

**STAR
SWING-TYPE
REMOVERS
RT-500 RT-600
USER'S MANUAL**



Pioneer of Automation Systems
STAROBO ROBOT CO., LTD.

CONTENTS

1. MECHANICAL SPECIFICATION
2. ACTION GRAPHIC
3. NAMES OF THE PARTS
 - 1). Vertical Unit
 - 2). Crosswise Unit
 - 3). Swing Unit
 - 4). Main Unit
 - 5). Solenoid Valve layout
 - 6). Controller Box
 - 7). Operating Panel
4. POWER ON
5. INPUT/OUTPUT DISPLAY SCREEN
6. INPUT/OUTPUT DISPLAY LIST
7. MODE SETTINGS
8. MODES
9. TIMER SETTINGS
10. ALARM TIMER
11. LIST OF TIMER OPERATIONS
12. OPERATIONS
 - 1). Manual Operations
 - 2). Origin Return (Home Position)
 - 3). Counter Reset Method
 - 4). Automatic Operations
 - 5). How to Clear the Message Screen
13. CAUSES AND SOLUTIONS FOR ALARM MESSAGES
14. CAUSES OF AND SOLUTIONS TO ERROR MESSAGES
15. STEC-001 CONNECTION DIAGRAM
16. MECHANICAL INSPECTION
17. RT OVERALL DIAGRAM
18. RT LIMIT SWITCH LAYOUT
19. STEC-RT INTERLOCK DIAGRAM
20. AIR CIRCUITS

