                                                                                                 h1 bypas
          h1 bypas
                                                                                                 s status
            M813
                                                                                      ALT
       952
            ┵
                                                                                                 M814
          bypass h
                                                                                                 h2 bypas
                                                                                                 s status
            M910
          hl teach
                                                                            -[MOV
                                                                                      К1
                                                                                                 D609
            M810
             \dashv \vdash
                                                                             MOV
                                                                                      К1
                                                                                                 D1109
          teach h2
```

Version: 14-0554K M911 _[MOV К2 D609 h1 jog M811 jog h2 MOV К2 D1109 M912 MOV D609 К3 h1 reset M812 reset h2 Mov D1109 К3 M913 -[MOV 4 + Κ4 D609 h1 bypas M813 MOV D1109 Κ4 bypass h

Main System Program (LSI Serial Number 14-0554) Version: 14-0554K M910 h1 teach _[MOV 1005 ΚO D609 M911 -₩ h1 jog M912 h1 reset M913 h1 bypas M810 _[MOV **--|↓|-**1018 ΚO D1109 teach h2 M811 jog h2 M812 reset h2 M813 اال⊢ bypass h

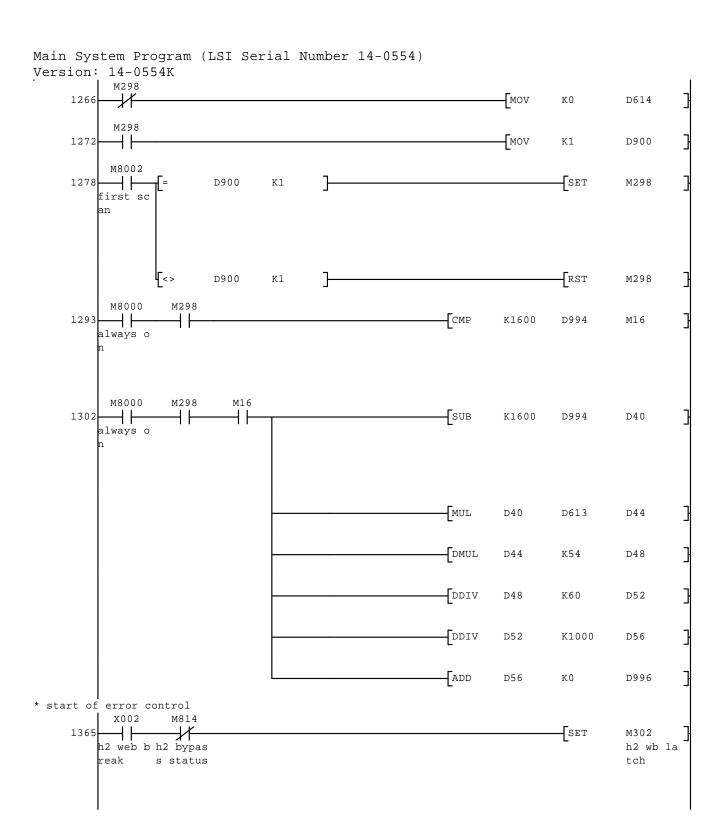






Main System Program (LSI Serial Number 14-0554) Version: 14-0554K * reset drive after estop M940 X007 M941 estop la MCR 1163 \dashv \vdash IVDR К1 H0FD Н9696 Κ2 reset es tch top M8029 +RST M940 command estop la complete tch RST M941 reset es top M8000 SPD 1178 \dashv \vdash X001 K1000 D10 always o Mov D10 D20 DMUL D20 K6000 D24 DDIV D24 D611 D36 Mov D36 D994 * product counter X000 K32767 1222 **(**C102 h1 trigg product counter X016 K32767 **-**(C6 h2 trigg

```
Main System Program (LSI Serial Number 14-0554)
Version: 14-0554K
            C102
                                                                                  RST
     1230
                                                                                            C102
          product
                                                                                            product
          counter
                                                                                            counter
            M995
          reset pr
          od ctr
             С6
                                                                                  RST
     1234
                                                                                            С6
            M885
             Т0
                                                                                              K100
     1238
                                                                                           (T0
            X000
                                                                                             K32767
     1242
             +
                                                                                           (C18
          hl trigg
                                                                                           rate cou
          er
                                                                                           nter
* rate
           M8000
                      Т0
            \dashv \vdash
                                                               MUL
     1246
                                                                                            D15
                                                                        C18
                                                                                 Кб
                                                                                            rate ppm
          always o
                                                                        rate cou
                                                                        nter
                                                                                           (M70
             M70
                                                                                  RST
     1256
                                                                                            C18
                                                                                            rate cou
                                                                                            nter
             C18
          rate cou
          nter
            M298
     1260
                                                                         MOV
                                                                                            D614
                                                                                 К1
