

Σ -II Series SGDH
DeviceNet INTERFACE MODULE
USER'S MANUAL

MODEL: JUSP-NS300



YASKAWA

MANUAL NO. SIE-C718-6B

TABLE OF CONTENTS

Safety Information	iii
Visual Aids	iv
Overview	xii
Using This Manual	xiii
Registered Trademark	xiii
Safety Precautions	xiv
1 Checking Products and Part Names	
1.1 Checking Products on Delivery	1 -2
1.2 Product Part Names	1 -3
1.3 Mounting the NS300 Module	1 -4
2 Installation	
2.1 Storage Conditions	2 -2
2.2 Installation Site	2 -2
2.3 Orientation	2 -3
2.4 Installation	2 -4
3 Connectors	
3.1 Connecting to Peripheral Devices	3 -2
3.1.1 Single-phase (100 V or 200 V) Main Circuit Specifications	3 -3
3.1.2 Three-phase, 200-V Main Circuit Specifications	3 -4
3.1.3 Three-phase, 400-V Main Circuit Specifications	3 -5
3.2 SERVOPACK Internal Block Diagrams	3 -6
3.3 I/O Signals	3 -7
3.3.1 Connection Example of I/O Signal Connector (CN1)	3 -7
3.3.2 I/O Signals Connector (CN1)	3 -8
3.3.3 I/O Signal Names and Functions	3 -9
3.3.4 Interface Circuits	3 -10
3.4 I/O Signal Connections for NS300 Modules (CN4)	3 -12
3.4.1 Connection Terminal Layout	3 -12
3.4.2 I/O Signal Interface Circuits	3 -13
3.4.3 Fully-closed Encoder Connection Example	3 -14
3.5 Connections for DeviceNet Communications	3 -15
3.5.1 DeviceNet Communications Connection Example	3 -15
3.5.2 DeviceNet Communications Connectors (CN6)	3 -17

3.5.3 Precautions for Wiring DeviceNet Cables	3 -18
3.5.4 Grounding	3 -21
4 Parameter Settings	
4.1 Parameters	4 -2
4.1.1 Outline of Parameters	4 -2
4.1.2 Parameter Types	4 -2
4.1.3 Editing Parameters	4 -3
4.1.4 Effective Timing	4 -3
4.2 Parameter Tables	4 -4
4.2.1 Unit Parameters	4 -4
4.2.2 Zero Point Return Parameters	4 -4
4.2.3 Machine System and Peripheral Device Parameters	4 -5
4.2.4 Speed, Acceleration, and Deceleration Parameters	4 -6
4.2.5 Positioning Parameters	4 -8
4.2.6 Multi-speed Positioning Parameters	4 -8
4.2.7 Notch Output Parameters	4 -11
4.3 Parameter Details	4 -12
4.3.1 Unit Parameters	4 -12
4.3.2 Zero Point Return Parameters	4 -15
4.3.3 Machine System and Peripheral Devices	4 -21
4.3.4 Speed, Acceleration, and Deceleration	4 -24
4.3.5 Positioning	4 -37
4.3.6 Multi-speed Positioning	4 -39
4.3.7 Notch Signal Output Positioning	4 -40
5 DeviceNet Communications	
5.1 Specifications and Configuration	5 -3
5.1.1 Specifications	5 -3
5.1.2 Control Configuration	5-33
5.2 DeviceNet Communications Setting Switches	5 -4
5.2.1 Rotary Switch Settings for Setting Node Address	5 -4
5.2.2 Rotary Switch Settings for Setting Baud Rate	5 -5
5.2.3 LED Indicators	5 -5
5.3 Command/Response Format	5 -7
5.3.1 Command Format	5 -7
5.3.2 General Command Bits and Status	5 -8
5.3.3 Move Command Messages	5 -11
5.3.4 Set/Read Command Messages	5 -18
5.4 Motion Command Methods	5 -26
5.4.1 Constant Feed Command	5 -26
5.4.2 Step Command	5 -28
5.4.3 Station Command	5 -30
5.4.4 Point Table Command	5 -32
5.4.5 Zero Point Return Command	5 -34

