

MITSUBISHI

General-Purpose AC Servo

MELSERVO-J2 Series

General-Purpose Interface

MR-J2-□A

Specifications and Installation Guide

CONTENTS

CHAPTER 1 INTRODUCTION	1-1~1-17
1-1 Inspection at delivery	1-2
1-1-1 Packing list	1-2
1-1-2 Model definition	1-2
1-1-3 Combination with servo motor	1-7
1-2 Parts identification and applications	1-8
1-2-1 Servo amplifier	1-8
1-2-2 Servo motor	1-13
1-3 Function list	1-14
1-4 Basic configuration	1-15
1-4-1 MR-J2-100A or less	1-15
1-4-2 MR-J2-200A or more	1-17
CHAPTER 2 OPERATION	2-1~2-54
2-1 Standard connection examples	2-2
2-1-1 Position control mode	2-2
2-1-2 Speed control mode	2-6
2-1-3 Torque control mode	2-8
2-2 Operation	2-10
2-2-1 Pre-operation checks	2-10
2-2-2 Start-up	2-11
2-3 Display and operation	2-18
2-3-1 Display flowchart	2-18
2-3-2 Status display	2-19
2-3-3 Diagnostic mode	2-20
2-3-4 Alarm mode	2-27
2-3-5 Parameter mode	2-28
2-4 Adjustments	2-50
2-4-1 Auto tuning	2-50
2-4-2 Manual gain adjustment	2-50
2-4-3 Slight vibration suppression control	2-54
CHAPTER 3 WIRING	3-1~3-62
3-1 Servo amplifier	3-3
3-1-1 Terminal blocks	3-3
3-1-2 Signal connectors	3-6
3-1-3 Detailed information on I/O signals	3-18
3-1-4 Interfaces	3-32
3-2 Connection of servo amplifier and servo motor	3-36
3-2-1 Connection instructions	3-36
3-2-2 Connection diagram	3-37
3-2-3 I/O terminals	3-38
3-2-4 Connectors used for servo motor wiring	3-41
3-3 Common line	3-55
3-4 Grounding	3-56
3-5 Power supply circuit	3-57
3-6 Alarm occurrence timing chart	3-59
3-7 Servo motor with electromagnetic brake	3-60
CHAPTER 4 INSTALLATION	4-1~4-9
4-1 Servo amplifier	4-2
4-2 Servo motor	4-5

CHAPTER 5	ABSOLUTE POSITION DETECTION SYSTEM	5-1~5-6
CHAPTER 6	OPTIONS AND AUXILIARY EQUIPMENT	6-1~6-27
6-1	Dedicated options	6-2
6-1-1	Regenerative brake options	6-2
6-1-2	Cable connectors	6-7
6-1-3	Junction terminal block	6-14
6-1-4	Maintenance junction card	6-15
6-1-5	Set-up software (will be released soon)	6-16
6-2	Auxiliary equipment	6-17
6-2-1	Cables	6-17
6-2-2	No-fuse breakers, fuses, magnetic contactors	6-17
6-2-3	Power factor improving reactors	6-18
6-2-4	Relays	6-18
6-2-5	Surge absorbers	6-19
6-2-6	Noise reduction techniques	6-20
6-2-7	Leakage current breaker	6-25
6-2-8	Battery (MR-BAT, A6BAT)	6-26
6-2-9	Setting potentiometers for analog inputs	6-27
CHAPTER 7	INSPECTION	7-1~7-3
CHAPTER 8	TROUBLESHOOTING	8-1~8-13
8-1	Troubleshooting at start-up	8-2
8-1-1	Position control mode	8-2
8-1-2	Speed control mode	8-4
8-1-3	Torque control mode	8-5
8-2	Alarms and warnings	8-6
8-2-1	Alarm and warning list	8-6
8-2-2	Alarms	8-7
8-2-3	Warnings	8-13
CHAPTER 9	CHARACTERISTICS	9-1~9-12
9-1	Overload protection characteristics	9-2
9-2	Losses generated in the servo amplifier	9-4
9-3	Electromagnetic brake characteristics	9-6
9-4	Dynamic brake characteristics	9-10
9-5	Vibration rank	9-12
CHAPTER 10	SPECIFICATIONS	10-1~10-110
10-1	Standard specifications	10-2
10-2	Torque characteristics	10-6
10-3	Servo motors with reduction gears	10-10
10-4	Servo motors with special shafts	10-14
10-5	Outline dimension drawings	10-16
10-5-1	Servo amplifiers	10-16
10-5-2	Servo motors	10-19
10-5-3	Servo motors (in inches)	10-61
10-5-4	Cable side plugs	10-103

CHAPTER 11 SELECTION	11-1~11-13
11-1 Specification symbol list	11-2
11-2 Position resolution and electronic gear setting	11-3
11-3 Speed and command pulse frequency	11-4
11-4 Stopping characteristics	11-5
11-5 Capacity selection.....	11-6
11-6 Load torque equations	11-8
11-7 Load inertia moment equations	11-9
11-8 Precautions for zeroing.....	11-10
11-9 Selection example.....	11-11