```



Version: 14-0554K

X004 M914

1368 Set M304

hl web b hl bypas

reak s status

SET M304

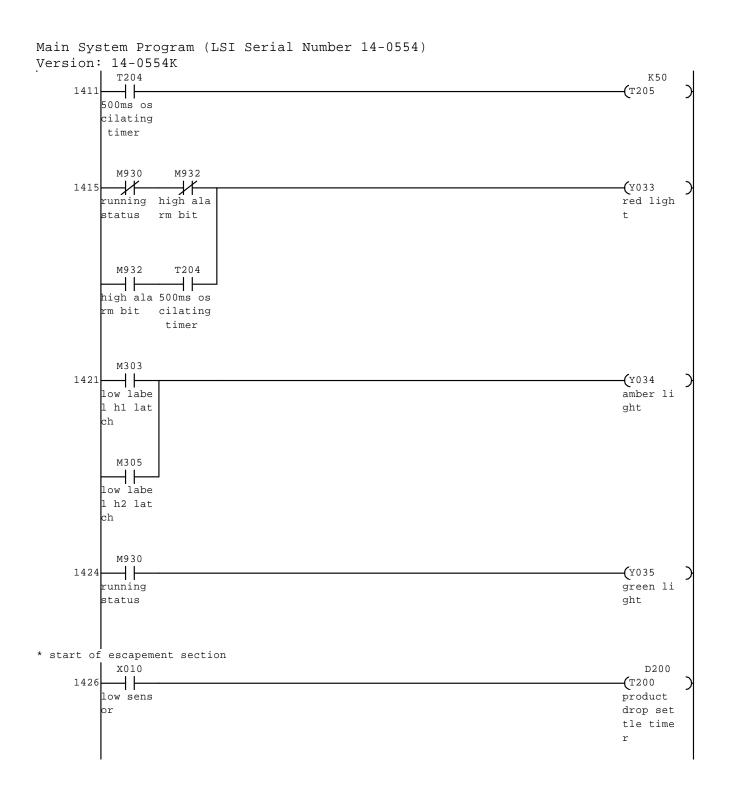
hl web b

reak lat

ch

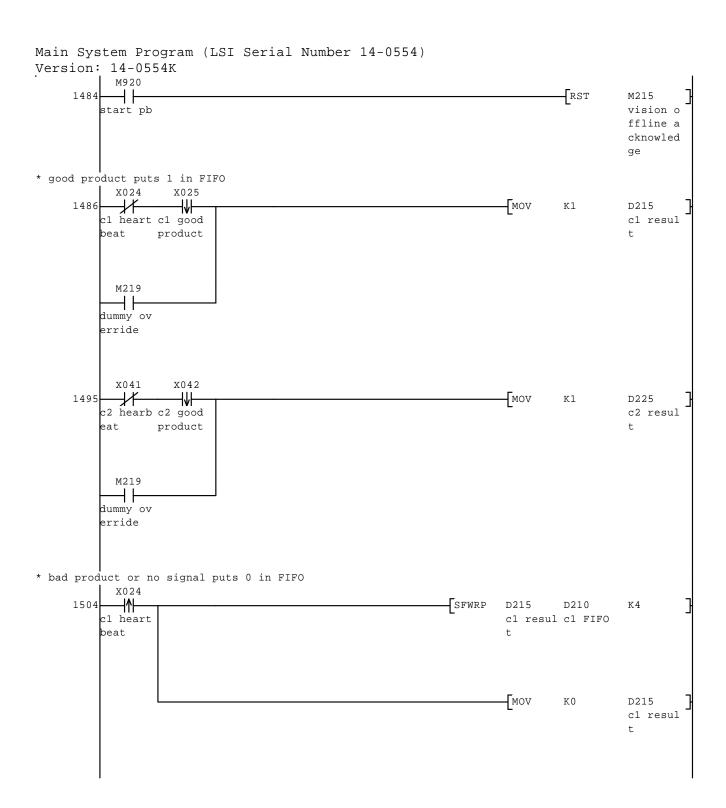
Version: 14-0554K * high alarm stops conveyor M302 1371 **(**M921 h2 wb la stop pb tch M304 X006 \dashv \vdash MOV К9 D250 h1 web b clutch k screen w indow co reak lat ickout ch ntrol X006 X006 **(**M931 clutch k clutch k window c ickout ickout ontrol b it M940 \dashv \vdash **(**M932 high ala estop la tch rm bit M204 \dashv \vdash reject b in not i n place M206 \dashv \vdash product jam timi ng screw M207 outfeed bin not in place M205 \dashv \vdash consecut ive reje cted pro ducts

```
Main System Program (LSI Serial Number 14-0554)
Version: 14-0554K
            M217
          reject u
          nverifie
            M210
             \dashv \vdash
          vision s
          ystem of
          fline
           M228
            \dashv \vdash
          Outfeed
          Bins Ful
            M231
          reject s
          ensor fa
          ilure
           M931
                                                                        MOV
            D250
                                                                                 ΚO
                                                                                           screen w
          ontrol b
                                                                                           indow co
          it
                                                                                           ntrol
           X014
          low labe
                                                                                 SET
     1403
                                                                                           M303
                                                                                           low labe
          l h1
                                                                                           l h1 lat
                                                                                           ch
           X005
          low labe
                                                                                 SET
     1405
                                                                                           M305
                                                                                           low labe
          1 h2
                                                                                           1 h2 lat
                                                                                           ch
* alarm beacon section (Red Amber Green)
            T205
                                                                                              K50
     1407
                                                                                           -(T204
                                                                                          500ms os
                                                                                          cilating
                                                                                           timer
```



```
Main System Program (LSI Serial Number 14-0554)
Version: 14-0554K
                      M203
            T200
      1430
                                                                                               (Y002
          product
                    product
                                                                                              high sto
          drop set dropped
                                                                                              pper
          tle time
            Y002
          high sto
          pper
            Y002
                     X011
      1434
            \dashv \vdash
                                                                                               (Y030
          high sto high sen
                                                                                              hopper f
          pper
                   sor
                                                                                              ull (to
                                                                                              cust)
                      Y002
            X012
             --|↓|-
                                                                                     SET
      1437
                                                                                               M202
          timing s high sto
                                                                                               ready to
          crew syn pper
                                                                                                drop
          ch senso
                               M202
                                        X007
                                                  X006
           M8000
                     Y002
            \dashv\vdash
                               \dashv \vdash
                                                                                               (Y003
                      \dashv \vdash