5.4.6 Positioning Command	5 -36
5.4.7 External Positioning	5 -38
5.4.8 Notch Output Positioning Command	5 -40
5.4.9 Multi-speed Positioning Command	5 -41
5.5 Commands from the Host Controller	5 -45
5.5.1 Basic Operation	5 -45
5.5.2 Command Method	5 -45
5.6 Changing Parameters	5 -50
5.6.1 Managing DeviceNet Data	5 -50
5.6.2 Editing Parameters	5 -51
5.7 Data Trace Function	5 -53
5.7.1 Trace Parameters	5 -54
5.7.2 Reading Trace Data	5 -57
5.7.3 Executing Data Traces	5 -61
6 Parameter Settings	
6.1 Parameters and Standard Settings for NS300 Modules	6 -3
6.1.1 Automatically Set Parameters	6 -3
6.1.2 Standard Settings for CN1 I/O Signals	6 -4
6.2 Settings According to Equipment Characteristics	6 -5
6.2.1 Switching Servomotor Rotation Direction	6 -5
6.2.2 Stop Mode Selection at Servo OFF	6 -5
6.2.3 Fully-closed Control	6 -7
6.2.4 Fully-closed System Specifications	6 -7
6.2.5 Parameter Settings for the Fully-closed System	6 -8
6.3 Settings According to Host Controller	6 -9
6.3.1 Sequence I/O Signals	6 -9
6.4 Setting Up the SERVOPACK	6 -11
6.4.1 Parameters	6 -11
6.4.2 Input Circuit Signal Allocation	6 -11
6.4.3 Output Circuit Signal Allocations	6 -12
6.4.4 Analog Monitors	6 -14
6.5 Setting Stop Functions	6 -15
6.5.1 Using the Dynamic Brake	6 -15
6.5.2 Using the Holding Brake	6 -16
6.6 Absolute Encoders	6 -20
6.6.1 Selecting an Absolute Encoder	6 -20
6.6.2 Absolute Encoder Setup	6 -21
6.6.3 Multiturn Limit Setting	6 -21
6.7 Digital Operator	6 -23
6.7.1 Connecting the Digital Operator	6 -23
6.7.2 Limitations in Using a Hand-held Digital Operator	6 -23
6.7.3 Panel Operator Indicators	6 -24

7	Using the NSxxx Setup Tool	
7.1	Connection and Installation	7 -2
7.1.1	Connecting the NS300 Module	7 -2
7.1.2	Installing the Software	7 -2
7.2	How to Use	7 -3
7.2.1	Screen Configuration at Startup	7 -3
7.2.2	Functions Configuration	7 -6
8	Ratings, Specifications, and Dimensions	
8.1	Ratings and Specifications	8 -2
8.2	Dimensional Drawings	8 -3
8.2.1	NS300 Module	8 -3
9	Error Diagnosis and Troubleshooting	
9.1	Troubleshooting with Alarm Displays	9 -2
9.2	Troubleshooting Problems with No Alarm Display	9 -36
9.3	Alarm Display Table	9 -38
9.4	Warning Codes	9 -41
A	DeviceNet Object Model	
A.1	DeviceNet Object Model	A -2
B	DeviceNet Attributes	
B.1	Identity Object (0x01)	B -2
B.2	Message Router Object (0x02)	B -3
B.3	DeviceNet Object (0x03)	B -4
B.4	Assembly Object (0x04)	B -5
B.5	Connection Object (0x05)	B -6
B.6	Control Parameter Object (0x64)	B -9
B.7	Point Table Object (0x65)	B -17
B.8	SERVOPACK Parameter Object (0x66)	B -22

C Alarm and Warning Codes**C.1 Alarm Codes C -2****C.2 Warning Codes C -5**