                                                  \dashv \vdash
          always o high sto ready to MCR
                                                clutch k
                                                                                              low stop
                                                ickout
                   pper drop
                                                                                              per
            Y003
                      X010
                                                                                                  D201
      1447
            \dashv \vdash
                                                                                               (T201
          low stop low sens
                                                                                              drop int
          per or
                                                                                              o screw
                                                                                              clear ti
                                                                                              mer
            T201
          drop int
                                                                                     RST
      1452
                                                                                               M202
                                                                                               ready to
                                                                                                drop
          o screw
          clear ti
          mer
            Y003
                                                                                               (M203
          low stop
                                                                                              product
          per
                                                                                              dropped
```

Main System Program (LSI Serial Number 14-0554) Version: 14-0554K * start of vision inspection * check to see if cameras are online X023 M215 M224 **(**M210 cl not o vision o vision s vision s ffline a ystem by nline ystem of cknowled pass fline ge X040 c2 not o nline $\mbox{\scriptsize \star}$ if no inspection has occured in 4 pockets, reset FIFO X012 Κ4 ⊣↓⊢ 1462 **(**C120 timing s vision r crew syn eset cou ch senso nter X024 1467 # RST C120 c1 heart vision r beat eset cou nter X041 ||/ c2 hearb eat C120 آ+ MOV 1471 D210 ΚO vision r c1 FIFO eset cou nter MOV ΚO D220 c2 FIFO RST C120 vision r eset cou nter



Main System Program (LSI Serial Number 14-0554) Version: 14-0554K X041 1518 SFWRP D225 D220 К4 c2 hearb c2 resul c2 FIFO eat t MOV ΚO D225 c2 resul X024 SET $\dashv \uparrow \vdash$ 1532 M230 c1 heart camera 2 inspect beat ion done M230 X013 K150 **(**T210 1535 camera 2 reject s inspect ensor ion done X041 SET **--|**↑|-M232 c2 hearb camera 1 eat inspect ion done M232 X013 K200 1543 **(**T211 camera 1 reject s inspect ensor ion done T210 SET 1548 M231 reject s

T211

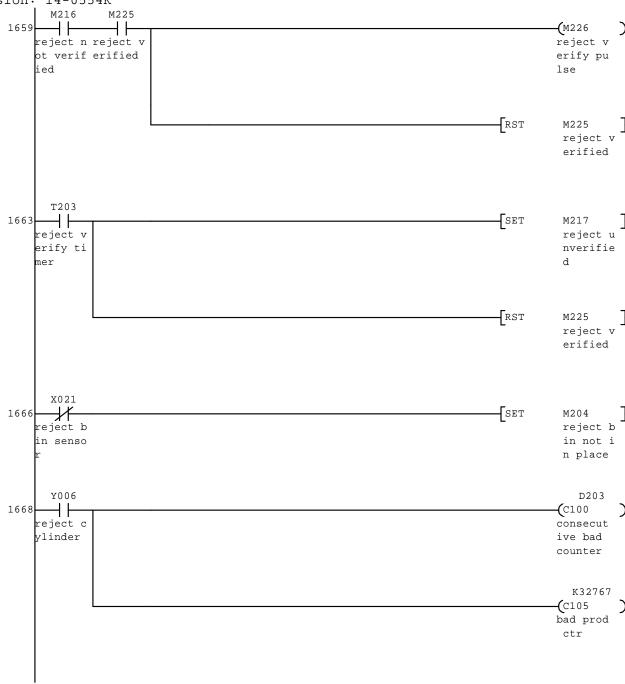
ensor fa ilure

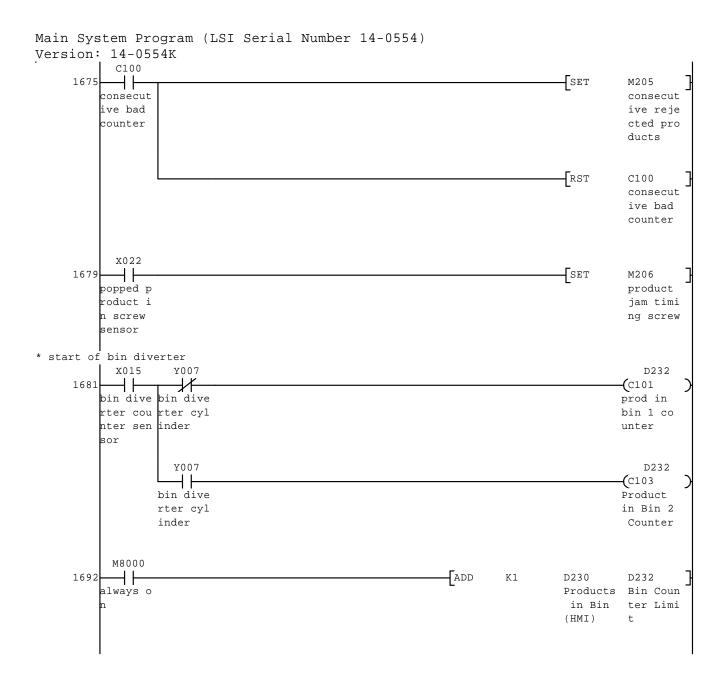
```
Main System Program (LSI Serial Number 14-0554)
Version: 14-0554K
            X013
                      M230
      1551
                                                                                    RST
                                                                                              M230
          reject s camera 2
                                                                                              camera 2
          ensor
                    inspect
                                                                                               inspect
                   ion done
                                                                                              ion done
                      M232
            X013
             \dashv \uparrow \vdash
                                                                                    RST
                                                                                              M232
          reject s camera 1
                                                                                              camera 1
          ensor
                    inspect
                                                                                               inspect
                   ion done
                                                                                              ion done
            M231
             \dashv \vdash
           reject s
           ensor fa
          ilure
           M8002
          first sc
          an
* Added M224 & M213 - MW 01-22-09
            X013
                      M224
                                                                                    SET
      1562
             ╢
                                                                                              M212
                                                                                              read res
          reject s vision s
                   ystem by
                                                                                              ults lat
          ensor
                                                                                              ch
                   pass
                      M224
                                                                                    SET
                                                                                              M213
                   vision s
                                                                                              bad prod
                   ystem by
                                                                                              uct
                   pass
* read FIFO on leading edge of reject sensor
            M212
          read res
                                                                  SFRDP
      1570
                                                                           D210
                                                                                    D216
                                                                                              Κ4
                                                                           c1 FIFO c1 resul
          ults lat
                                                                                    ts POP
          ch
                                                                  SFRDP
                                                                           D220
                                                                                    D226
                                                                                              Κ4
                                                                           c2 FIFO c2 resul
                                                                                    ts POP
```

Main System Program (LSI Serial Number 14-0554) Version: 14-0554K * if either FIFO = 0 , reject M212 read res 1585 D216 ΚO SET M213 c1 resul bad prod ults lat ts POP uct ch RST D226 M212 ΚO c2 resul read res ts POP ults lat ch * if both FIFOs =1, good product M212 1599 D216 H= D226 RST C100 read res c1 resul c2 resul consecut ults lat ts POP ts POP ive bad ch counter K32767 **(**C104 good pro duct cou nter RST M212 read res ults lat ch M220 RST 1616 C104 st good good pro prod ct duct cou nter M223 \dashv \vdash RST 1619 C105 rst bad bad prod prod ctr ctr

Version: 14-0554K * on trailing edge of reject sensor, reject * Upper Output step was LDI T202 LDI M224 OUT Y006 - MW 01-22-09 $\,$ X013 M213 T202 **(**Y006 reject s bad prod reject t reject c ensor uct ime ylinder Y006 RST \dashv \vdash M213 reject c bad prod ylinder uct Y006 D202 1631 \dashv \vdash **(**T202 reject c reject t ylinder ime X013 M213 ╢ 1/ MOV 1635 ΚO D216 reject s bad prod c1 resul ensor uct ts POP MOV ΚO D226 c2 resul ts POP Y006 M217 M226 ╢ **(**M216 reject c reject u reject v reject n ylinder nverifie erify pu ot verif ied lse M216 reject n ot verif ied M216 M225 K50 **(**T203 reject n reject v reject v ot verif erified erify ti ied mer

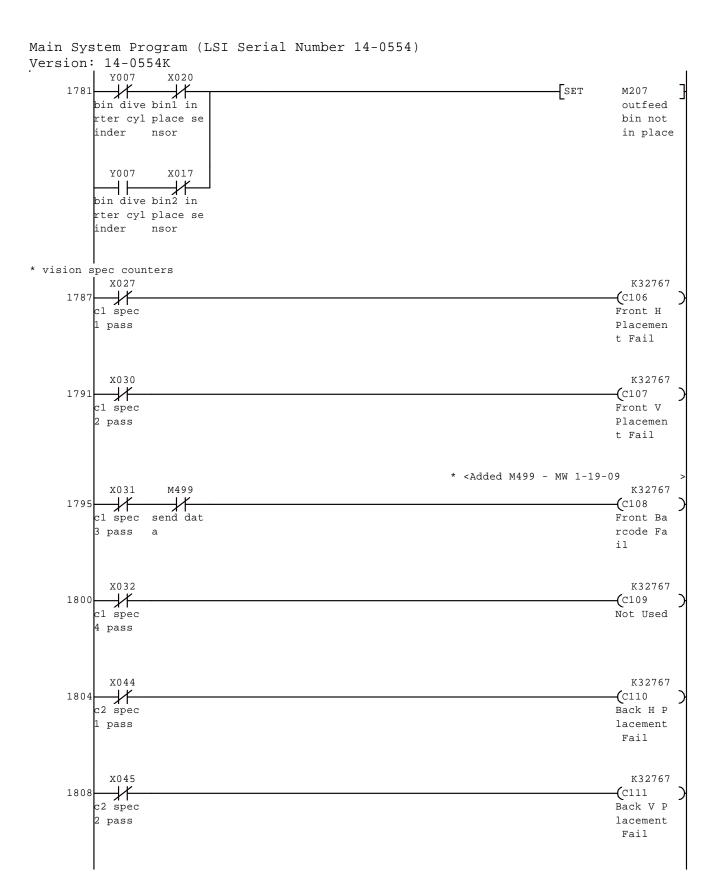
Main System Program (LSI Serial Number 14-0554) Version: 14-0554K





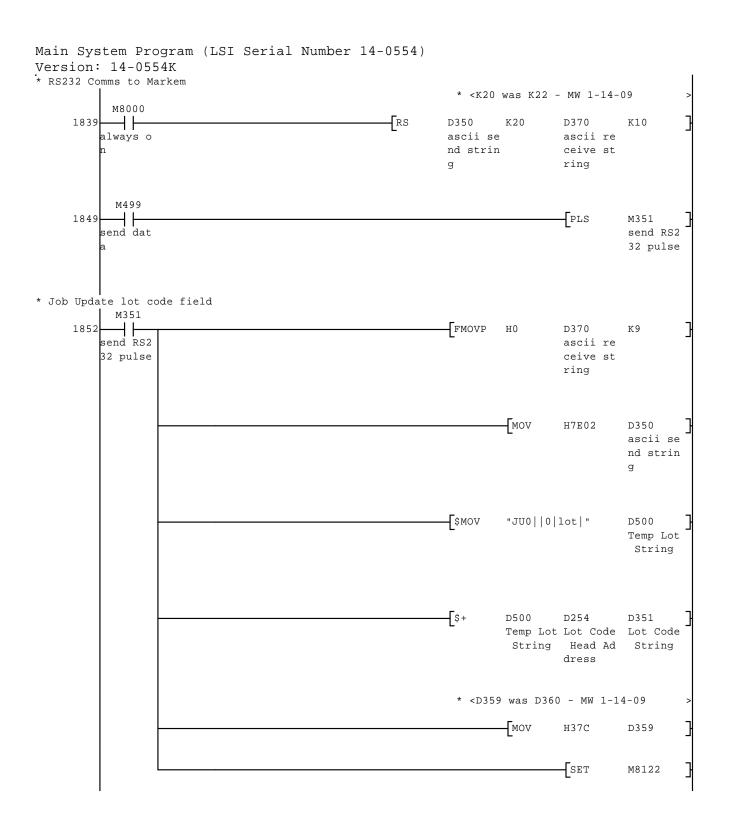
Main System Program (LSI Serial Number 14-0554) Version: 14-0554K M8000 1700 \dashv \vdash C101 D230 SUB C101 К1 D231 always o prod in Products prod in Bin 1 Co bin 1 co in Bin bin 1 co unter (HMI) unter unter MOV C101 C101 D230 D231 prod in Bin 1 Co prod in Products bin 1 co in Bin bin 1 co unter unter (HMI) unter C103 D230 C103 D234 Product Products Product Bin 2 Co in Bin 2 in Bin in Bin 2 unter Counter (HMI) Counter MOV C103 C103 D230 D234 Product Products Product Bin 2 Co in Bin 2 unter in Bin 2 in Bin Counter (HMI) Counter C101 C103 ALT Y007 prod in Product bin dive bin dive bin 1 co in Bin 2 rter cyl rter cyl unter Counter inder inder C103 C101 Y007 Product prod in bin dive in Bin 2 bin 1 co rter cyl Counter unter inder C101 C103 SET M228 Outfeed bin 1 co in Bin 2 Bins Ful unter Counter

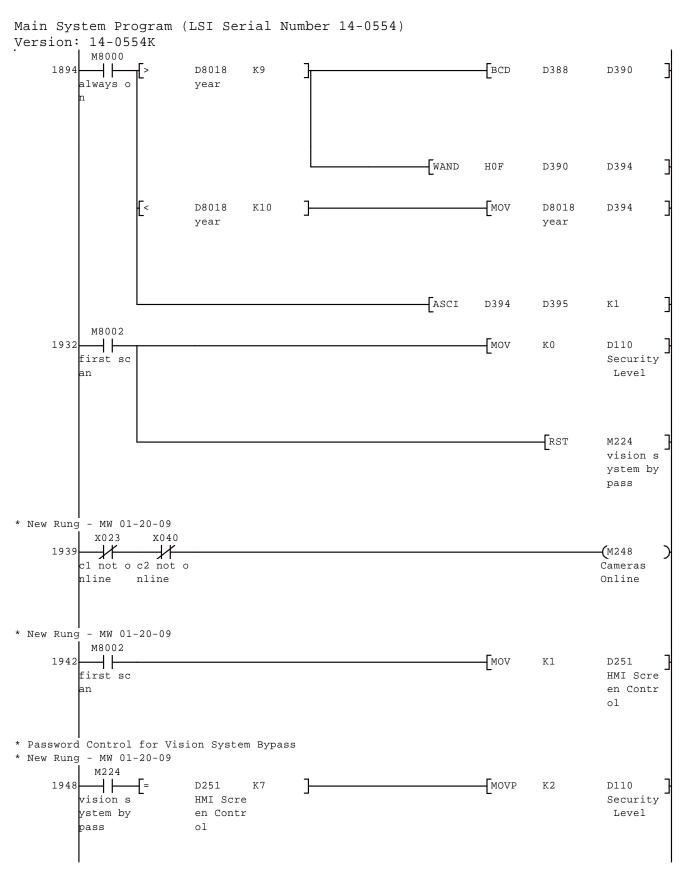
Main System Program (LSI Serial Number 14-0554) Version: 14-0554K M228 M229 1762 Outfeed Outfeed RST C101 prod in Bins Ful Bin Full bin 1 co Reset unter RST C103 Product in Bin 2 Counter RST M228 Outfeed Bins Ful Y007 X020 C101 RST 1769 C101 prod in prod in bin dive binl in bin 1 co rter cyl place se bin 1 co inder unter unter nsor M218 \dashv \vdash reset bi n ctr C103 X017 Y007 RST C103 Product bin dive bin2 in Product in Bin 2 rter cyl place se in Bin 2 Counter inder Counter M218 reset bi n ctr

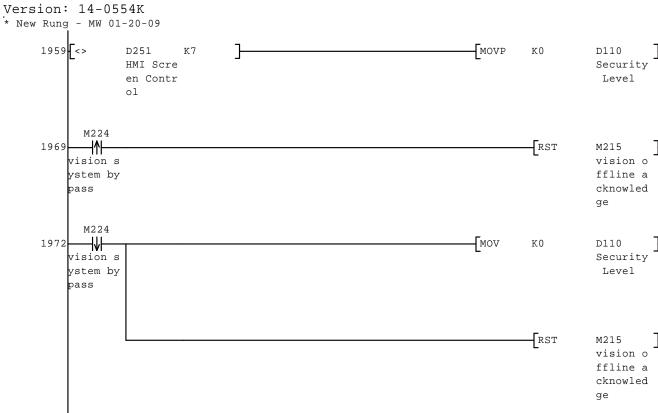




Main System Program (LSI Serial Number 14-0554) Version: 14-0554K M222 reset sp RST 1822 C106 Front H ec count Placemen ers t Fail RST C107 Front V Placemen t Fail RST C108 Front Ba rcode Fa il RST C109 Not Used RST C110 Back H P lacement Fail RST C111 Back V P lacement Fail RST C112 Back Bar code Fai 1 RST C113 Back Lot Code Fa il







Main System Program (LSI Serial Number 14-0554) Version: 14-0554K * New Rung - MW 1-14-09 M495 Save Bar MOV 1980 D264 D260 Front Ba Front Ba code Cha rcode Te rcode nges mp Mov D266 D262 Back Bar Back Bar code Tem code Mov D205 ΚO D264 D7014 Front Ba US Front Program Select rcode Te Barcode MOV D205 ΚO D266 D7015 Back Bar US Back Program Select code Tem Barcode Mov D205 К1 D264 D7044 Program Front Ba Canada F rcode Te ront Bar Select code mp MOV D205 К1 D266 D7045 Program Back Bar Canada B Select code Tem ack Barc ode Mov ┞╸ D205 D264 D7074 Κ2 Program Front Ba Other Fr Select rcode Te ont Barc ode mp

D205

Program Select

К2

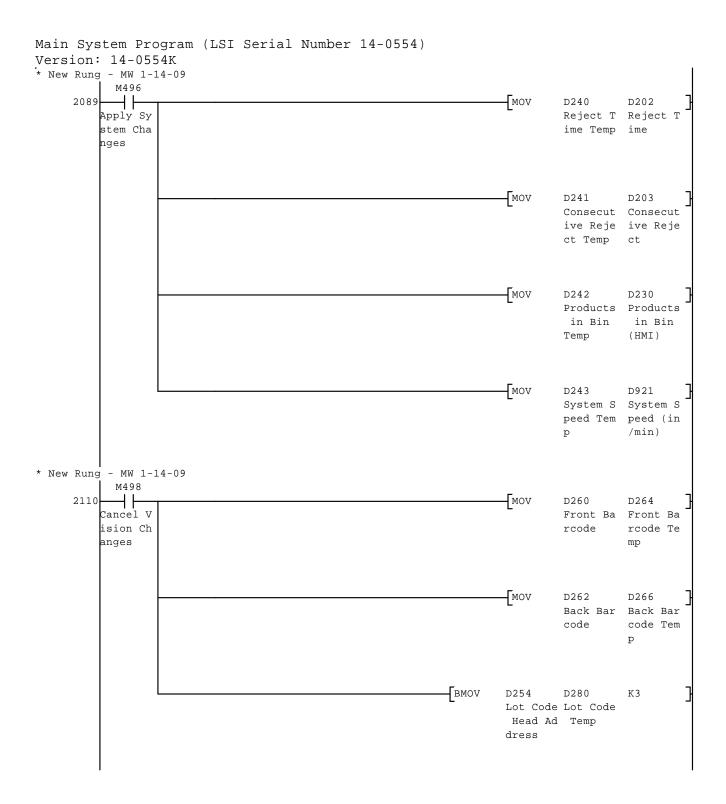
Mov

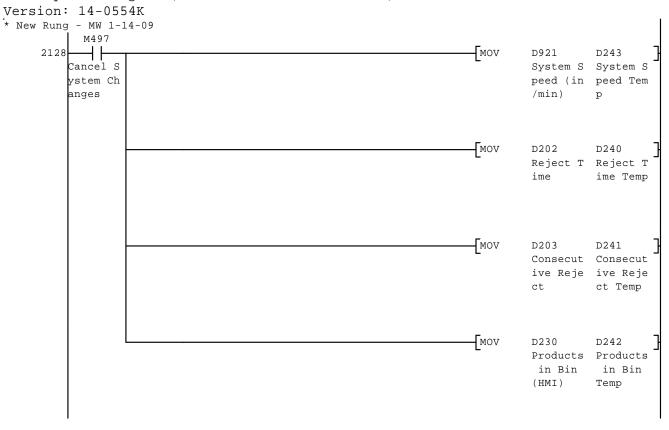
D266

D7075 Back Bar Other Ba

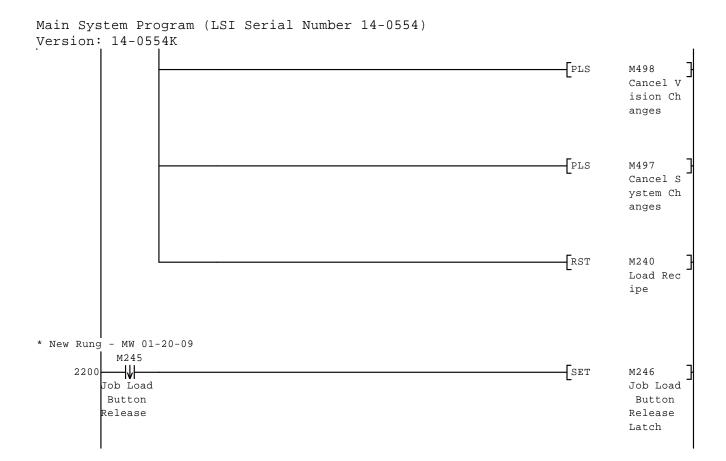
code Tem ck Barco de

Version: 14-0554K Mov D205 К3 D264 D7104 Front Ba Engineer Program Select rcode Te ing Fron t Barcod MOV D205 К3 D266 D7105 Back Bar Engineer Program Select code Tem ing Back Barcode BMOV D254 D280 К3 Lot Code Lot Code Head Ad Temp dress SET M499 send dat RST M495 Save Bar code Cha nges

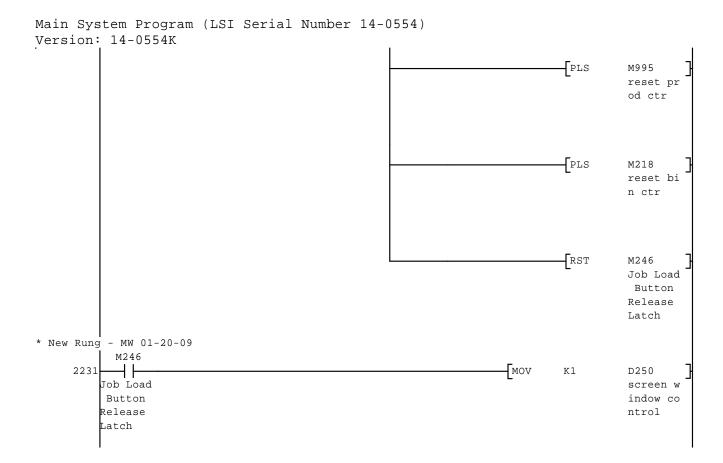


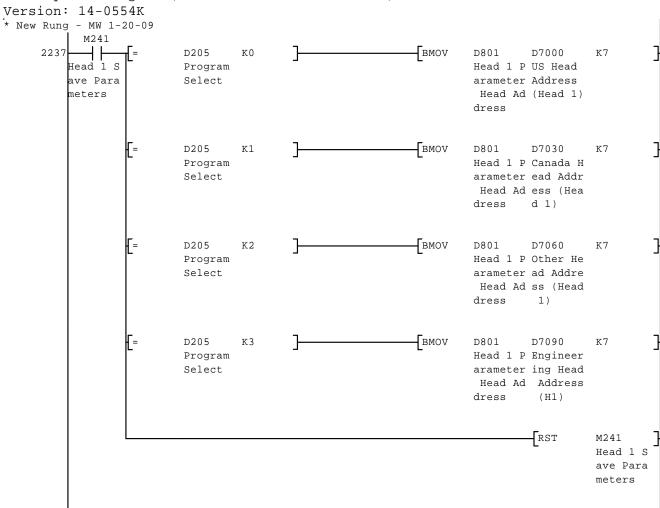


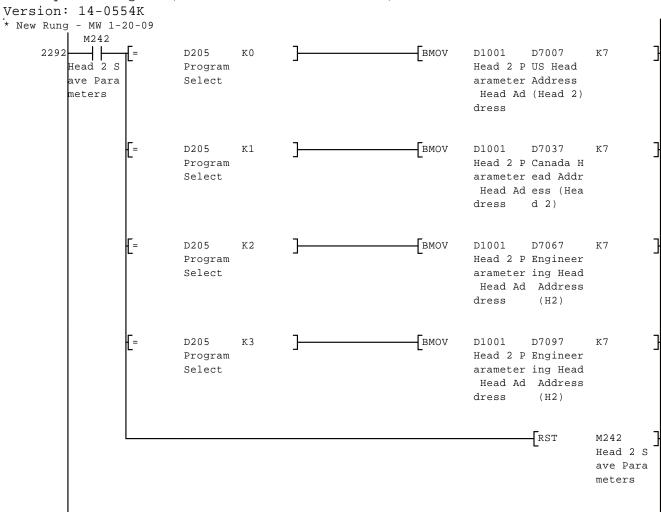
Version: 14-0554K * Recipe Handling * New Rung - MW 1-14-09 M240 CALL 2149 D205 ΚO Ρ4 Load Rec Program US Load ipe Select Recipe CALL D205 К1 Р5 Canada L Program Select oad Reci рe D205 CALL Р6 Program Other Lo ad Recip Select CALL D205 Р7 К3 Program Engineer Select ing Load Recipe PLS M900 send dat a h1 PLS M800 send dat a h2 PLS M902 cancel s end para ms h1 PLS M802 cancel s end para ms h2

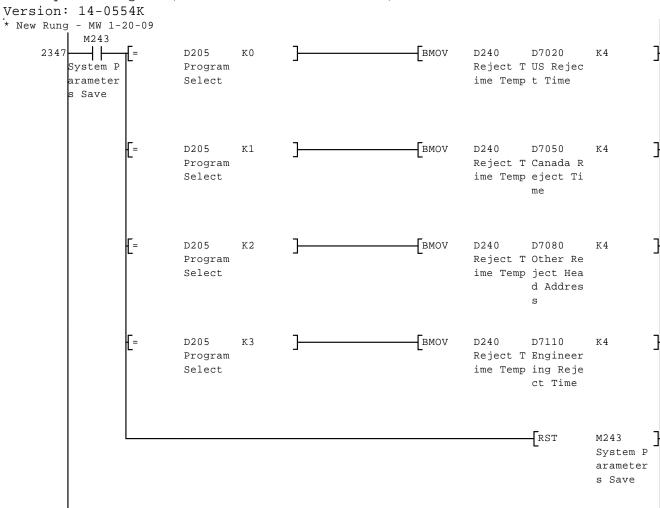


Main System Program (LSI Serial Number 14-0554) Version: 14-0554K * New Rung - MW 01-20-09 M246 К1 Job Load 2203 **(**T6 Camera L Button oad Puls e Width Release Latch Т6 Camera L **(**Y010 Camera 1 oad Puls Job Loa e Width d **(**Y020 Camera 2 Job Loa d X040 X023 K100 Т6 1/ **(**T7 Send Dat Camera L cl not o c2 not o oad Puls nline nline a Delay e Width Т7 SET M499 Send Dat send dat a Delay а PLS M220 rst good prod ct PLS M222 reset sp ec count ers PLS M223 rst bad prod ctr

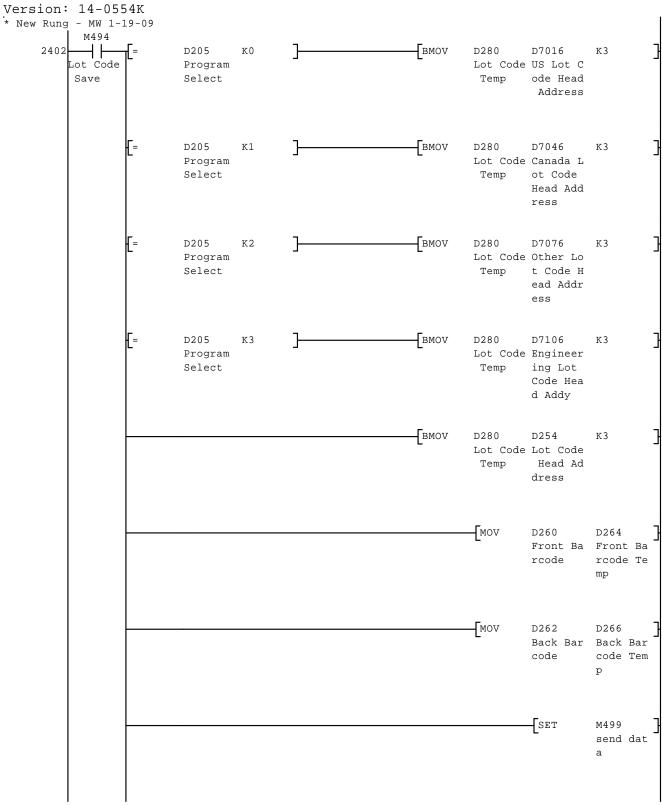


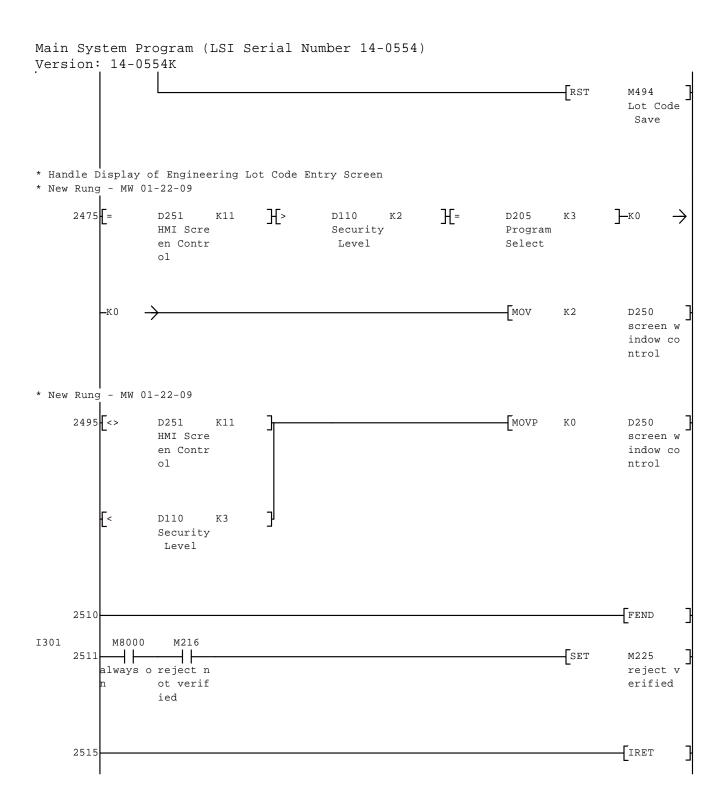


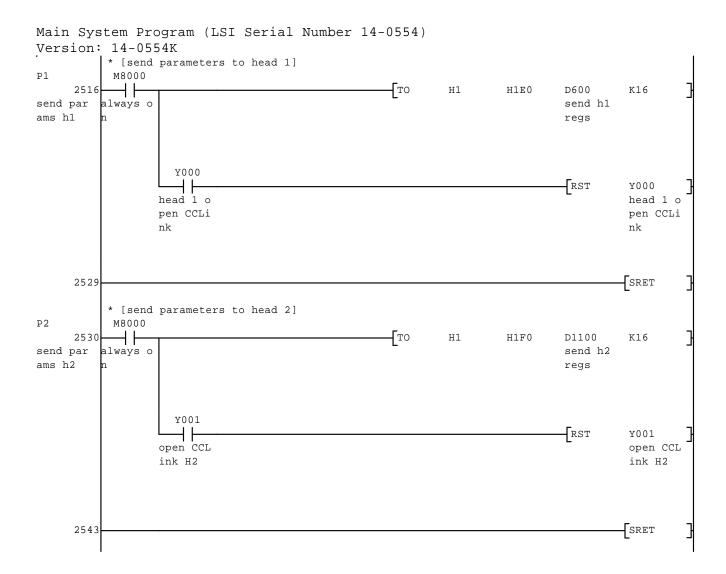


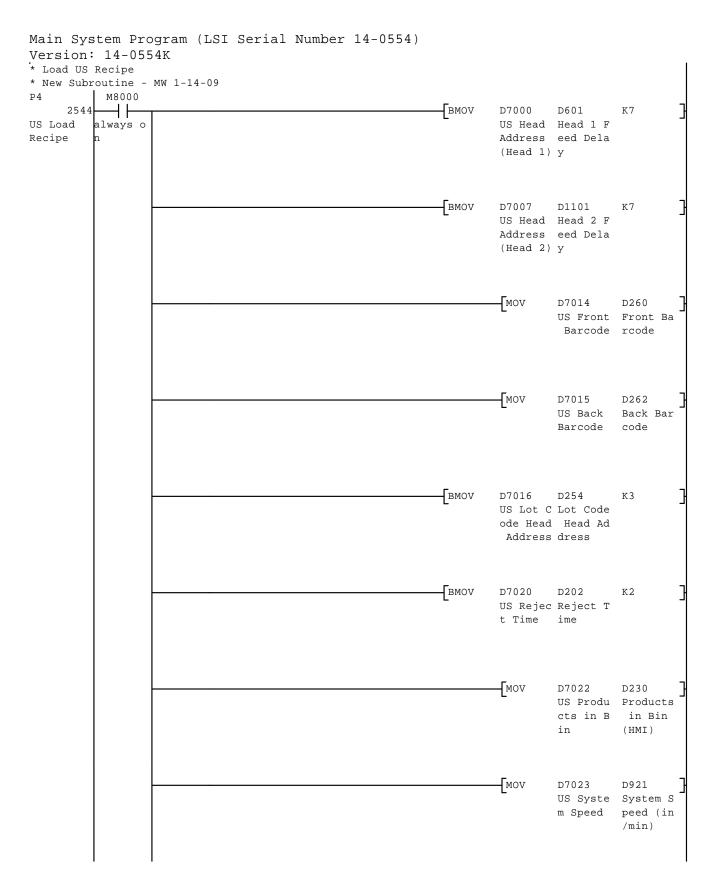


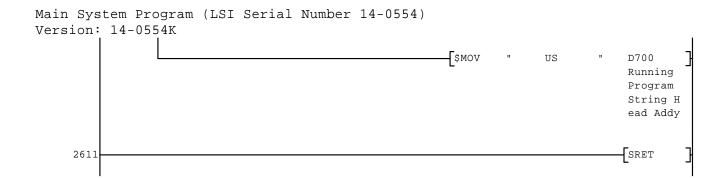
Main System Program (LSI Serial Number 14-0554)

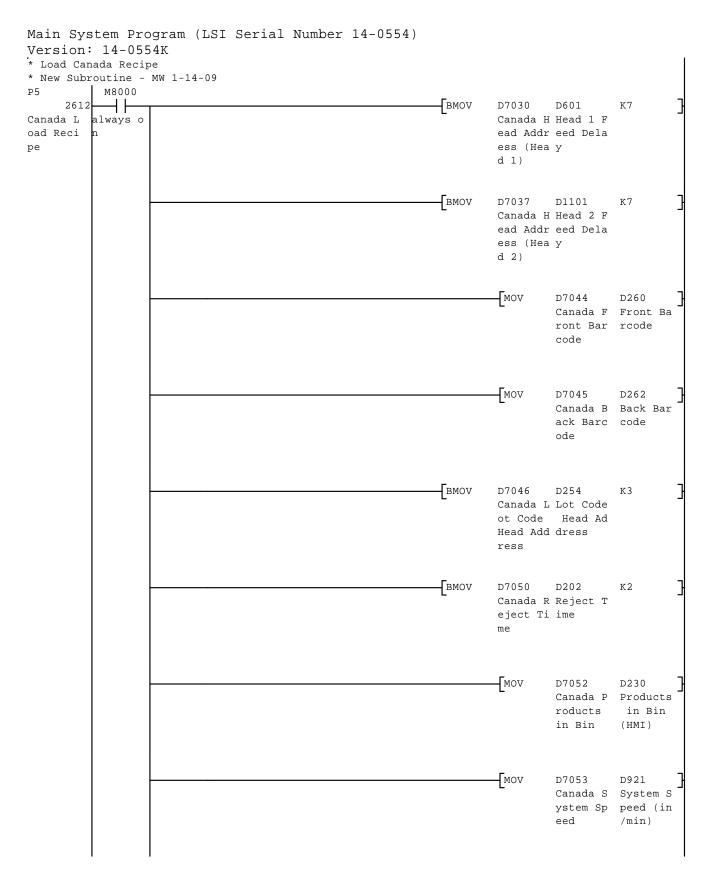


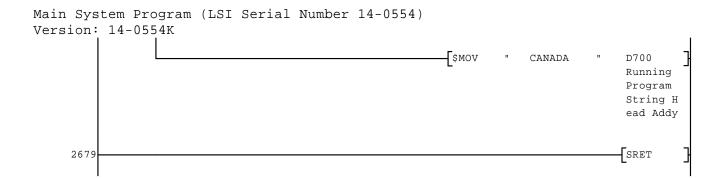


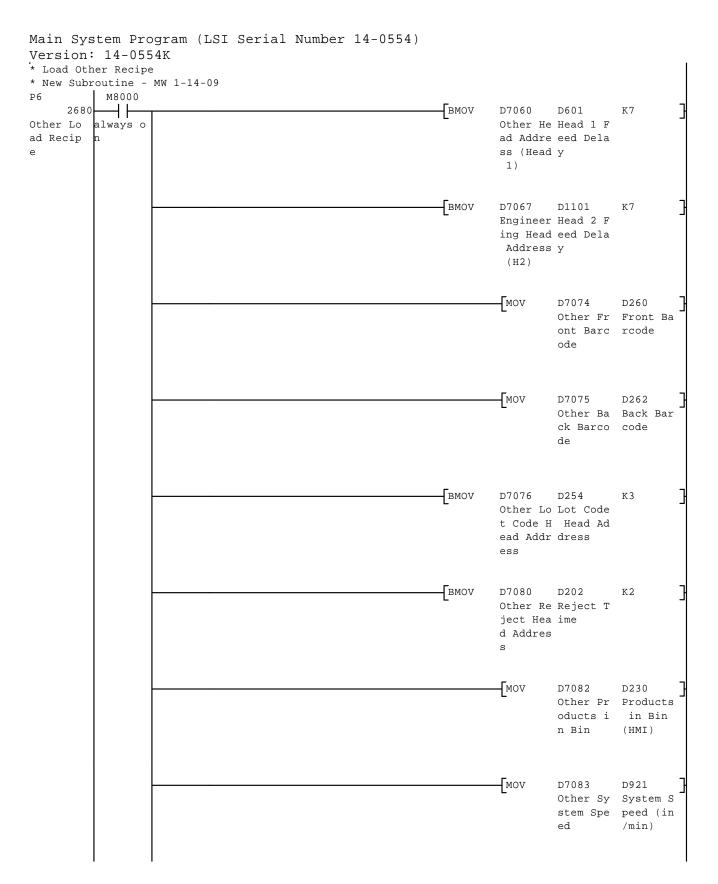


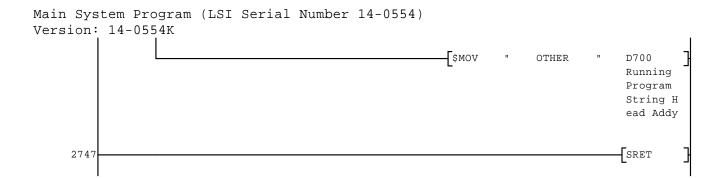


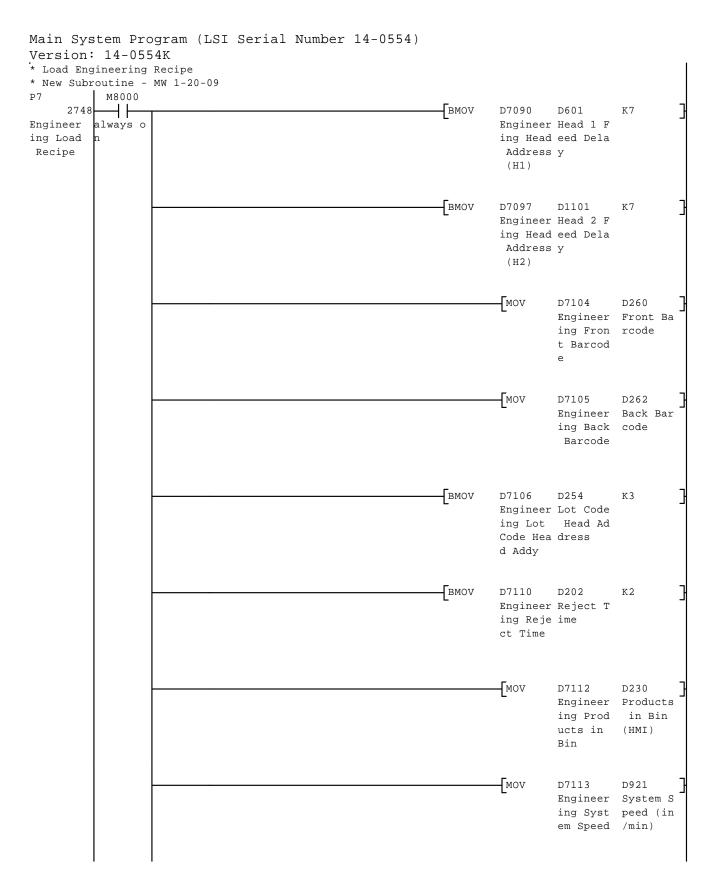


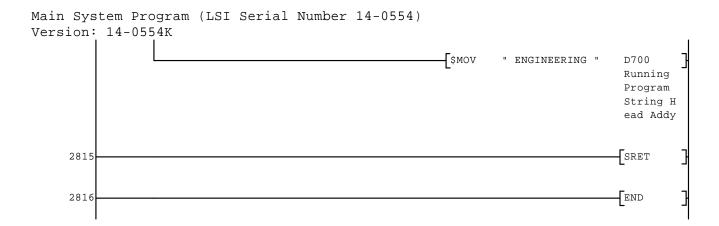








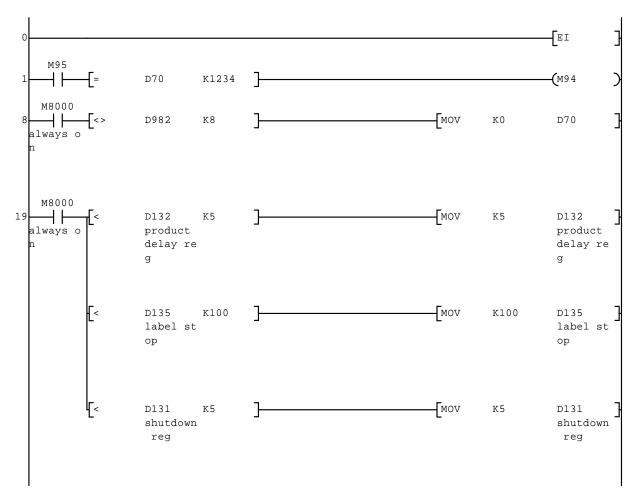


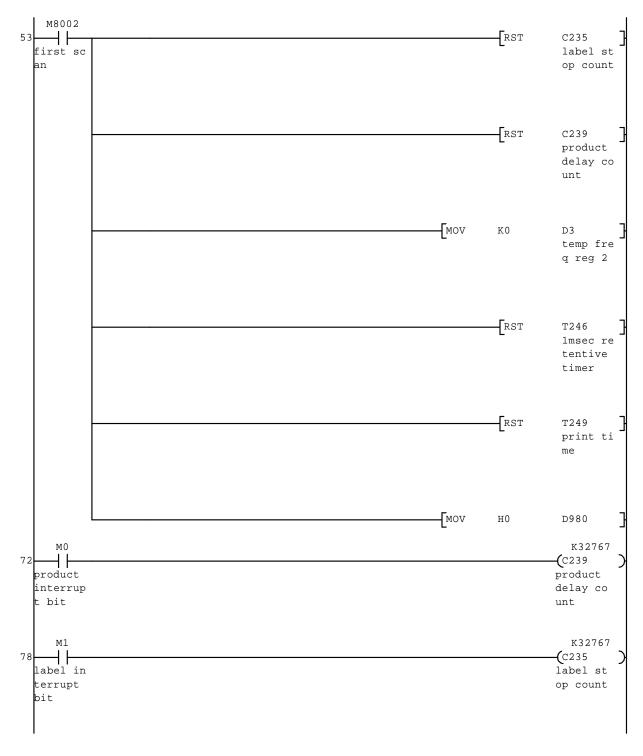


Labeling Head Program (LSI Serial Numbers 40-0334R & 40-0335L)

Both Labeling Heads run an Identical Program

Version: 14-0554 Head Rev D



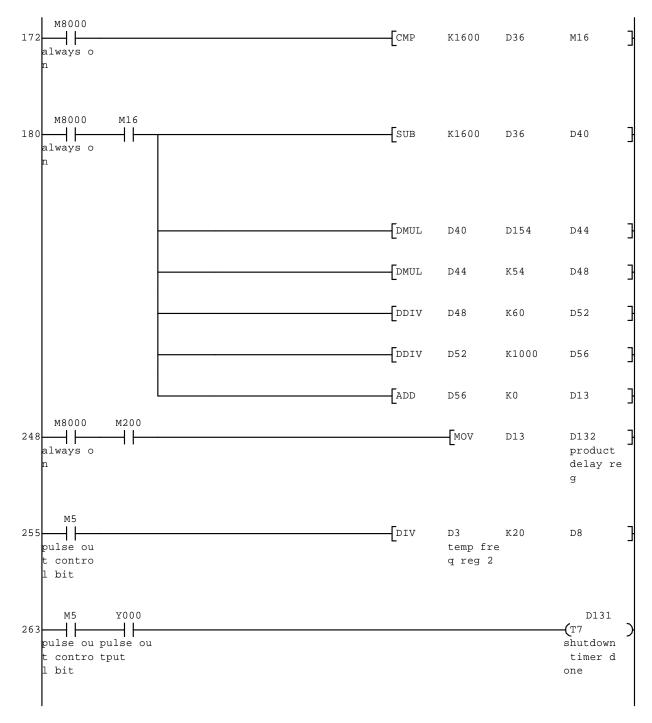


Labeling Head Program (LSI Serial Numbers 40-0334R & 40-0335L) Both Labeling Heads run an Identical Program Version: 14-0554 Head Rev D

```
. \star if non-teach shutdown, inhibit product trigger
          T7 M65
          shutdown teach in
                                                                                PLS
                                                                                          M100
          timer d tlk
          one
           M100
                                                                                         (M105
       88
            M105
                     M61
                  f2 intlk
            M105
       93
                                                                                         (M1213
                                                                                         (M1212
                                                                                         (M1211
          f2 intlk
                                                                                         (M102
```

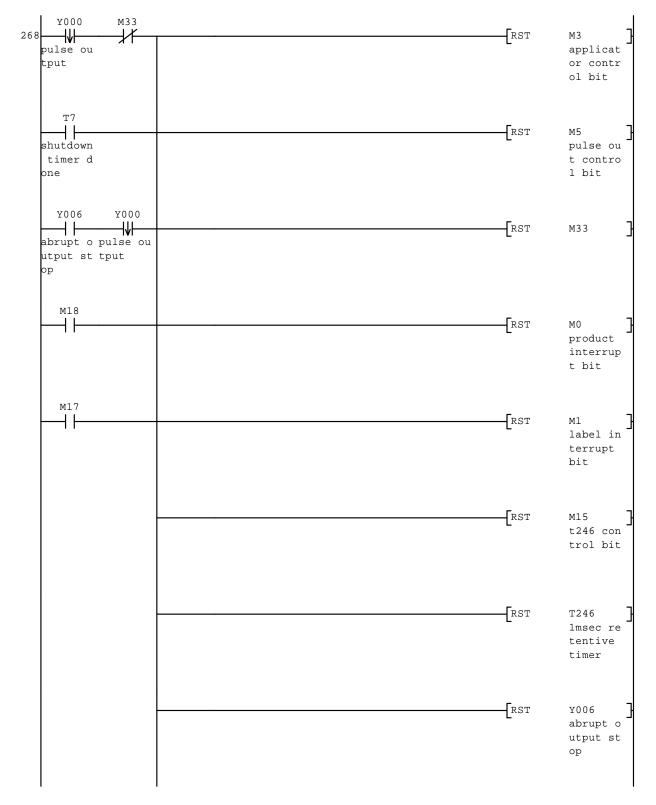
Version: 14-0554 Head Rev D

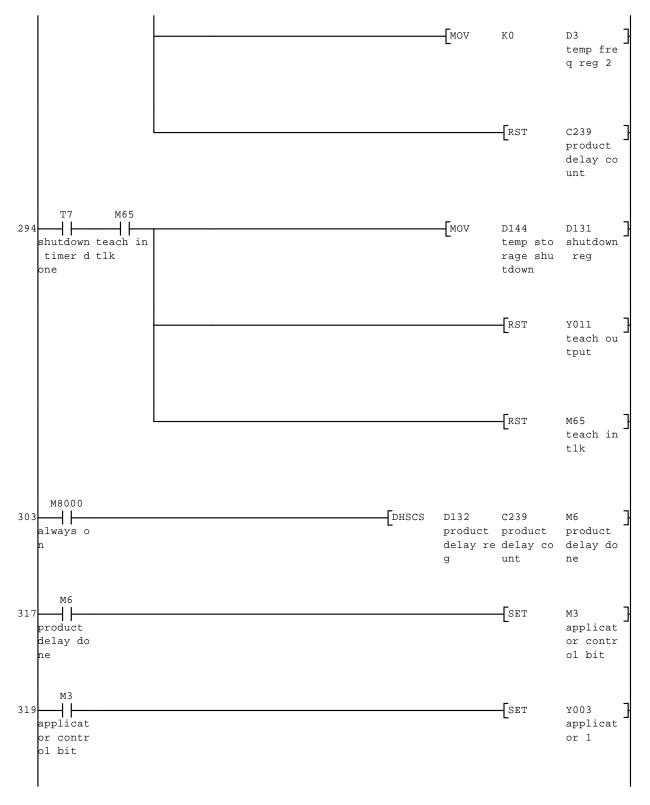
M8000 М5 SPD X001 K100 D10 always o pulse ou teach in speed ca t contro tlk 1c multp l bit input М5 M33 pulse ou contro l bit М5 M65 MOV D10 D20 pulse ou teach in speed ca contro tlk 1c multp l bit input М5 M33 + \dashv \vdash pulse ou t contro 1 bit * <K60000 was K57000 - MW 1-14-09 M8000 M65 -1/4 DMUL 126 D20 K60000 D24 always o teach in tlk M65 -1/4 DDIV D24 D160 D36 teach in Aux Puls tlk e/in M65 MOV D36 D145 teach in calc fre tlk q M8000 \dashv MUL D145 K20 D147 always o calc fre geared freq q



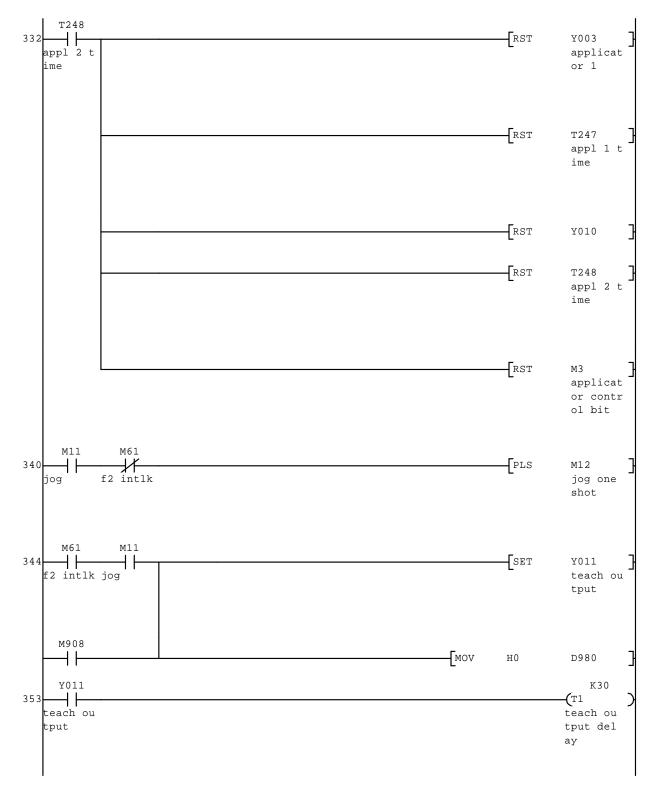
Labeling Head Program (LSI Serial Numbers 40-0334R & 40-0335L)

Both Labeling Heads run an Identical Program

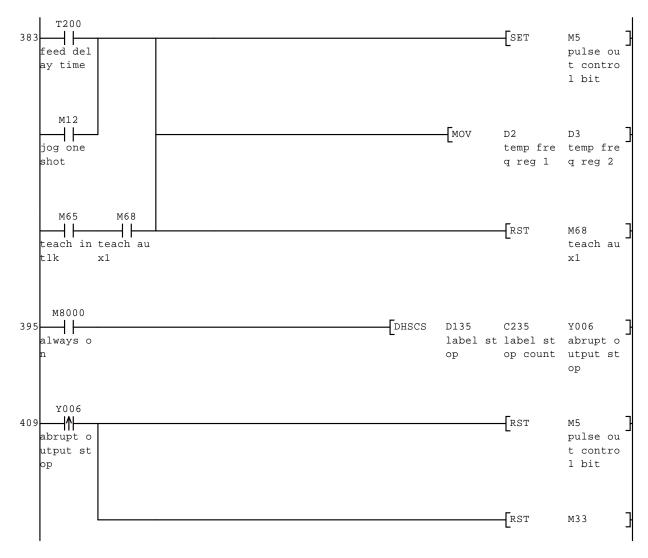




```
Y003
                                                                                       D128
321
                                                                                    (T247
   applicat
                                                                                    appl 1 t
   or 1
                                                                                    ime
     T247
   appl 1 t
                                                                         -[SET
325
                                                                                    Y010
   ime
     X014
   smart se
   nsor
     Y010
                                                                                       D134
328
                                                                                    (T248
                                                                                    appl 2 t
                                                                                    ime
```

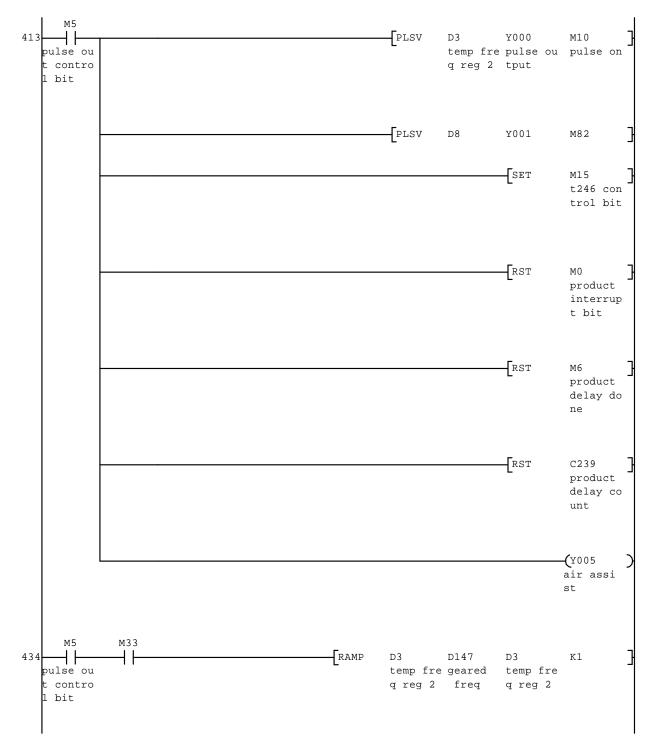


```
Т1
                                                                             PLS
                                                                                        M66
                                                                                        teach de
    teach ou
   tput del
                                                                                        lay done
   ау
                                                                                        one sho
     M66
360 teach de
                                                                             CALL
                                                                                        Р3
                                                                                       call tea
   lay done
                                                                                        ch
    one sho
      M65
                М5
                                                                             PLS
                                                                                        M67
   teach in pulse ou
                                                                                        teach au
   tlk
            t contro
            1 bit
      M67
368
                                                                             SET
     \dashv \vdash
                                                                                        M68
   teach au
                                                                                        teach au
                                                                                        x1
      Мб
                                                                                          D129
                                                                                       (T200
                                                                                       feed del
    product
   delay do
                                                                                       ay time
   ne
                                                                             PLS
                                                                                        M51
                                                                                        prod del
                                                                                        ay done
                                                                                        aux
               M51
      Мб
                                                                    MOV
                                                                             K11
                                                                                        D2
   product prod del
                                                                                        temp fre
   delay do ay done
                                                                                        q reg 1
   ne
            aux
```



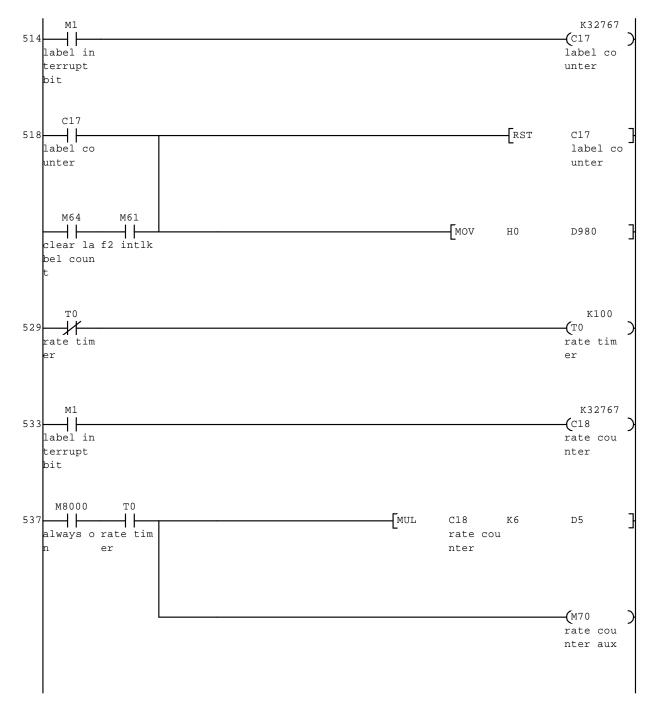
Labeling Head Program (LSI Serial Numbers 40-0334R & 40-0335L)

Both Labeling Heads run an Identical Program



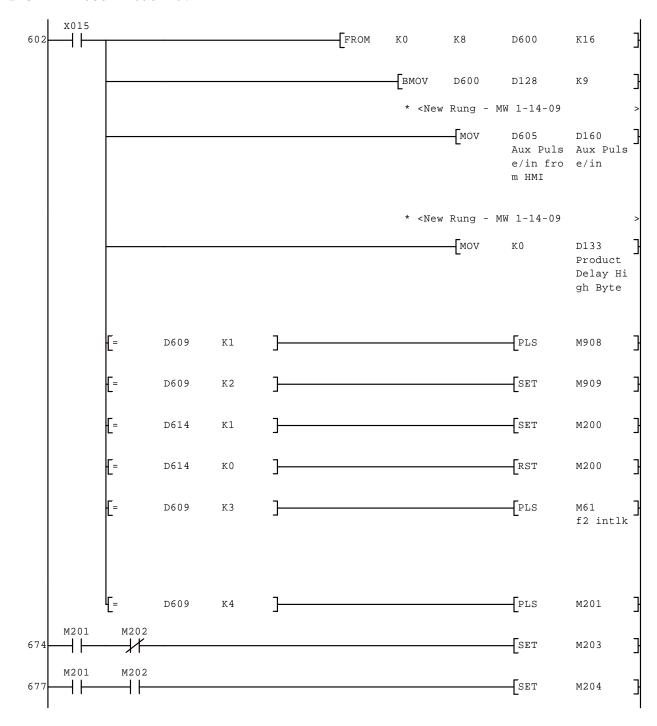
```
M10
                                                                 MOV
                                                                          ΚO
                                                                                     D2
pulse on
                                                                                     temp fre
                                                                                     q reg 1
  M15
                                                                                       D137
t246 con
                                                                                    (T246
                                                                                    1msec re
trol bit
                                                                                    tentive
                                                                                    timer
  T246
  \dashv \vdash
                                                        CMP
                                                                 D147
                                                                          D3
                                                                                     M20
1msec re
                                                                 geared temp fre subrouti
tentive
                                                                          q reg 2
                                                                                    ne compa
timer
                                                                                     re
            M20
                                                                          CALL
                                                                                     ΡO
          subrouti
                                                                                     call acc
         ne compa
                                                                                     el
         re
            M20
            #
                                                                          SET
                                                                                     M33
         subrouti
         ne compa
         re
                                                                          RST
                                                                                     T246
                                                                                     1msec re
                                                                                     tentive
                                                                                     timer
            M20
                                                                          RST
            +
                                                                                     M20
         subrouti
                                                                                     subrouti
         ne compa
                                                                                     ne compa
         re
                                                                                     re
 M8000
                                                        CMP
                                                                 D130
                                                                          ΚO
                                                                                     M52
always o
                                                                 printer
                                                                                     printer
                                                                 time
                                                                                     timer en
                                                                                     abled
```

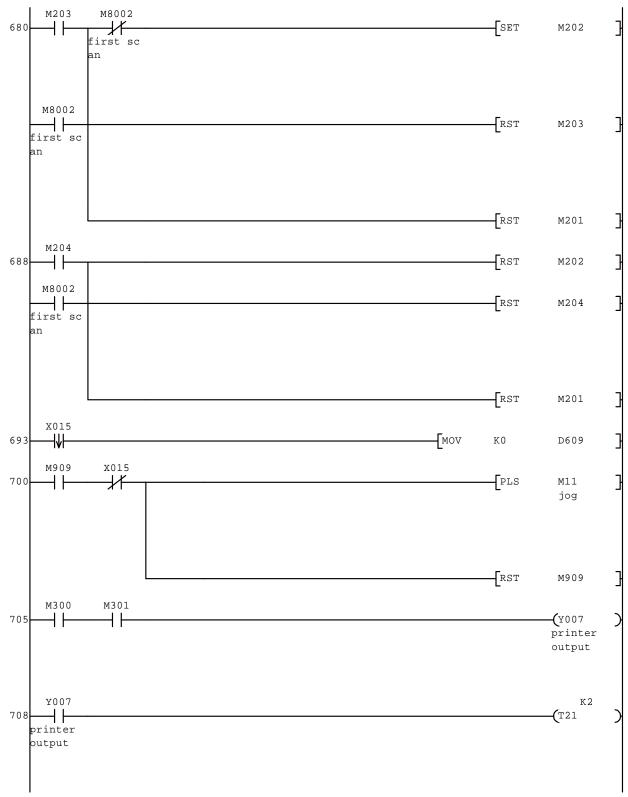
```
M52
                M10
                                                                                  PLS
                                                                                             M56
                                                                                             printer
   printer pulse on
   timer en
                                                                                             aux
   abled
      M56
   printer
                                                                                  SET
489
                                                                                             Y004
                                                                                             printer
   aux
     Y004
                                                                                                D130
     \dashv \vdash
                                                                                            (T249
   printer
                                                                                            print ti
                                                                                            me
      T249
                                                                                  RST
      \dashv \vdash
                                                                                             Y004
   print ti
                                                                                             printer
   me
                                                                                  RST
                                                                                             T249
                                                                                             print ti
                                                                                             me
       МО
                                                                                               K32767
                                                                                            (C16
                                                                                            product
   product
   interrup
                                                                                            counter
   t bit
     C16
                                                                                  RST
503
     \dashv \vdash
                                                                                             C16
   product
                                                                                             product
                                                                                             counter
   counter
      M63
                M61
                                                                        MOV
                                                                                             D980
                                                                                  Н0
   clear pr f2 intlk
   od count
```

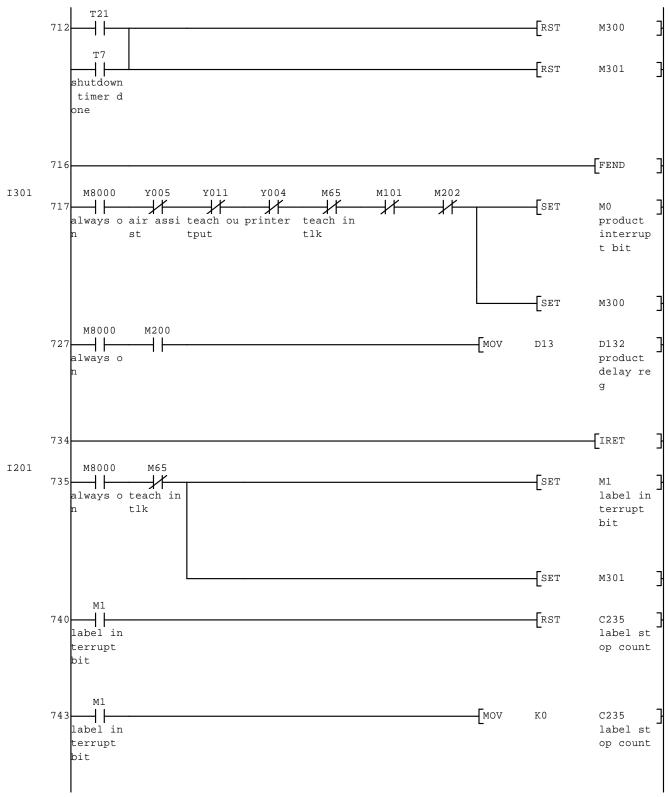


```
M70
                                                                                         RST
                                                                                                     C18
                                                                                                     rate cou
    rate cou
    nter aux
                                                                                                     nter
       C18
    rate cou
    nter
       M71
                                                                                         CALL
       \dashv \uparrow \vdash
                                                                                                     Ρ4
    save cal
                                                                                                     save cal
    l aux
       M80
    recall c
                                                                                         CALL
556
                                                                                                     Р5
                                                                                                     recall c
    all aux
                                                                                                     all
      X012
       \dashv \vdash
                                                                                                    (M75
561
    low labe
```

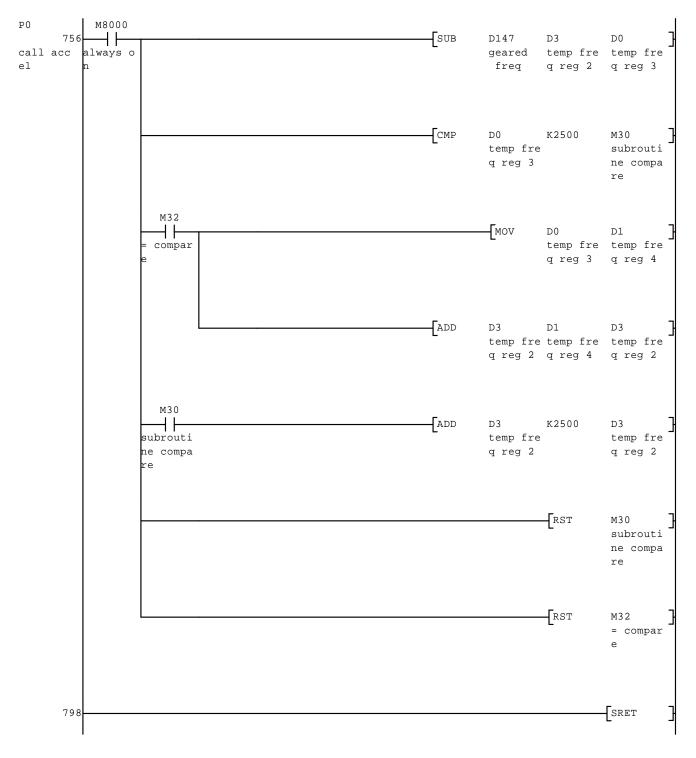
```
X013
                                                                                                -(M76
566
    web brea
      M105
       M76
                 M61
              f2 intlk
      Y020
                 M76
572
      \dashv \vdash
                                                                                                (M112
    alarm li
   ght
      M112
                                                                                                (M111
                 M76
577
                 #
                                                                                                (Y020
                                                                                                alarm li
                                                                                                ght
       T10
       M76
                 T11
                                                                                                    K10
                 #
                                                                                                (T10
       ┨┞
       T10
                                                                                                (T11
586
      X012
      \dashv \vdash
                                                                                                -(Y024
   low labe
     X013
592 web brea
                                                                                                -(Y025
```

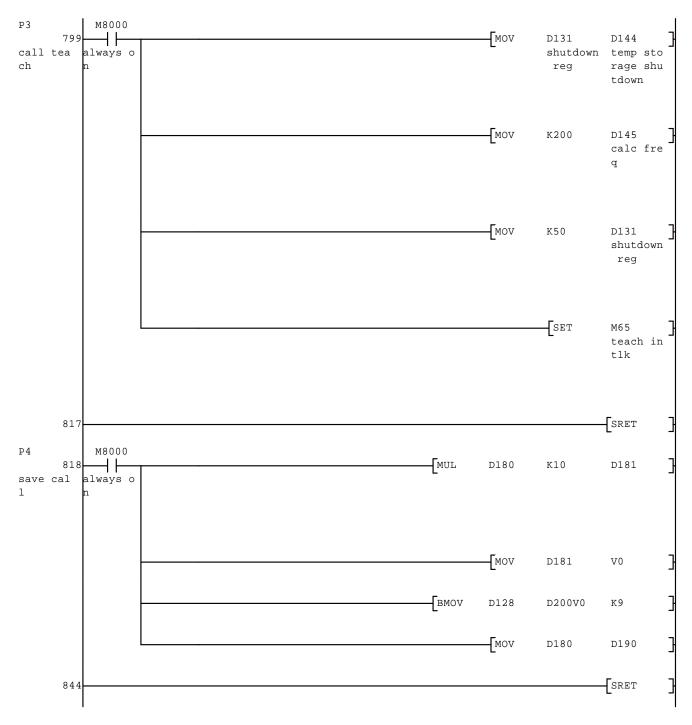




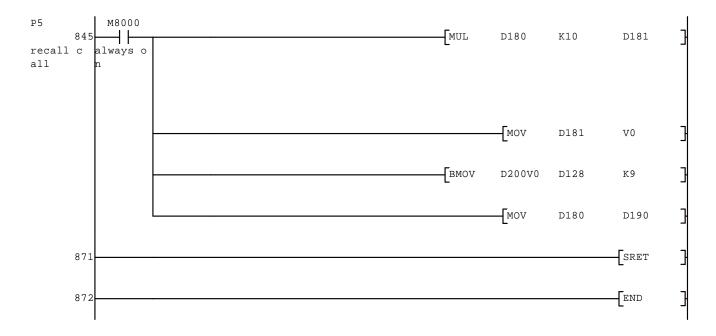


Labeling Head Program (LSI Serial Numbers 40-0334R & 40-0335L) Both Labeling Heads run an Identical Program Version: 14-0554 Head Rev D





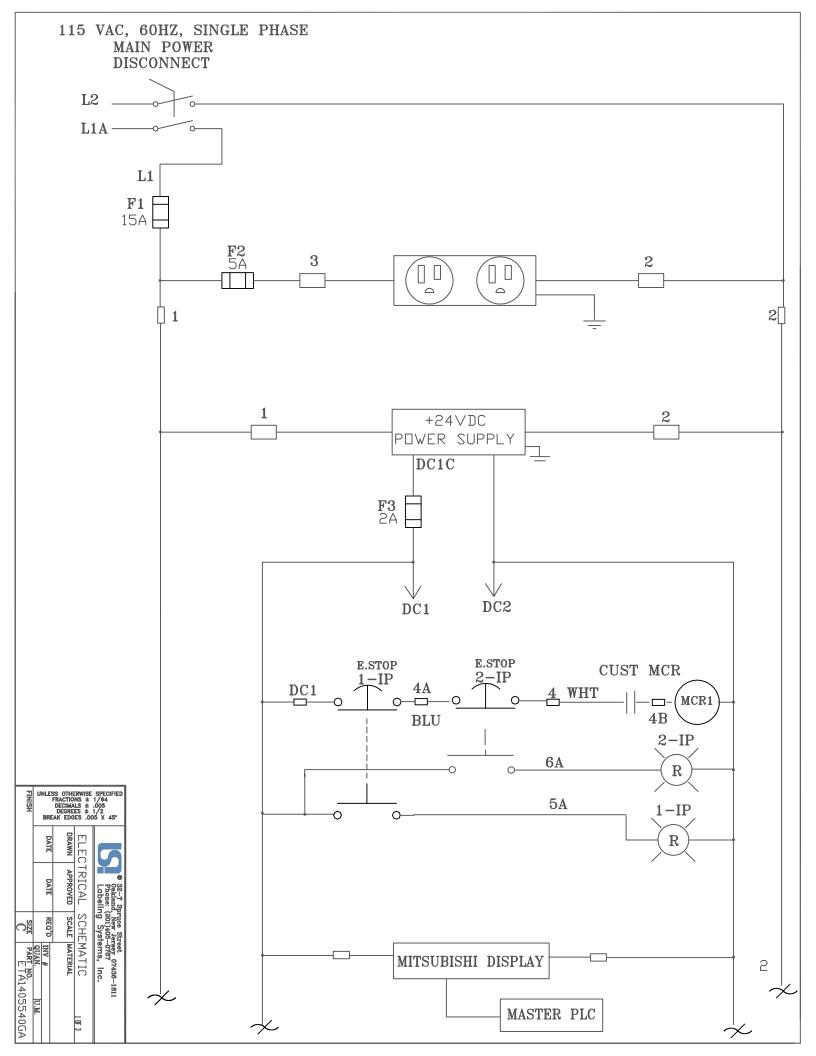
Labeling Head Program (LSI Serial Numbers 40-0334R & 40-0335L) Both Labeling Heads run an Identical Program Version: 14-0554 Head Rev D

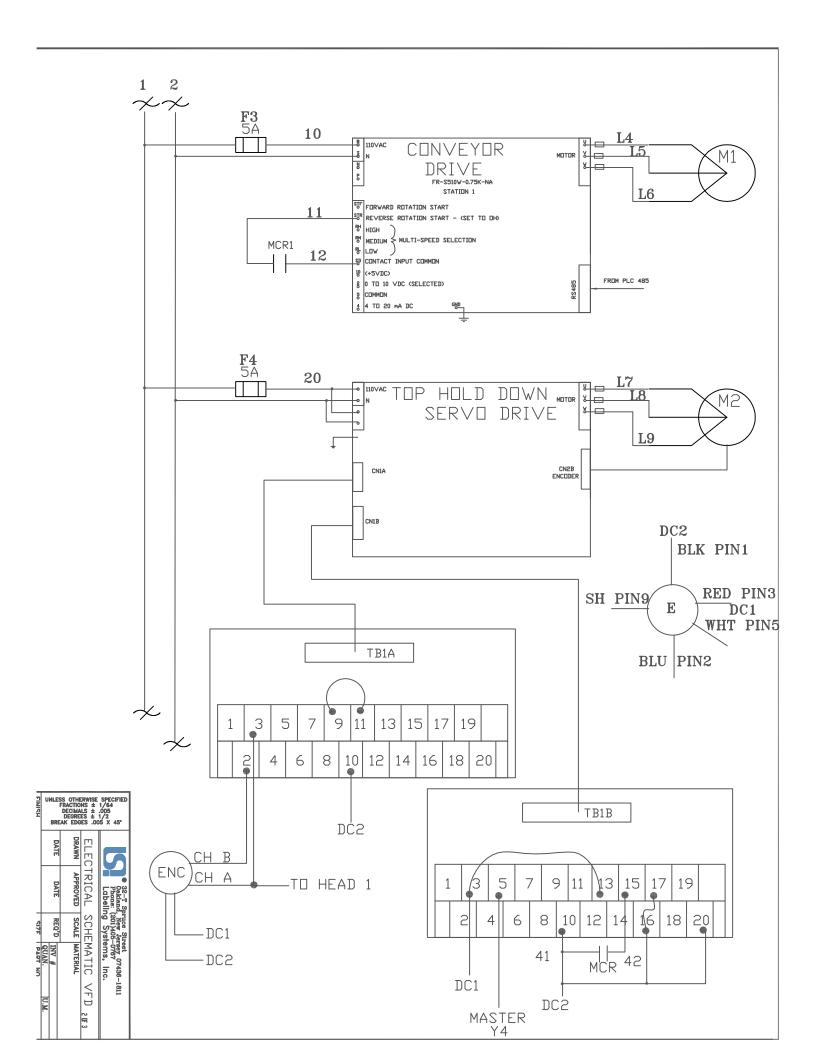


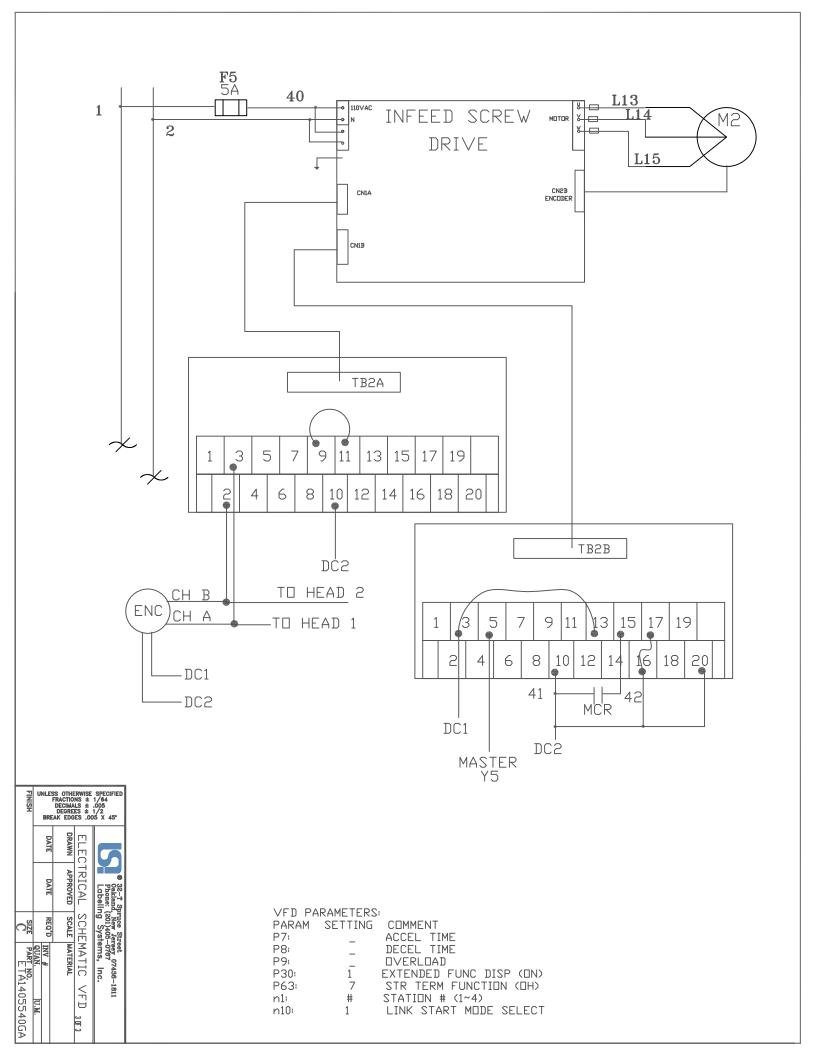


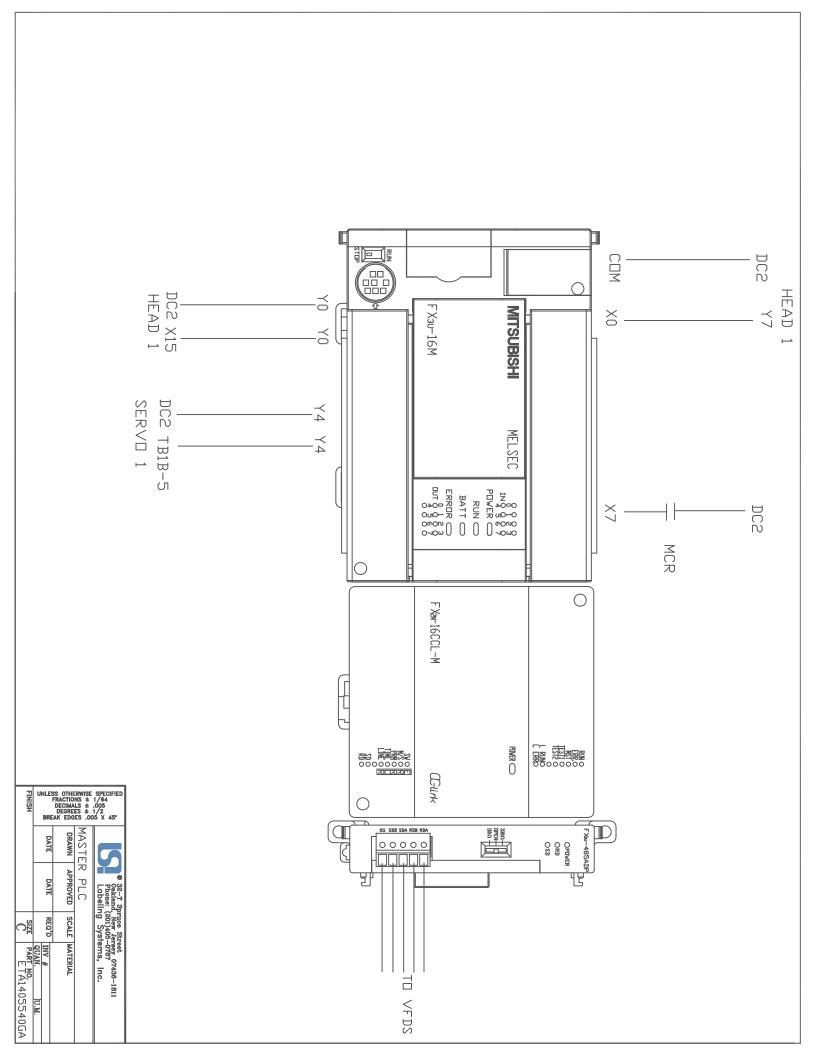
Appendix B Schematics

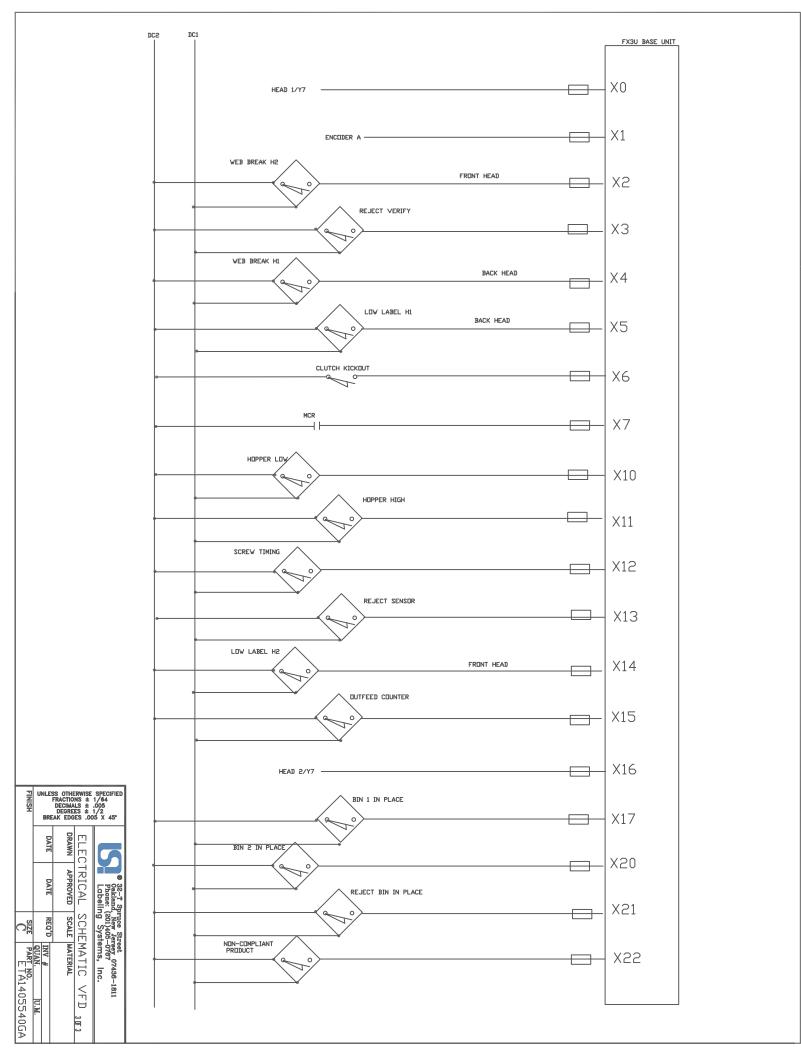
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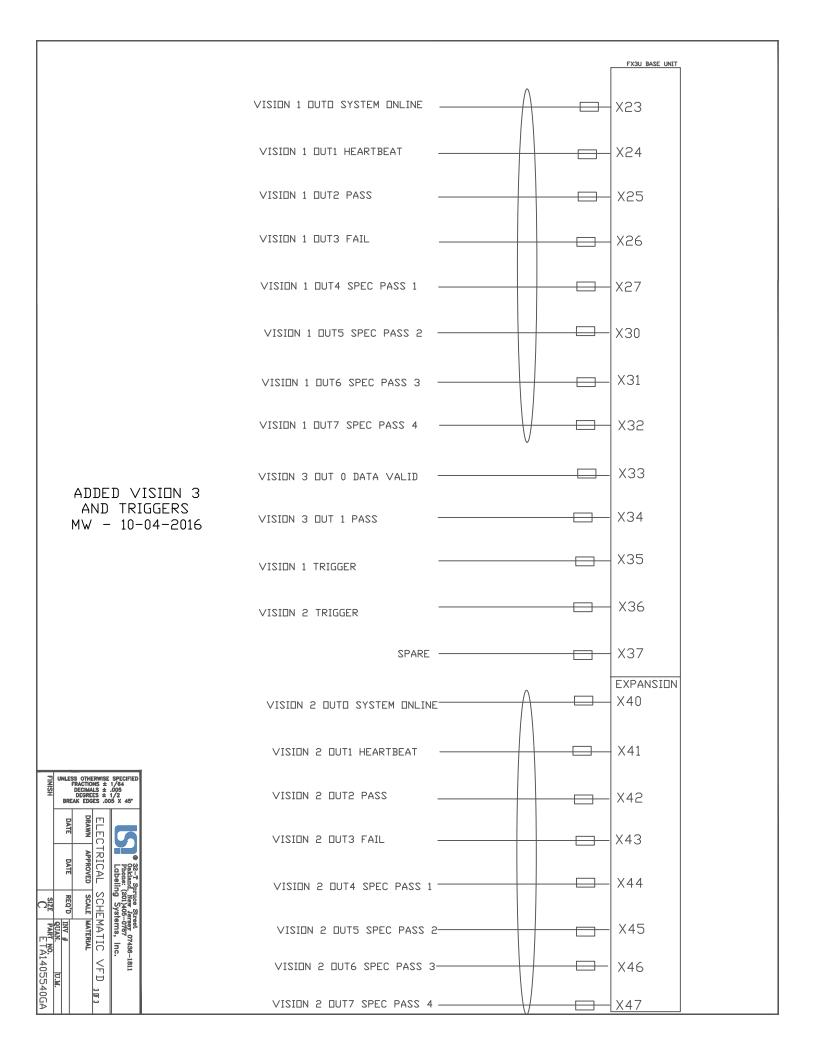


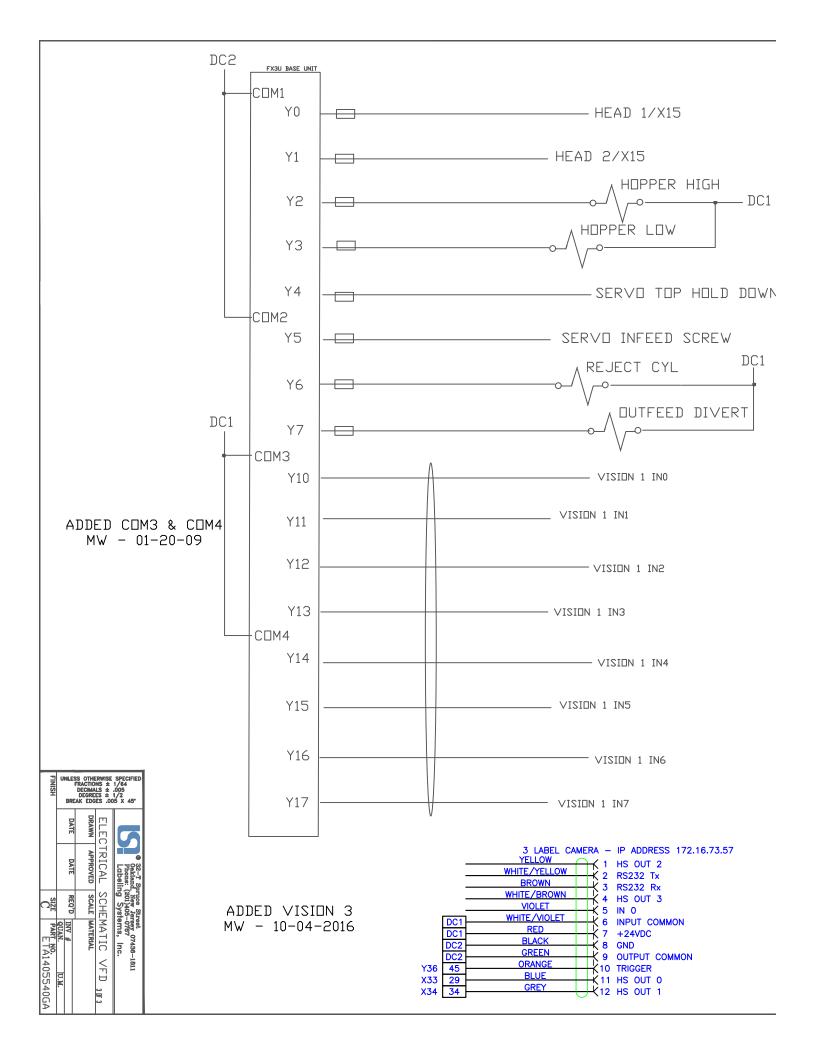


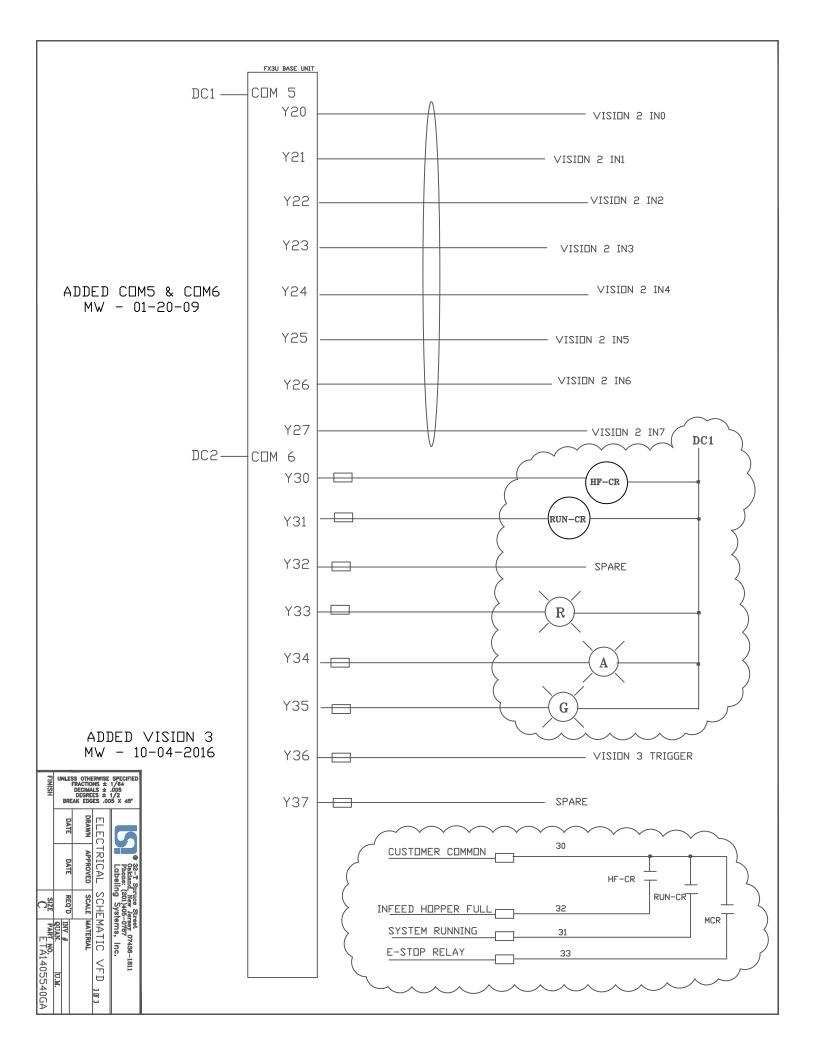


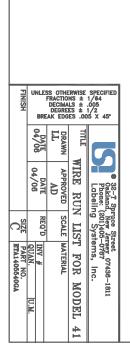


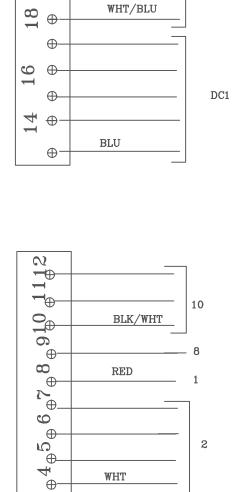












GRN

SP

DC2

GND

24 ⊕

 $^{\circ}_{\mathcal{O}}$ $^{\circ}_{\mathcal{O}}$

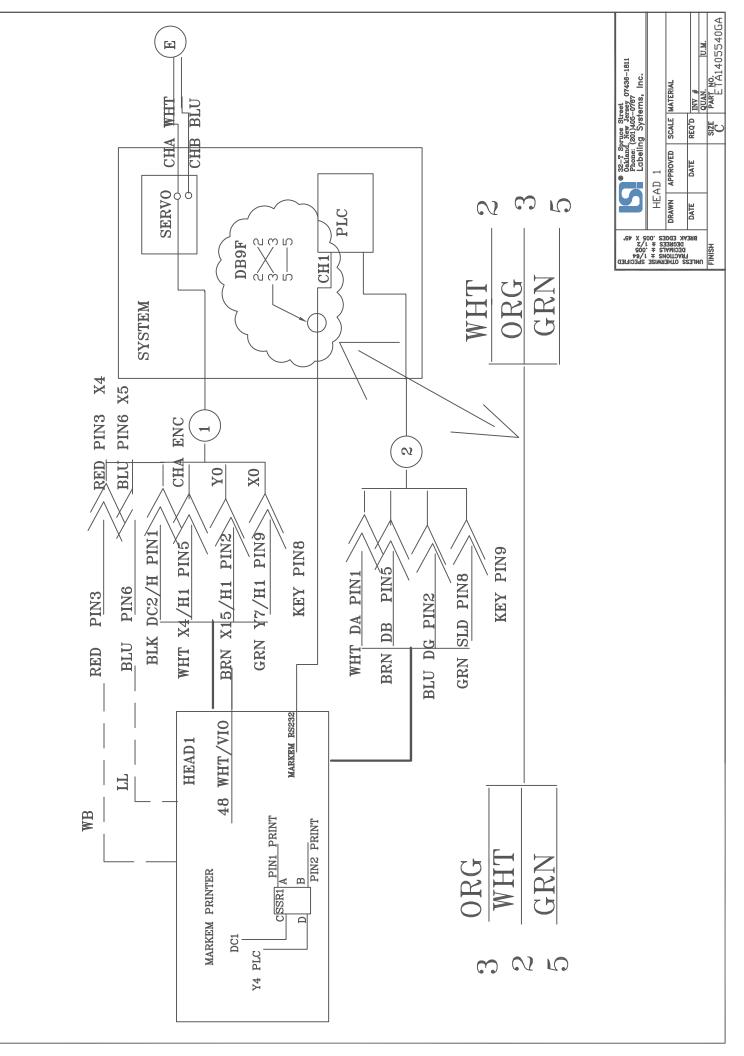
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 \oplus %

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48	WE	3
_	LL	
46 —		
⊕—		
44 ⊕—	YO/EXF	MOD BRN/WHT
⊕ —	Y11	ORG/WHT
27 ⊕—	Y7	GRY/WHT
⊕—	Y5	ORG
40	Y4	YEL/WHT
 	Y3	BRN
38	Y1	RED/WHT
က	Y0	YEL
Ψ_		

		_		
••	Φ-	X0	WHT/ORG	
536	⊕— 3⊕—		SP	
34,	Ψ ς ——		SP	
•••	Э_		SP	
323	-⊕ 9		SP	
		X6	WHT/GRY	
2627282930	—	X5	WHT/YEL	
	5	X4	WHT/GRN	
	Д Ф	хз	WHT/RED	
		X2	WHT/BLK	
	⊕	X1	WHT/BRN	
• •	⊋⊕—		SP	



		+	I		
BOTT		TOP	BOTT		TOP
1	1	SP	X33	29	X22
1	2	3	X41	30	X24
1	3	4	X43	31	X26
2	4	4A	X45	32	X30
2	5	SP	X47	33	X32
2	6	12	SP	34	X34
SP	7	DC1	Y1	35	X40
L13	8	DC1	Y3	36	X42
L14	9	DC1	Y5	37	X44
L15	10	DC1	Y7	38	X46
DA	11	SP	SP	39	SP
DB	12	DC2	SP	40	Y0
DG	13	DC2	Y32	41	Y2
SLD	14	DC2	Y33	42	Y4
SP	15	DC2	Y34	43	Y6
X1	16	СНА	Y35	44	SP
Х3	17	DIODE	Y36	45	DC1
X5	18	СНВ	Y37	46	DC1
SP	19	X0	SP	47	DC1
X11	20	X2	L4	48	DC2
X13	21	X4	L5	49	DC2
X15	22	X6	L6	50	DC2
X17	23	SP	L7	51	Y30
X21	24	X10	L8	52	Y31
X23	25	X12	L9	53	30
X25	26	X14		54	31
X27	27	X16		55	32
X31	28	X20		56	33



